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# The evolution of harmonic maps 

by

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The evolution of harmonic maps

# A thesis presented <br> by 

Kazuhiro Horihata
to
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Tohoku University
Sendai, Japan

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## Prefaces

The purpose of this thesis is to study partial regularity of the weakly evolutional harmonic maps whose target manifolds are spheres.

Harmonic maps are considered a generalization of the closed geodesics in differential geometry and have been studied by Almgren, Brezis, Eells, Giaquinta, Hardt, Hildebrandt, Lin, Lieb, Nishikawa, Schoen, Struwe and Uhlenbeck, etc. We recall several important results on harmonic maps.

Let $B^{d}$ and $S^{D-1}$ be the $d$-dimensional unit ball and the $D-1$-dimensional unit sphere respectively with positive integers $d$ and $D$ more than or equal to 2 . $H^{1,2}\left(B^{d} ; \mathbb{R}^{D}\right)$ denotes

$$
\begin{aligned}
& H^{1,2}\left(B^{d} ; \mathbb{R}^{D}\right)=\left\{u=\left(u^{i}\right)(i=1, \ldots, D) ; u^{i} \in L^{2}\left(B^{d}\right), \partial u^{i} / \partial x_{\alpha}\right. \\
& \left.\quad \in L^{2}\left(B^{d}\right)(\alpha=1, \ldots, d)\right\}, \quad\left(\partial u^{i} / \partial x_{\alpha} ; \text { weak derivative of } u^{i}\right), \\
& \text { the norm }\|u\|_{H^{1,2}} \text { of } H^{1,2}\left(B^{d} ; \mathbb{R}^{D}\right) \text { is given by } \\
& \|u\|_{H^{1,2}}=\left\{\sum_{i=1}^{D} \int_{B^{d}}\left|u^{i}\right|^{2} d x+\sum_{\alpha=1}^{d} \sum_{i=1}^{D} \int_{B^{d}}\left|\frac{\partial u^{i}}{\partial x_{\alpha}}\right|^{2} d x\right\}^{1 / 2} .
\end{aligned}
$$

Also

$$
\begin{aligned}
& H^{1,2}\left(B^{d} ; S^{D-1}\right)=\left\{u \in H^{1,2}\left(B^{d} ; \mathbb{R}^{D}\right) ;|u|=1, \text { a.e. } x \in B^{d}\right\}, \\
& \stackrel{\circ}{1,2}^{1,2}\left(B^{d} ; \mathbb{R}^{D}\right)=\overline{C_{0}^{\infty}\left(B^{d} ; \mathbb{R}^{D}\right)}{ }^{H^{1,2}\left(B^{d} ; \mathbb{R}^{D}\right)} .
\end{aligned}
$$

Give $u_{0} \in H^{1,2}\left(B^{d} ; S^{D-1}\right)$. We consider the boundary value problem to the following system:

$$
\begin{aligned}
& \triangle u+|\nabla u|^{2} u=0, \quad \text { in } \quad B^{d}, \\
& u=u_{0} \quad \text { on } \quad \partial B^{d} .
\end{aligned}
$$

A solution of the boundary value problem above is called a (Dirichlet) harmonic map.

Since harmonic maps are the Euler-Lagrange equations of the Dirichlet energy

$$
E[u]=\frac{1}{2} \int_{B^{d}}|\nabla u|^{2} d x, \quad \text { with restriction }|u|=1,
$$

the existence of a harmonic map follows from the variational problem:
Problem 1. Find a map $u_{\text {min }}$ in $H^{1,2}\left(B^{d} ; S^{D-1}\right)$ with

$$
E\left[u_{\text {min }}\right]=\inf _{u \in H_{u_{0}}^{1,2}\left(B^{d} ; S^{D-1}\right)} E[u],
$$

where $H_{u_{0}}^{1,2}\left(B^{d} ; S^{D-1}\right)=\left\{u \in H^{1,2}\left(B^{d} ; S^{D-1}\right) ; u-u_{0} \in \stackrel{H}{H}^{1,2}\left(B^{d} ; \mathbb{R}^{D}\right)\right\}$.
The map $u_{\text {min }}$ is often called "minimizer." Related to the problem above, the following two results on minimizer are fundamental:
(I) $u_{\text {min }}$ exists in all $d, D$ if $H_{u_{0}}^{1,2}\left(B^{d} ; S^{D-1}\right)$ is not empty and it is smooth in $d=2$. (Special case of the results by Morrey, C. B. Jr; see "Multiple integrals in the calculus of variations")
(II) $u_{\text {min }}$ is smooth on an open set whose compliment is a set of at most finite (d-3)-Hausdorff measure. (This result is due to Schoen, R and Uhlenbeck, K).
As is well-known, $H_{u_{0}}^{1,2}\left(B^{d} ; S^{d-1}\right)$ is not empty and any map $u: B^{d} \rightarrow S^{d-1}$ with $\operatorname{deg}\left(\left.u\right|_{\partial B^{d}}\right) \neq 0$ has at least one singular point (non-continuous point) if $d \geq 3$. Thus the result by Schoen, R and Uhlenbeck, K is sharp.
$u_{\min }$ is the critical point of the Dirichlet energy $E$ and hence is a harmonic map. The result above shows the existence of a harmonic map for a given boundary value $u_{0}$. However, in general harmonic maps are not unique. Then the following problem naturally arises:

Problem 2. For a given map $u_{0} \in H_{u_{0}}^{1,2}\left(B^{d} ; S^{D-1}\right)$, find all harmonic map with a boundary value $u_{0}$.

To solve the problem 2, Eells-Sampson proposed the strategy that considers the following parabolic system:

$$
\begin{array}{rlr}
\frac{\partial u}{\partial t} & =\triangle u+|\nabla u|^{2} u & \text { in } Q_{\infty}, \\
u(0, x) & =u_{0}(x) & \text { in }\{0\} \times B^{d}, \\
u(t, x) & =u_{0}(x) & \text { in }[0, \infty) \times \partial B^{d}, \\
& \left(Q_{\infty}=(0, \infty) \times B^{d}\right)
\end{array}
$$

shows that a solution $u(t, x)$ of the system above, converges to a harmonic map as $t \rightarrow+\infty$. A solution $u(t, x)$ of the system above is called "evolutional harmonic map". By using a certain penalty method, Chen, Y and Struwe, M have constructed a weakly evolutional harmonic map $u(t, x)$, that is, a map satisfying

$$
\begin{equation*}
u \in L^{\infty}\left(0, T ; H^{1,2}\left(B^{d} ; S^{D-1}\right)\right) \cap H^{1,2}\left(0, T ; L^{2}\left(B^{d} ; S^{D-1}\right)\right) \tag{A-1}
\end{equation*}
$$

for any positive number $T$,
[A-2] $u(t, x)$ satisfies the system above in the distribution sense,

$$
\begin{equation*}
u(t, x)-u_{0}(x) \in \stackrel{\circ}{H}^{1,2}\left(B^{d} ; \mathbb{R}^{D}\right) \quad \text { for almost every } \quad t \in(0, T), \tag{A-3}
\end{equation*}
$$

$$
\begin{equation*}
\lim _{t \rightarrow+0} u(t, \cdot)=u_{0}(\cdot) \quad \text { in } \quad L^{2}\left(B^{d} ; \mathbb{R}^{D}\right) ; \tag{A-4}
\end{equation*}
$$

a penalty method is to examine the following approximate systems:

$$
\begin{array}{lr}
\frac{\partial u_{\lambda}}{\partial t}=\triangle u_{\lambda}-\lambda\left(\left|u_{\lambda}\right|^{2}-1\right) u_{\lambda} & \text { for } \quad Q_{\infty} \\
u_{\lambda}(0, x)=u_{0}(x) & \text { in }\{0\} \times B^{d} \\
u_{\lambda}(t, x)=u_{0}(x) & \text { in }[0, \infty) \times \partial B^{d}
\end{array}
$$

where $\lambda$ is any positive number, $u_{\lambda}$ is a map from $Q_{\infty}$ to $\mathbb{R}^{D}$ and $u_{0}$ is a map from $B^{d}$ to $\mathbb{R}^{D}$ with $\left|u_{0}\right|=1$. However, in general, the weakly evolutional harmonic maps are neither unique nor smooth on the whole domain by the topological obstruction. To ensure the uniqueness, a class of solutions proposed by Chen, Y and Struwe, M seems too broad. The main purpose of the thesis is to find a class of solutions with the following two requirements:
(I) There exists a unique weakly evolutional harmonic map in a class of solutions.
(II) The singular set of weakly evolutional harmonic map in this class is smaller than that of the weakly evolutional harmonic maps constructed by Chen, Y and Struwe, M.
To the requirements of (I) and (II), we show the class of solutions $u(t, x)$ that implies the following properties:

$$
\begin{equation*}
u(t, x) \text { satisfies }[\mathrm{A}-1]-[\mathrm{A}-4], \tag{H-1}
\end{equation*}
$$

$$
\begin{equation*}
\lim _{h \backslash 0} \frac{1}{h} \int_{Q}|\langle x+h \mathbf{e}, \nabla\rangle u(t, x+h \mathbf{e})-\langle x, \nabla\rangle u(z)|^{2} d z=0 \tag{H-2}
\end{equation*}
$$

$$
\begin{equation*}
\lim _{h 〕 0} \frac{1}{h} \int_{Q}|\nabla u(t+h, x)-\nabla u(z)|^{2} d z=0 \tag{H-3}
\end{equation*}
$$

where $z=(t, x), d z=d t d x$, e is a unit vector in $\mathbb{R}^{d}$ and any compact set $Q \subset \subset Q_{\infty}$. Then we state our first main theorem:

Theorem 1. Let d be 3. If a map $u: Q_{\infty} \rightarrow S^{D-1}$ satisfies the hypothesis [H-1] - [H-3], then the map $u$ is smooth except for a relative closed set in $Q_{\infty}$ having at most zero 3-dimensional Hausdorff measure with respect to the parabolic metric where the parabolic metric $d_{\mathrm{P}}$ means for any points $(t, x)$ and $(s, y) \in \mathbb{R}_{+} \times \mathbb{R}^{d}$,

$$
d_{\mathrm{P}}((t, x),(s, y))=|t-s|^{1 / 2}+|x-y| .
$$

The proof of this theorem is directly performed by the combining the following two theorems:

Theorem 2. Let u be a map satisfying [H-1] - [H-3]; when we set

$$
\Sigma_{u}=\left\{z_{0}=\left(t_{0}, x_{0}\right) \in Q_{\infty} ; \liminf _{r \backslash 0} r^{-3} \int_{Q_{r}\left(z_{0}\right)}|\nabla u|^{2} d z>0\right\},
$$

then $\Sigma_{u}$ is a relative closed set in $Q_{\infty}$ satisfying $\mathcal{H}^{3}\left(\Sigma_{u}\right)=0$. Here the 3 -dimensional Hausdorff measure with respect to the parabolic metric $\mathcal{H}^{3}\left(\Sigma_{u}\right)$ is given by

$$
\mathcal{H}^{3}\left(\Sigma_{u}\right)=\sup _{R>0}\left\{\inf _{\text {covering }}\left\{\sum_{i} r_{i}^{3} ; \Sigma_{u} \subset \bigcup_{i} P_{r_{i}}\left(z_{i}\right), z_{i}=\left(t_{i}, x_{i}\right) \in \Sigma_{u}, r_{i}<R\right\}\right\},
$$

with $P_{R}\left(z_{0}\right)=\left(t_{0}-R^{2}, t_{0}+R^{2}\right) \times B_{R}\left(x_{0}\right)$.
Theorem 3. There exist constants $0<\epsilon_{0}, \tau_{0}<1$ such that for any map $u$ with [H-1] - [H-3] and any $Q_{r}\left(z_{0}\right) \subset \subset Q_{\infty}$,

$$
\begin{aligned}
& \frac{r^{-3}}{2} \int_{Q_{r}\left(z_{0}\right)}|\nabla u|^{2} d z<\epsilon_{0} \quad \text { implies } \\
& \frac{\left(\tau_{0} r\right)^{-3}}{2} \int_{Q_{T_{0} r}\left(z_{0}\right)}|\nabla u|^{2} d z \leq \frac{1}{2} \frac{r^{-3}}{2} \int_{Q_{r}\left(z_{0}\right)}|\nabla u|^{2} d z
\end{aligned}
$$

The following monotonicity lemma has played a crucial role in the proof of Theorem 3:

Lemma 1. For all map $u$ with $[\mathrm{H}-1]-[\mathrm{H}-3]$, the inequality holds

$$
\frac{1}{r_{2}^{2}} \int_{t_{0}-r_{2}^{2}}^{t_{0}} \frac{d t}{r_{1}} \int_{B_{r_{1}\left(x_{0}\right)}}|\nabla u|^{2} d x \leq \frac{C_{M}}{\left(2 r_{2}\right)^{2}} \int_{t_{0}-\left(2 r_{2}\right)^{2}}^{t_{0}} \frac{d t}{2 r_{2}} \int_{B_{2 r_{2}\left(x_{0}\right)}}|\nabla u|^{2} d x
$$

where $\left(t_{0}-r_{2}^{2}, t_{0}\right) \times B_{r_{1}}\left(x_{0}\right) \subset Q_{r_{2}}\left(z_{0}\right) \subset Q_{2 r_{2}}\left(z_{0}\right) \subset \subset Q_{\infty}$ are any concentric cylinders with $z_{0}=\left(t_{0}, x_{0}\right)$ and $C_{M}$ is a positive constant independent of $r_{1}, r_{2}, z_{0}$,u.

To complete the proof of Theorem 1, we apply DeGiorgi-Nash-Moser's iteration technique to Theorem 3 and successively use the Schauder estimates for the parabolic equations and the boot strap argument; we can verify that $u$ with [H-1] - [H-3] belongs to $C^{\infty}\left(Q_{\infty} \backslash \Sigma_{u}\right)$. Struwe, M suggests that the class of solutions satisfying $[\mathrm{A}-1]-[\mathrm{A}-4]$ and the monotonicity formula may permit us to possess the unique solution $u$ to the prescribed initial-boundary condition. The existence of a map with $[\mathrm{H}-1]-[\mathrm{H}-3]$ will be discussed in the forthcoming paper. This will be stated in Chapter 2.

Chapter 3 demonstrates a new proof of a partial regularity of the weakly evolutional harmonic maps constructed by Chen, Y and Struwe, M. This new method enables us explicitly to estimate various constants appeared in the proof. We show it by combining Giaquinta's and Ladyžhenskaya-Ural'ceva's iteration techniques with the nonlinear Fefferman-Phong inequality which is instructive in itself. Here the nonlinear Fefferman-Phong inequality is

Lemma 2. Let $u_{\lambda}$ be the smooth solution of the penalty system and $\eta$ a nonnegative smooth function with a compact support on a parabolic cube $D_{R}\left(z_{0}\right)$ and $\sup _{D_{R}\left(z_{0}\right)} \eta(z) \leq 1 ;$ Then, for the Ginzburg-Landau energy density $e_{\lambda}\left(u_{\lambda}\right)=$
$1 / 2\left|\nabla u_{\lambda}\right|^{2}+\lambda / 4\left(\left|u_{\lambda}\right|^{2}-1\right)^{2}$,

$$
\begin{aligned}
& \int_{D_{R}\left(z_{0}\right)}\left|\left(\left(\sqrt{e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)}\right)^{p} \eta\right)\right|^{2+2 / p} d z \leq C_{F P} \Phi_{R}^{2}\left(z_{0}\right) \\
& \quad \times \int_{D_{R}\left(z_{0}\right)}\left|\nabla\left(\left(\sqrt{e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)}\right)^{p} \eta\right)\right|^{2} d z
\end{aligned}
$$

holds where $\kappa$ is any positive number, $e_{\lambda}^{(\kappa)}=\max \left\{e_{\lambda}-\kappa, 0\right\}, p=1,1+2 / d, C_{F P}$ is a positive constant independent of $\kappa, R, z_{0}, u_{\lambda}$ and $\eta$, and

$$
\begin{aligned}
& \Phi_{R}^{2}\left(z_{0}\right)=\left(10 \sqrt{3} e^{1 / 4}+1\right) R^{-d} \int_{t_{0}-4 R^{2}}^{t_{0}+R^{2}} d t \int_{D_{(1+\delta(R)) R}\left(x_{0}\right)} e_{\lambda}\left(u_{\lambda}\right) d x \\
&+ 10 \sqrt{3} R^{2-d} \exp \left(-\frac{\delta^{2}(R)}{12}\right) \operatorname{ess} \cdot \sup \\
& 0 \leq t \leq \infty \\
& \int_{B^{d}} e_{\lambda}\left(u_{\lambda}\right) d x \\
&+ 5 \sqrt{3} R\left(\sup _{x \in \partial B^{d}}\left(|x|+\frac{|x|^{2}}{\epsilon_{0}}\right) \sup _{z \in\{0\} \times B^{d} \cup[0, \infty) \times \partial B^{d}}\left|\nabla_{\tan } u_{0}\right|^{2}\right. \\
&+\left.2 \sup _{z \in\{0\} \times B^{d} \cup[0, \infty) \times \partial B^{d}}\left|\frac{\partial u_{0}}{\partial t}\right|^{2}\right) \mathcal{L}^{d-1}\left(\partial B^{d}\right) \\
& \times \sup _{0 \leq s \leq \infty} \max \left(s^{1-d}, s^{5-d}\right) \exp \left(-\frac{1}{4 s^{2}} \inf _{x \in \partial B^{d}}|x|^{2}\right)
\end{aligned}
$$

with $z_{0}=\left(t_{0}, x_{0}\right) \in Q_{\infty}, d z=d t d x, \delta(R)=\sqrt{(12(d-2)+1) \cdot|\log R|}$ and $\mathcal{L}^{d-1}=$ the $(d-1)$-dimensional Lebesgue measure.

## CHAPTER 1

## The evolution of Harmonic maps

## 1. Harmonic maps

Let $M$ be a $d$-dimensional Riemannian manifold with metric $\gamma$ and $N$ a compact $D$-dimensional manifold with a metric $g$, respectively. By Nash's embedding theorem (See Nash [87]) we assume that $N$ can be isometrically imbedded to a $\hat{D}$-dimensional Euclidean space $\mathbb{R}^{\hat{D}}$ for some positive integer $\hat{D}$. For a $C^{1}$-map $u=\left(u^{1}, \ldots, u^{\hat{D}}\right): M \rightarrow N \subset \mathbb{R}^{\hat{D}}$ let

$$
e(u)=\frac{1}{2} \gamma^{\alpha \beta}(x) u_{x_{\alpha}}^{i} u_{x_{\beta}}^{i}=: \frac{1}{2}|\nabla u|_{M}^{2}
$$

be the energy density, written in local coordinates $x=\left(x_{\alpha}\right)_{\alpha=1, \ldots, d}$ on $M$ with $\gamma=\left(\gamma_{\alpha \beta}\right),\left(\gamma^{\alpha \beta}\right)=\left(\gamma_{\alpha \beta}\right)^{-1}$. Repeated Greek indices tacitly will be summed from 1 to $d$, repeated Latin indices from 1 to $\hat{D}$. Moreover, $u_{x_{\alpha}}^{i}=\partial u^{i} / \partial x_{\alpha}$ etc. A $C^{1}$ variation of $u$ is a family $\left(u_{\epsilon}\right)$ of $C^{1}$-maps $u_{\epsilon}: M \rightarrow N \subset \mathbb{R}^{\hat{D}}$ smoothly depending on a parameter $|\epsilon|<\epsilon_{0}$, and such that $u_{0}=u$. A variation $\left(u_{\epsilon}\right)$ of $u$ is said to be compactly supported variations if there exists a compact set $\Omega \subset \subset M$ such that $u_{\epsilon}=u$ on $M \backslash \Omega$ for all $|\epsilon| \ll 1$.

Definition 1.1. A $C^{1}$-map $u: M \rightarrow N \subset \mathbb{R}^{\hat{D}}$ is harmonic if it is stationary for Dirichlet's energy

$$
\begin{equation*}
E(u)=\int_{M} e(u) d v o l_{M} \tag{1.1}
\end{equation*}
$$

with respect to compactly supported variations.
Note that in local coordinates $d v o l_{M}=\sqrt{|\gamma|} d x$, where $|\gamma|=\left|\operatorname{det}\left(\gamma_{\alpha \beta}\right)\right|$.
We derive the Euler-Lagrange equation satisfied by a harmonic map $u$ : let $U \subset \mathbb{R}^{\hat{D}}$ be a tubular neighborhood of $N$ and $\pi_{N}: U \rightarrow N$ the (smooth) nearestneighbor projection. By $T_{p} N\left(\subset T_{p} \mathbb{R}^{\hat{D}}\right)$ denote the tangent space to $N$ at a point $p \in N$. Choose $\phi \in C_{0}^{1}\left(M ; \mathbb{R}^{\hat{D}}\right)$ satisfy

$$
\phi(x) \in T_{u(x)} N
$$

for all $x \in M . \phi$ induces a $C^{1}$-variation

$$
u_{\epsilon}=\pi_{N} \circ(u+\epsilon \phi) .
$$

Since $\left.d \pi_{N}(p)\right|_{T_{p} N}=$ id for $p \in \mathbb{N}$, clearly we have

$$
\left.\frac{d u_{\epsilon}}{d \epsilon}\right|_{\epsilon=0}=\left(d \pi_{N} \circ u\right) \phi=\phi .
$$

Suppose that $\phi$ has support in a single coordinate chart. Then

$$
\begin{aligned}
\left.\frac{d E}{d \epsilon}\left[u_{\epsilon}\right]\right|_{\epsilon=0} & =\int_{M} \gamma^{\alpha \beta} \sqrt{|\gamma|} u_{x_{\beta}}^{i} \phi_{x_{\alpha}}^{i} d x \\
& =-\int_{M} \frac{1}{\sqrt{|\gamma|}} \frac{\partial}{\partial x_{\alpha}}\left(\gamma^{\alpha \beta} \sqrt{|\gamma|} \frac{\partial}{\partial x_{\beta}} u^{i}\right) \phi^{i} \sqrt{|\gamma|} d x \\
& =-\int_{M} \triangle_{M} u^{i} \phi^{i} d v o l_{M},
\end{aligned}
$$

where $\triangle_{M}=1 / \sqrt{|\gamma|} \partial / \partial x_{\alpha}\left(\gamma^{\alpha \beta} \sqrt{|\gamma|} \partial / \partial x_{\beta}\right)$ denotes the Laplace-Beltrami operator on $M$.

Thus, if $u \in C^{2}$ is harmonic, $u$ satisfies

$$
\begin{equation*}
\triangle_{M} u \perp T_{u} N \tag{1.2}
\end{equation*}
$$

and conversely. To obtain a more explicit form of (1.2), let $\nu_{D+1}, \ldots, \nu_{\hat{D}}$ denote a local orthonormal frame for $\left(T_{p} N\right)^{\perp}$, the orthogonal complement of $T_{p} N$ in $\mathbb{R}^{\hat{D}}$, near $p=u(x) \in N$. Then, by (1.2) there exist scalar functions $\lambda^{D+1}, \ldots, \lambda^{\hat{D}}$ such that

$$
-\triangle_{M} u=\sum_{k=D+1}^{\hat{D}} \lambda^{k}\left(\nu_{k} \circ u\right) .
$$

For any fixed $k$, multiplying by $\nu_{k}$, since $\left\langle u_{x_{\alpha}}, \nu_{k} \circ u\right\rangle=0$ for all $\alpha$, we obtain

$$
\begin{aligned}
\lambda^{k} & =-\triangle_{M}\left\langle u,\left(\nu_{k} \circ u\right)\right\rangle=-\operatorname{div}\left\langle\nabla u, \nu_{k}(u)\right\rangle+\gamma^{\alpha \beta}\left\langle u_{x_{\alpha}}, \frac{\partial}{\partial x_{\beta}}\left(\nu_{k} \circ u\right)\right\rangle \\
& =\gamma^{\alpha \beta} A^{k}(u)\left(u_{x_{\alpha}}, u_{x_{\beta}}\right),
\end{aligned}
$$

where $A^{k}=d \nu_{k}$ denotes the second fundamental form with respect to $\nu_{k}$. $\langle\cdot, \cdot\rangle$ means the inner product between a map and a map. Thus we find that (1.2) is equivalent to

$$
\begin{equation*}
-\triangle_{M} u=A(u)(\nabla u, \nabla u)_{M}, \tag{1.3}
\end{equation*}
$$

where in local coordinates

$$
A(u)(\nabla u, \nabla u)_{M}=\sum_{k=D+1}^{\hat{D}} \gamma^{\alpha \beta} A^{k}(u)\left(u_{x_{\alpha}}, u_{x_{\beta}}\right)\left(\nu_{k} \circ u\right) .
$$

Example 1.1. If $M=T^{d}=\mathbb{R}^{d} / \mathbb{Z}^{d}, N=S^{d} \subset \mathbb{R}^{d+1}$, equation (1.3) simply becomes

$$
-\triangle u=|\nabla u|^{2} u .
$$

Harmonic maps are a generalized concept of harmonic functions. Harmonic maps $S^{1} \rightarrow N$ correspond to closed geodesics on $N$. Important applications of harmonic maps are in Teichmüller theory in understanding the Weil-Peterson metric on Teichmüller space, see Earle-Eells [31], [32], Eells [33], Fisher-Tromba [44], Tromba [114], or in proving rigidity theorems for Kähler manifolds (Mostow [85], Mostow-Siu [86], Siu [103]). Comprehensive surveys of harmonic maps and their applications are given in Eells-Lemaire [34], [35], Hildebrandt [65], [66], Jost [70], [71] and Schoen-Yau [99]. Also Hardt [58] gives a survey of the structure of the singular set of harmonic maps and Smith [104] surveys harmonic maps from spheres to spheres. This thesis mainly treats with the case of $M=B_{1}^{d}(0) \subset \mathbb{R}^{d}$ (the $d$-dimensional unit ball) and of $N=S^{D-1}$ (the $D-1$-dimensional unit sphere) by the following reason:
(i) The sphere is the simplest target manifold in hard situation; the hard situation means, for example, the positive curvature target manifold and the manifold with $\pi_{D}(N) \neq 0$. If we compare Eells-Sampson [36] with ChenStruwe [24], what we should realize is that if we can obtain a result on harmonic maps whose target is the $D$-dimensional sphere, we can show the corresponding result on one's of the $D$-dimensional compact Riemannian manifold without a boundary.
(ii) We have two applications to physics: One is liquid crystal theory in $M=$ $B_{1}^{3}(0), N=S^{2}$, another is the instantons in Yang-Mills connections in $M=$ $\mathbb{R}^{4}, N=S^{3} \cong S U(2)$. For instance we refer to Ericksen-Kinderlehrer [38] and therein for liquid crystal theory and to Atiyah [1] for Yan-Mills connections.
(iii) A higher symmetric structure of the sphere enables us to find "highly symmetric harmonic maps." Later this will be discussed in detail.

## Bochner identity

A Bochner identity is very useful to analyze the harmonic maps: It is a certain differential equation satisfied by the energy density $e(u)$ of a harmonic map $u: M \rightarrow N$. Let $R^{(M)}$, $\operatorname{Ric}^{(M)}$ and $R^{(N)}$ denote the Riemann curvature tensor on $M$, Ricci curvature on $M$ and the Riemann curvature tensor on $N$, respectively. Given any point $x_{0} \in M, R^{(M)}=\left(R_{\alpha \mu \beta \nu}\right)$ and $\operatorname{Ric}^{(M)}=\left(R_{\alpha \beta}\right)$ respectively means the coordinate representation of $R^{(M)}, \operatorname{Ric}^{(M)}$ in normal coordinates $x=\left(x_{\alpha}\right)$ $(\alpha=1, \ldots, d)$ about $x_{0} \in M$; while $R^{(N)}=\left(\tilde{R}_{i k j l}\right)$ does the coordinate representation of $R^{(N)}$ in normal coordinates $u=\left(u^{i}\right)$ around $u_{0}=u\left(x_{0}\right) \in N$. We use the notation of Jost [72].

Proposition 1.1. If $u \in C^{3}(M ; N)$ is harmonic, then in local coordinates as above the following holds:

$$
\begin{equation*}
-\triangle_{M} e(u)+|\nabla d u|^{2}+R_{\alpha \beta} u_{x_{\alpha}}^{i} u_{x_{\beta}}^{i}=\tilde{R}_{i k j l} u_{x_{\alpha}}^{i} u_{x_{\alpha}}^{j} u_{x_{\beta}}^{k} u_{x_{\beta}}^{l}, \tag{1.4}
\end{equation*}
$$

where $\nabla$ denotes the covariant derivative on $T^{*} M \otimes u^{-1} T N$. (See Jost [72, p. 96f] for an equivalent expression in general coordinates and an invariant form of (1.4)).

Proof. The proof relies on the following identities valid at $x_{0} \in M$ in normal coordinates around $x_{0}$ on $M$ and around $u\left(x_{0}\right)$ on $N$. Let $\gamma_{, \alpha}^{\mu \nu}=\left(\gamma^{\mu \nu}\right)_{x_{\alpha}}$, etc. Then the identities are

$$
\begin{gathered}
\gamma_{, \alpha \beta}^{\mu \nu}=-\gamma_{\mu \nu, \alpha \beta} ; \\
\left(\triangle_{M} u\right)_{x_{\mu}}-\triangle_{M}\left(u_{x_{\mu}}\right)=\left(\gamma^{\alpha \beta} \sqrt{|\gamma|}\right)_{x_{\alpha} x_{\mu}} u_{x_{\beta}}=\gamma_{, \alpha \mu}^{\alpha \beta} u_{x_{\beta}}+\frac{1}{2} \gamma_{\rho \rho, \alpha \mu} u_{x_{\alpha}} \\
=-\gamma_{\alpha \beta, \alpha \mu} u_{x_{\beta}}+\frac{1}{2} \gamma_{\rho \rho, \alpha \mu} u_{x_{\alpha}} ; \\
R_{\alpha \beta}=R_{\alpha \mu \beta}^{\mu}=\Gamma_{\alpha \beta, \mu}^{\mu}-\Gamma_{\alpha \mu, \beta}^{\mu}=\frac{1}{2}\left(\gamma_{\alpha \mu, \beta \mu}+\gamma_{\beta \mu, \alpha \mu}\right)-\frac{1}{2}\left(\gamma_{\alpha \beta, \mu \mu}+\gamma_{\mu \mu, \alpha \beta}\right) .
\end{gathered}
$$

Thus, at $x_{0}$ we obtain

$$
\begin{align*}
\triangle_{M} e(u)= & \triangle_{M}\left(\frac{1}{2} \gamma^{\mu \nu} g_{i j}(u) u_{x_{\mu}}^{i} u_{x_{\nu}}^{j}\right) \\
= & \left(\triangle_{M} u_{x_{\mu}}^{i}\right) u_{x_{\mu}}^{i}+\frac{1}{2} \gamma_{, \alpha \alpha}^{\mu \nu} u_{x_{\mu}}^{i} u_{x_{\nu}}^{i}+u_{x_{\alpha} x_{\mu}}^{i} u_{x_{\alpha} x_{\mu}}^{i}+\frac{1}{2} g_{i j, k l}(u) u_{x_{\mu}}^{i} u_{x_{\mu}}^{j} u_{x_{\alpha}}^{k} u_{x_{x_{\alpha}}}^{l} \\
= & \left(\triangle_{M} u^{i}\right)_{x_{\mu}} u_{x_{\mu}}^{i}+u_{x_{\alpha} x_{\mu}}^{i} u_{x_{\alpha} x_{\mu}}^{i}+\gamma_{\alpha \beta, \alpha \mu} u_{x_{\beta}}^{i} u_{x_{\mu}}^{i} \\
& \quad-\frac{1}{2}\left(\gamma_{\mu \nu, \alpha \alpha}+\gamma_{\alpha \alpha, \mu \nu}\right) u_{x_{\mu}}^{i} u_{x_{\nu}}^{i}+\frac{1}{2} g_{i j, k l}(u) u_{x_{\mu}}^{i} u_{x_{\mu}}^{j} u_{x_{\alpha}}^{k} u_{x_{\alpha}}^{l} \\
= & \left(\triangle_{M} u^{i}\right)_{x_{\mu}} u_{x_{\mu}}^{i}+u_{x_{\alpha} x_{\mu}}^{i} u_{x_{\alpha} x_{\mu}}^{i}+R_{\alpha \beta} u_{x_{\alpha}}^{i} u_{x_{\beta}}^{i} \\
& \quad+\frac{1}{2}\left(g_{i j, k l}+g_{i l, j k}-g_{j l, i k}\right) u_{x_{\mu}}^{i} u_{x_{\mu}}^{j} u_{x_{\alpha}}^{k} u_{x_{\alpha} .}^{l} . \tag{1.5}
\end{align*}
$$

Finally, note that by (1.3) we have

$$
\left(\triangle_{M} u^{i}\right)_{x_{\mu}} u_{x_{\mu}}^{i}=-\tilde{\Gamma}_{k l, j}^{i}(u) u_{x_{\alpha}}^{k} u_{x_{\alpha}}^{l} u_{x_{\mu}}^{i} u_{x_{\mu}}^{j}
$$

at $x_{0}$, because $\tilde{\Gamma}\left(u\left(x_{0}\right)\right)=0$ by our choice of coordinates. Moreover, note

$$
\begin{align*}
& \tilde{R}_{i l j k}=\tilde{\Gamma}_{k l, j}^{i}-\tilde{\Gamma}_{j l, k}^{i}, \\
& \tilde{\Gamma}_{j l, k}^{i}=\frac{1}{2}\left(g_{i j, k l}+g_{i l, j k}-g_{j l, i k}\right) . \tag{1.6}
\end{align*}
$$

Then we conclude

$$
-\triangle_{M} e(u)+u_{x_{\alpha} x_{\mu}}^{i} u_{x_{\alpha} x_{\mu}}^{i}=-R_{\alpha \beta} u_{x_{\alpha}}^{i} u_{x_{\beta}}^{i}+\tilde{R}_{i l j k} u_{x_{\mu}}^{i} u_{x_{x_{\mu}}}^{j} u_{x_{\alpha}}^{k} u_{x_{\alpha}}^{l} .
$$

Since $\tilde{R}_{i l j k}=\tilde{R}_{i k j l}$ the claim follows.
As a consequence of (1.4), we have the following corollary; see e.g. Jost [72].

Proposition 1.2. If $M$ is compact manifold with Ric $^{M} \geq 0$ and $\partial M=\emptyset$, and if the sectional curvature of $N$ is non-positive, then any harmonic map $u \in C^{\infty}(M ; N)$ is totally geodesic in the sense that $\nabla d u \equiv 0$; that is, du is parallel with respect to the pull-back covariant derivative on $T^{*} M \otimes u^{-1} T N$. Moreover, if Ric ${ }^{M}>0$ at a point of $M$, then $u \equiv$ const. If the sectional curvature $K^{N}$ of $N$ is negative, then $u \equiv$ const or $u(M)$ is covered by a closed geodesic ball.

Proof. Integrate (1.4) over $M$ to obtain $|\nabla d u|^{2} \equiv 0, \operatorname{Ric}^{(M)}(d u, d u) \equiv 0$, $\left\langle\tilde{R}^{(N)}(d u, d u) d u, d u\right\rangle \equiv 0$ on $M$ under the above assumptions.

For most of our purposes it suffices to note a weaker Bochner-type estimate. On account of (1.6), we obtain

$$
\begin{equation*}
-\triangle_{M} e(u)+\left|\nabla^{2} u\right|^{2} \leq\left|R i c^{M}\right| e(u)+C(e(u))^{2} . \tag{1.7}
\end{equation*}
$$

## Weakly harmonic maps

Let

$$
H^{1,2}(M ; N)=\left\{u \in H^{1,2}\left(M ; \mathbb{R}^{\hat{D}}\right) ; u(x) \in N \quad \text { for almost every } x \in M\right\}
$$

where $H^{1,2}\left(M ; \mathbb{R}^{\hat{D}}\right)$ is the standard Sobolev space of $L^{2}$-maps $u: M \rightarrow \mathbb{R}^{\hat{D}}$ with distributional derivative $\nabla u \in L^{2}$. That is, $H^{1,2}(M ; N)$ is the space of maps $u: M \rightarrow N$ with finite energy $E(u)$. It was observed by Schoen-Uhlenbeck [98] that in general $H^{1,2}(M ; N)$ as defined above is larger than the weak closure of $C^{\infty}(M ; N)$ in the $H^{1,2}$-norm

$$
\|u\|_{H^{1,2}}^{2}=\int_{M}\left(|u|^{2}+|\nabla u|^{2}\right) d v o l_{M},
$$

which in turn is larger than the strong closure of $C^{\infty}(M ; N)$ in $H^{1,2}(M ; N)$. However, if $\operatorname{dim} M=2$, these spaces all coincide. By a result of Bethuel [4], the same is true if $\pi_{2}(N)=0$. The relations between Sobolev spaces whose elements are maps from $M$ to $N$ and it's weak- and strong- closures were analyzed by BethuelZheng [9] and Bethuel [4].

Definition 1.2. A map $u \in H^{1,2}(M ; N)$ is called weakly harmonic if $u$ satisfies (1.3) in the distribution sense.

Example 1.2. The map $u: B_{1}^{d}(0) \subset \mathbb{R}^{d} \rightarrow S^{d-1}$ given by

$$
u(x)=\frac{x}{|x|},
$$

belongs to $H^{1,2}\left(B_{1}^{d}(0) ; S^{d-1}\right)$ for $d \geq 3$ and weakly solves (1.3), that is, this map $u$ satisfies

$$
-\triangle u=|\nabla u|^{2} u \quad \text { in } \quad\left(\mathcal{D}\left(B_{1}^{d}(0) ; \mathbb{R}^{d}\right)\right)^{\prime}
$$

## Existence of harmonic maps

As in Hodge theory, where one seeks to realize a de Rham cohomology class by a harmonic differential form, a basic existence problem for harmonic maps is the following:

Homotopy problem: Given a map $u_{0}: M \rightarrow N$, is there a harmonic map $u$ homotopic to $u_{0}$ ?

This question, as we shall see below, has an affirmative answer if the sectional curvature $K^{N}$ of $N$ is non-positive (Eells-Sampson [36]) or if $d=2$ and $\pi_{2}(N)=0$ (Lemaire [76], Sacks-Uhlenbeck [95]). However, for $N=S^{2}$ and $d=2$, we have the following counter-examples:

Example 1.3. (Lemaire [76], Wente [119]): If $u: B_{1}^{2}(0) \subset \mathbb{R}^{2} \rightarrow S^{2}$ is harmonic and $u_{\partial B_{1}^{2}(0)} \equiv$ const, then $u \equiv$ const.

Example 1.4. (Eells-Wood [37]): If $u: T^{2} \rightarrow S^{2}$ is harmonic, then $\operatorname{deg} u \neq \pm 1$.
In higher dimensions ( $d \geq 3$ ), hardly any result is known for the homotopy problem unless $K^{N} \leq 0$. However, there are various existence results for the Dirichlet problem.

## Dirichlet problem and variational methods

The Dirichlet problem can be formulated as follows: Suppose $\partial M \neq \emptyset$ and let $u_{0}: M \rightarrow N$ be any given map belonging to $H^{1,2}(M ; N)$. Is there a harmonic map $u: M \rightarrow N$ such that $u=u_{0}$ on $\partial M$ ?

The Dirichlet problem can be attacked by using variational methods. Once we can seek a map which minimizes $E$ among the class

$$
H_{u_{0}}^{1,2}(M ; N)=\left\{u \in H^{1,2}(M ; N) ; u=u_{0} \text { on } \partial M\right\},
$$

we obtain a weakly harmonic map $u$ satisfying the desired boundary condition because the harmonic maps are the critical points of the energy (1.1) in the class above.

In other words, the variational methods are to find a map $u_{\min } \in H_{u_{0}}^{1,2}(M ; N)$ with

$$
\begin{equation*}
E\left[u_{\text {min }}\right]=\inf _{u \in H_{u_{0}}^{1,2}(M ; N)} E[u] . \tag{1.8}
\end{equation*}
$$

The map satisfying (1.8) is usually called "minimizer." It is easy to check that (1.3) is the Euler-Lagrange equations of the energy (1.1) among $H_{u_{0}}^{1,2}(M ; N)$. That is, to show the existence of a harmonic map, we have only to search a smooth minimizer. If $\operatorname{dim} M=2$, Morrey [83] has proved:

Theorem 1.1. Every minimizer $u_{\min }: M \rightarrow N$ with $\operatorname{dim} M=2$, is smooth.
On the other hand, in $\operatorname{dim} M \geq 3$, by the topological obstruction, we have nohope to prove the everywhere regularity. For instance the equator map $x \rightarrow x /|x|$
$: B_{1}^{3}(0) \rightarrow S^{2}$ is the unique absolute minimizer of $E[\cdot]$ in $H_{x}^{1,2}\left(B_{1}^{3}(0) ; S^{2}\right)$. (Brezis-Coron-Lieb [11], Lin [79]). Schoen-Uhlenbeck [97] and [98] have established:

Theorem 1.2. A minimizer $u_{\min }$ of $E[\cdot]$ in $H_{u_{0}}^{1,2}(M ; N)$ with $\operatorname{dim} M \geq 3$ is smooth on an open set whose compliment has at most ( $\operatorname{dim} M-3$ )-dimensional Hausdorff dimension.

This result is best possible. For example, even if a map $u_{\left.0\right|_{\partial B_{1}^{d}(0)}}: \partial B_{1}^{d}(0)=$ $S^{d} \rightarrow S^{d}$ is smooth with 0-degree, a minimizer of $E[\cdot]$ in $H_{u_{0}}^{1,2}\left(B_{1}^{d}(0) ; S^{d-1}\right)$ is not always smooth, nevertheless a smooth extention of $u_{\left.0\right|_{\partial B_{1}^{d}(0)}}$ inside $B_{1}^{d}(0)$ exists. In addition if we regard the map $u(x)=x /|x|$ as a map $u: B_{1}^{d}(0) \subset \mathbb{R}^{d} \rightarrow S^{d-1}$ $\subset S^{d} \subset \mathbb{R}^{d+1}$, there is no topological reason for a singularity. However the maps $u$ above are still minimizer in $H_{x}^{1,2}\left(B_{1}^{d}(0) ; S^{d}\right)$ if $d \geq 7$ (Jäger-Kaul [68], Baldes [2]). Related to liquid crystal theory, a property of $E[\cdot]$ in $H_{u_{0}}^{1,2}\left(B_{1}^{3}(0) ; S^{2}\right)$ has been much drawn into concerns from 80' (Ericksen-Kinderlehrer [38]). Basic facts to the minimizers of $E[\cdot]$ in $H_{u_{0}}^{1,2}\left(B_{1}^{3}(0) ; S^{2}\right)$ are the following:
(i) Monotonicity for the scaled energy and the hybrid inequality: The fundamental technical properties of minimizers may be monotonicity and the hybrid inequality: Let $u_{\text {min }}$ be minimizers of $E[\cdot]$ in $H_{u_{0}}^{1,2}\left(B_{1}^{3}(0) ; S^{2}\right)$ and set $x_{0} \in B_{1}^{3}(0)$, any ball $B_{r_{1}}\left(x_{0}\right) \subset B_{r_{2}}\left(x_{0}\right) \subset \subset B_{1}^{3}(0)$; Then monotonicity denotes

$$
\frac{1}{r_{1}} \int_{B_{r_{1}}}|\nabla u|^{2} d x \leq \frac{1}{r_{2}} \int_{B_{r_{2}}}|\nabla u|^{2} d x
$$

while the hybrid inequality is given by

$$
\int_{B_{r}}|\nabla u|^{2} d x \leq C \int_{\partial B_{r}}|\nabla u \| u-a| d \mathcal{H}^{2},
$$

for any vector $a \in \mathbb{R}^{3}$ and any ball $B_{r}\left(x_{0}\right) \subset \subset B_{1}^{3}(0)$ with some positive number $C$ depending only on the dimension 3. For the proof, see SchoenUhlenbeck [97] and Hardt-Kinderlehrer-Lin [59].
(ii) Tangential approximation: A rich development occurred in a paper of Simon [102] which provides with the problem the existence of the unique tangential approximating maps. At regular points, the tangential approximating map is constant. For a singular point $y$ of $u_{\min }$ in $B_{1}^{3}(0)$, in the light of Simon's result [102], there exists the unique harmonic map $f: S^{2} \rightarrow S^{2}$ such that $u\left(y+r \omega_{2}\right) \rightarrow f\left(\omega_{2}\right)$ as $r \searrow 0$ uniformly with $\omega_{2}=(x-y) /|x-y|$.
Similarly, one can try to solve the homotopy problem by minimizing $E[\cdot]$ in a given homotopy class. However, Lemaire's example shows that in general homotopy classes are not weakly closed in $H^{1,2}(M ; N)$.

This is made explicit by the following example, whose construction relies on the fact that the conformal group on $S^{2}$ acts non-compactly on $H^{1,2}\left(S^{2} ; S^{2}\right)$.

Example 1.5. When we set $\pi_{p}: S^{2} \backslash\{p\} \rightarrow \mathbb{R}^{2}$ which denotes stereographic projection and $D_{\lambda} x=\lambda x$ which is dilation by a factor $\lambda$, the maps

$$
u_{\lambda}=\pi_{p}^{-1} \circ D_{\lambda} \circ \pi_{p}: S^{2} \rightarrow S^{2},
$$

are homotopic to the identity $i d=u_{1}: S^{2} \rightarrow S^{2}$. But

$$
u_{\lambda} \rightharpoondown u_{\infty}(x) \equiv p \quad(\lambda \rightarrow \infty),
$$

weakly in $H^{1,2}\left(S^{2} ; S^{2}\right)$. (Accidentally, by conformal invariance of $E$ in dimension $d=2$, all $u_{\lambda}$ are harmonic!)

Non-minimizing harmonic maps: By the lack of information, the study of nonminimizing harmonic maps is quite challenging. If $\operatorname{dim} M=2$, Grüter [55] proved smoothness of conformal weakly harmonic maps. This result was extended by Schoen [96] to harmonic maps that are stationary with respect to variations of parameters in the domain: He showed that the harmonic maps above have a holomorphic Hopf differential

$$
(\partial u)^{2} d z^{2}:=\left(\left|u_{x}\right|^{2}-\left|u_{y}\right|^{2}-2 i\left\langle u_{x}, u_{y}\right\rangle\right) d z^{2}
$$

in suitable conformal parameters $z=x+i y$ on $M$. Finally Hélein [63] recently has shown the regularity of weakly harmonic maps in general.

Theorem 1.3 (Hélein [63]). Assume $\operatorname{dim} M=2$ and let $u \in H^{1,2}(M, N)$ be weakly harmonic. Then $u \in C^{\infty}(M ; N)$.
Proof. For $N=S^{\hat{D}-1}$ and $M=B_{1}^{2}(0)$, his proof invokes a trick: the equivalence of (1.3) and

$$
-\triangle u^{i}=\sum_{j=1}^{\hat{D}}\left\langle\nabla u^{j}, u^{i} \nabla u^{j}-u^{j} \nabla u^{i}\right\rangle(i=1, \ldots, \hat{D}),
$$

in the light of $0=\nabla|u|^{2}=2 \sum_{j} u^{j} \nabla u^{j}$. He then observes that for any $i, j=1,2, \ldots, \hat{D}$, there holds

$$
\begin{equation*}
\operatorname{div}\left(u^{i} \nabla u^{j}-u^{j} \nabla u^{i}\right)=u^{i} \triangle u^{j}-u^{j} \triangle u^{i}=0 . \tag{1.9}
\end{equation*}
$$

Thus there is a potential $a^{i j} \in H^{1,2}$ such that

$$
\operatorname{rot} a^{i j}=u^{i} \nabla u^{j}-u^{j} \nabla u^{i}
$$

and (1.3) takes the form

$$
-\triangle u^{i}=\sum_{j=1}^{\hat{D}}\left(u_{x_{1}}^{j} a_{x_{2}}^{i j}-u_{x_{2}}^{j} a_{x_{1}}^{i j}\right) \quad \text { for } \quad x=\left(x_{1}, x_{2}\right) \in B_{1}^{2}(0) .
$$

Here the right-hand side is the sum of Jacobians of $H^{1,2}$-maps. Continuity of $u$ (and hence smoothness) then follows from results of Wente [118] and BrezisCoron [10].

Notice that (1.9) is a consequence of Noether's principle and the symmetries of $S^{\hat{D}-1}$. Hélein then generalized this simple and beautiful idea to arbitrary target manifolds by an ingenious choice of rotated frame fields on $u^{-1} T N$.
Inspired by Hélein's result, Evans [40] has obtained a partial regularity result for "stationary" weakly harmonic maps from $B^{d}$ to $S^{D-1}$ with $d \geq 3$ and $D \geq 3$. A drastic difference between $d=2$ and $d \geq 3$ actually emerges to the smoothness result on weakly harmonic maps. Hardt-Lin-Poon [61] has constructed examples of harmonic maps $u: B_{1}^{3}(0) \rightarrow S^{2}$ with the cylindrical symmetry whose boundary data $u \|_{\partial B_{1}^{3}(0)}: \partial B_{1}(0) \cong S^{2} \rightarrow S^{2}$ have degree 0 so that $u$ possesses an arbitrarily large number of singular points on the axis of symmetry and Rivière [93] has exhibited weakly harmonic maps $u: \mathbb{R}^{3} \rightarrow S^{2}$ with line singularities.

## 2. Evolutional harmonic maps

## The Eells-Sampson result

By Examples 1.3, 1.4 and 1.5 above, we know that it may be difficult to solve the homotopy problem for harmonic maps by variational methods. To overcome these difficulties, Eells - Sampson [36] proposed to study the evolution problem

$$
\begin{equation*}
u_{t}-\triangle_{M} u=A(u)(\nabla u, \nabla u)_{M} \quad \text { on }[0, \infty) \times M \tag{1.10}
\end{equation*}
$$

with initial and boundary data

$$
\begin{equation*}
u=u_{0} \quad \text { at } t=0 \text { and on }[0, \infty) \times \partial M \tag{1.11}
\end{equation*}
$$

for maps $u:[0, \infty) \times M \rightarrow N \subset \mathbb{R}^{\hat{D}}$, the idea behind this strategy of course being that a continuous deformation $u(t, \cdot)$ of $u_{0}$ will remain in the given homotopy class. Moreover, the "energy inequality" (see Lemma 1.1 below) shows that (1.10) is the $\left(L^{2}\right)$-gradient flow for $E$, whence one can hope that the solution $u(t, \cdot)$ for $t \rightarrow \infty$ will converge to a critical point (a harmonic map) of $E$, if we can show that the $\left(L^{2}\right)$-gradient flow for $E$ is smooth; for suitable targets, this program is successfully solved.

Theorem 1.4 (Eells-Sampson [36]). Suppose that $M$ is compact without boundary and that the sectional curvature $K^{N}$ of $N$ is non-positive. Then for any $u_{0} \in C^{\infty}(M ; N)$, the Cauchy problem (1.10) and (1.11) admits the unique, global, smooth solution $u: M \times[0, \infty) \rightarrow N$ which, as $t \rightarrow \infty$ suitably, converges smoothly to a harmonic map $u_{\infty} \in C^{\infty}(M ; N)$ homotopic to $u_{0}$.

The proof uses three ingredients.
Lemma 1.1 (Energy inequality). Set $E(u(t))=\int_{M} e(u)(t, \cdot) d v o l_{M}$ and let $T$ be any positive number For a smooth solution $u$ of (1.10) and (1.11), it follows

$$
\int_{0}^{T} \int_{M}\left|u_{t}\right|^{2} d t d v o l_{M}+E(u(T)) \leq E\left(u_{0}\right)
$$

Proof. Recall that $A(u)(\nabla u, \nabla u) \perp T_{u} N$. Multiplying (1.10) by $u_{t}$ and integrating by parts, we obtain

$$
\int_{M}\left|u_{t}\right|^{2} d v o l_{M}+\frac{d E}{d t}(u(t))=0
$$

for any $t \geq 0$ and the desired estimate (in fact, with equality) follows from integrating in $t$.

Lemma 1.2 (Bochner inequality). If $K^{N} \leq 0$, then for any smooth solution $u$ of (1.10) with energy density e(u), there holds

$$
\begin{equation*}
\left(\frac{\partial}{\partial t}-\triangle_{M}\right) e(u) \leq C e(u) \tag{1.12}
\end{equation*}
$$

with a constant $C$ depending only on the Ricci curvature of $M$.
Proof. To derive this estimate we use the representation of $u$ in suitable local coordinates on $N$ : $u=\left(u^{1}, \ldots, u^{\hat{D}}\right)$. As in deriving (1.4) from (1.3) in the stationary case, we can conclude that (in normal coordinates around $x_{0}$ on $M$ )

$$
\left(\frac{\partial}{\partial t}-\triangle_{M}\right) e(u)+|\nabla d u|^{2}+R_{\alpha \beta} u_{x_{\alpha}}^{i} u_{x_{\beta}}^{i}=\tilde{R}_{i k j l} u_{x_{\alpha}}^{i} u_{x_{\alpha}}^{j} u_{x_{\beta}}^{k} u_{x_{\beta}}^{l}
$$

at $\left(t, x_{0}\right)$, where $\nabla, R_{\alpha \beta}, \tilde{R}_{i k j l}$, respectively, denotes the pull-back covariant derivative on $T^{*} M \otimes u^{-1} T N$, the Ricci curvature on $M$ and the Riemann curvature tensor on N. From this identity, the claim follows.

From (2), we obtain

$$
\begin{equation*}
\left(\frac{\partial}{\partial t}-\triangle_{M}\right) e(u)+\left|\nabla^{2} u\right|^{2} \leq C_{M} e(u)+C_{N}(e(u))^{2} \tag{1.13}
\end{equation*}
$$

where $\left|\nabla^{2} u\right|^{2}=\gamma^{\alpha \beta} \gamma^{\mu \nu} u_{x_{\alpha} x_{\mu}}^{i} u_{x_{\beta} x_{\nu}}^{i}$ and $C_{M}, C_{N}$ respectively denotes constant depending only on the Ricci curvature of $M$ and the second fundamental form of $N$.

The final ingredient is Moser's [84] sup-estimate for sub-solutions of parabolic equations. Set

$$
\mathcal{L}=\frac{\partial}{\partial t}-\triangle_{M} .
$$

By $Q_{R}\left(z_{0}\right)$, denote the cylinder

$$
Q_{R}\left(z_{0}\right)=\left\{z=(t, x) ; t_{0}-R^{2}<t<t_{0},\left|x-x_{0}\right|<R\right\}
$$

in local coordinates on $M$, where $z_{0}=\left(t_{0}, x_{0}\right) \in M$ and $R>0$. Note that $\gamma^{\alpha \beta} \in$ $C^{\infty}\left(Q_{R}\left(z_{0}\right)\right)$ satisfies the uniform ellipticity condition: there exist positive numbers $0<\lambda \leq \Lambda$ such that for any vector $\xi \in \mathbb{R}^{d}$

$$
\lambda|\xi|^{2} \leq \sqrt{|\gamma|} \gamma^{\alpha \beta}(z) \xi_{\alpha} \xi_{\beta} \leq \Lambda|\xi|^{2}
$$

holds in $z \in Q_{R}\left(z_{0}\right)$.

Lemma 1.3. Suppose that any smooth nonnegative function $v$ on $Q_{R}\left(z_{0}\right)$ satisfies $\mathcal{L} v \leq C_{1} v$ where $C_{1}$ is a positive constant. Then for some positive constant $C_{\mathrm{H}}=C_{\mathrm{H}}\left(\bar{\lambda}, \Lambda, C_{1}\right)$ the following holds

$$
\sup _{Q_{R / 2(0)}} e(v) \leq C_{\mathrm{H}} R^{-(d+2)} \int_{Q_{R}\left(z_{0}\right)} e(v) d z
$$

Proof of Theorem 1.4. Local existence can be inferred from the a-priori estimates for uniformly parabolic equations Ladyženskaya-Solonnikov-Ural'ceva [75]) and the standard implicit function theorem; see Hamilton [57].

Let $T$ be a maximal time of a local existence of the solution of (1.10) and (1.11) and $u \in C^{\infty}([0, T) \times M ; N)$ the solution of (1.10). By Lemma 1.2, the energy density is a subsolution to the equation

$$
\left(\partial_{t}-\triangle_{M}\right) e(u) \leq C e(u) .
$$

Let $\iota_{M}$ be the convexity radius on $M$. Choose $R<\min \left\{1, \sqrt{T}, \iota_{M}\right\}$ and apply Lemma 1.3 to conclude that

$$
\begin{aligned}
e(u)\left(z_{0}\right) & \leq C R^{-(d+2)} \int_{Q_{R}\left(z_{0}\right)} e(u) d z \\
& \leq C R^{-(d+2)} \int_{t_{0}-R^{2}}^{t_{0}} E(u(t)) d t \\
& \leq C R^{-d} E\left(u_{0}\right)
\end{aligned}
$$

for any $z_{0}=\left(t_{0}, x_{0}\right), t_{0} \geq R^{2}$, where $C=C(M)$. Hence $|\nabla u|$ is uniformly bounded on any compact set on $[0, T] \times M$. By a boot-strap argument, we obtain uniform bounds for all derivatives of $u$ on the same region as above; there exists a positive constant $C$ depending only on $E\left(u_{0}\right), M$ and $N$ such that $\sup _{K}\left|\nabla^{k} u\right| \leq C$ for any compact set $K$ in $[0, T] \times M$ and for any positive integer $k$. The solution thus can be continued as a smooth solution to (1.10) on $[0, \infty) \times M$. The preceding argument, then gives the uniform a-priori bounds for $u$ and its derivatives on $[1, \infty) \times M$ depending only on $M, N$ and $E\left(u_{0}\right)$. Hence, by Ascoli and Arzéla's theorem, the flow $(u(t, \cdot))_{t \geq 1}$ is relatively compact in any $C^{k}$-Topology. Finally, by Lemma 1.1, for a sequence $t_{k} \rightarrow \infty$ we have $u_{t}\left(t_{k}, \cdot\right) \rightarrow 0$ in $L^{2}(M)$, therefore a sub-sequence $\left(u\left(t_{k}, \cdot\right)\right)$ converges smoothly to a harmonic map $u_{\infty}$. As $u\left(t_{k}, \cdot\right)$ is homotopic to $u_{0}$ through the flow $(u(t, \cdot))_{0 \leq t \leq t_{k}}$ for any $k$, so is $u_{\infty}$. If $K^{N}<0$, the uniqueness of $u_{\infty}$ and the convergencity of the flow $u(t, \cdot) \rightarrow u_{\infty}$ follows from a maximum principle due to Jäger-Kaul [67].

The Eells-Sampson result was extended to harmonic maps with boundary by Hamilton [57]. The condition $K^{N} \leq 0$ can be replaced by the condition that the image of $u_{0}$ (and hence of $u$ ) should support a uniformly strictly convex function; see Jost [69] and von Wahl [116]. However, none of these results can be applied in case $u_{0}: T^{2} \rightarrow S^{2}$ has degree 1 and indeed Example 1.4 above shows that the
flow (1.10) and (1.11) in this case cannot exist for all time and does not converge smoothly as $t \rightarrow \infty$.

## 3. Finite time blow-up

It is remained to prove the question whether the heat flow (1.10) will develop singularities in finite or infinite time. Reversing the order of the historical developments, we first state this problem and later present the existence results for weak solutions that are the answers to these questions.

The heat flow (1.10) is a quasi-linear parabolic system and therefore hard to deal with explicitly. However when $N=S^{d}$, by enough symmetry, (1.10) can be reduced to a scalar equation in only two variables. Consider equivariant maps

$$
u_{0}(x)=\left(\frac{x}{|x|} \sin h_{0}(r), \cos h_{0}(r)\right)
$$

of $B_{1}^{d}(0)$ into $S^{d}$, where $r=|x|, h_{0}(0)=0$ and let $u: \quad[0, T) \times B_{1}^{d}(0) \rightarrow S^{d} \subset \mathbb{R}^{d+1}$ be the corresponding smooth solution of (1.10) and (1.11), defined on a maximal time interval $[0, T)$. By uniqueness, also $u$ is equivariant and can be written

$$
\begin{equation*}
u(t, x)=\left(\frac{x}{|x|} \sin h(t, r), \cos h(t, r)\right) \tag{1.14}
\end{equation*}
$$

in terms of a smooth map $h:[0, T) \times[0,1] \rightarrow \mathbb{R}$ satisfying the initial and boundary conditions

$$
\begin{array}{lll}
h(0, r)=h_{0}(r) & \text { for } & 0 \leq r \leq 1, \\
h(t, 0)=h_{0}(0)=h_{0, r r}(0)=0 & \text { for } & 0 \leq t \leq T,  \tag{1.15}\\
h(t, 1)=h_{0}(1)(=: b) & \text { for } & 0 \leq t \leq T .
\end{array}
$$

In terms of $h$, the equation (1.10)

$$
u_{t}-\triangle u=|\nabla u|^{2} u,
$$

becomes

$$
\begin{equation*}
h_{t}-h_{r r}-\frac{d-1}{r} h_{r}+\frac{\sin 2 h}{2 r^{2}}=0 . \tag{1.16}
\end{equation*}
$$

If $d \geq 3$, it was shown by Coron-Ghidaglia [28] that for suitable $h_{0}$, the solution $h$ of (1.15) and (1.16) -and therefore the solution $u$ of (1.10) and (1.11) - cannot be smoothly continued beyond some finite time. We will later see a deeper reason for this; see Theorem 1.11.

The case $d=2$ is more interesting. In dimension $d=2$, a family of stationary solutions $h$ of (1.16) with $h(0)=0$ is obtained by stereographic projection from
the south pole; see Example 1.5. In terms of $r=|x|$ and the polar angle $\theta=\phi(r)$ the stereographic projection is given by

$$
\frac{\sin \theta}{1+\cos \theta}=r
$$

we can write $\phi$ as

$$
\phi(r)=\arccos \left(\frac{1-r^{2}}{1+r^{2}}\right) .
$$

From a dilation $r \rightarrow r \lambda$, we obtain the family

$$
\phi_{\lambda}(r)=\phi\left(\frac{r}{\lambda}\right)=\arccos \left(\frac{\lambda^{2}-r^{2}}{\lambda^{2}+r^{2}}\right), \quad \lambda>0,
$$

of stationary solutions of (1.16) with $\phi_{\lambda}(0)=0$.
Theorem 1.5 (Grayson-Hamilton [50], Chang-Ding [17]). Let $d=2$. Suppose $\left|h_{0}\right| \leq \pi$. Then the solution $h$ of (1.15) and (1.16) exists for all time.
Proof. The idea is to construct a barrier, preventing $h$ from becoming discontinuous in finite time. Smoothness of $h$ in $(0,1)$ then follows from general results on quasilinear parabolic systems; see Ladyženskaya-Solonnikov-Ural'ceva [75].

First note that Lemma 1.1 translates into the uniform energy bound

$$
\pi \int_{0}^{1}\left|h_{r}\right|^{2} r d r \leq E(u(t)) \leq E\left(u_{0}\right)
$$

Hence, by Sobolev's embedding theorem, $h(t, \cdot)$ is locally Hölder continuous on $(0,1]$ uniformly in $t$, and a singularity can only develop at the origin.

We assume $0 \leq h_{0} \leq \pi$ for simplicity. Let $h_{1} \geq h_{0}$ satisfy $\pi / 2<h_{1} \leq \pi, h_{1}(0)=\pi$ and $h_{1}(a)<\pi$ for some $a \in(0,1]$. That is, $h_{1}$ maps into the (convex) lower hemisphere. Therefore, equation (1.10) and hence (1.16) with initial data $h(0, \cdot)=h_{1}$ possesses a global, smooth solution $\tilde{h}$. Moreover by the maximum principle (See Jäger-Kaul [67]), $\tilde{h}(t, r)<\pi$ for $0<r<1$ and $t>0$. Choose a strictly increasing function $\lambda(t)$ such that $\phi_{\lambda(0)}>h_{0}$ on $(0, a]$ and $\phi_{\lambda(t)}(a)>\tilde{h}(t, a)$ for all $t \geq 0$. Let

$$
\bar{h}(r, t)= \begin{cases}\inf \left\{\phi_{\lambda(t)}(r), \tilde{h}(t, r)\right\} & 0 \leq r \leq a \\ \tilde{h}(t, r) & a \leq r \leq 1\end{cases}
$$

be our barrier. Note that $\bar{h}$ is a supersolution to (1.16). Similarly, $\underline{h} \equiv 0$ is a subsolution. Hence $0 \leq h(t, r) \leq \bar{h}(t, r)$ on $[0, T] \times[0,1]$ by the maximum principle and $h(t, \cdot)$ is continuous. As a result, the smoothness of $h$ follows form Chang-Ding [17, Lemma 3.1] Thus $u$ is smooth at $r=0$ for any $t \geq 0$.

Quite surprisingly, the initial condition that $\left|b_{0}\right| \leq \pi$ in Theorem 1.5 is sharp.
Theorem 1.6 (Chang-Ding-Ye [18]). Suppose $|b|>\pi$. Then the solution $h$ to (1.15) and (1.16) blows up at finite time.

Proof. Let $b>\pi$. We show the existence of a sub-solution $f$ to (1.16) with $f(t, 0)=$ $0 \leq f \leq f(t, 1)=b$ such that $f_{r}(t, 0) \rightarrow \infty$ as $t \rightarrow T$ for some $T<\infty$. Set $h_{0}=f(0, \cdot)$ and let $h$ be the corresponding solution of (1.15) and (1.16), the maximum principle then implies that $h \geq f$ on $[0,1] \times[0, T)$. Consequently, $h$ must blow up before time $T$. (For general initial data the proof is somewhat more complicated.)

We make the following ansatz for $f$ :

$$
f(t, r)=\phi_{\lambda(t)}(r)+\phi_{\mu}\left(r^{1+\epsilon}\right),
$$

where $\epsilon>0, \mu>0$ and $\lambda=\lambda(t)$ will be suitably chosen later. Note that for any $\epsilon>0$ we have

$$
\phi_{\mu}\left(r^{1+\epsilon}\right)=\arccos \left(\frac{\mu^{2}-r^{2+2 \epsilon}}{\mu^{2}+r^{2+2 \epsilon}}\right) \rightarrow 0 \quad(\mu \rightarrow \infty)
$$

uniformly in $r \in[0,1]$. Hence, for any given $\epsilon>0$, taking $\mu^{2} \geq 2 / \epsilon+1$, we obtain

$$
\cos \phi_{\mu}\left(r^{1+\epsilon}\right) \geq \frac{1}{1+\epsilon} \quad \text { for } r \in[0,1] \text {. }
$$

Next observe that for any $\mu$ and $\epsilon>0$ the function $\theta(r)=\phi_{\mu}\left(r^{1+\epsilon}\right)$ satisfies

$$
-\theta_{r r}-\frac{1}{r} \theta_{r}+\frac{(1+\epsilon)^{2} \sin 2 \theta}{2 r^{2}}=0
$$

Therefore

$$
\begin{aligned}
\tau(f) & :=f_{r r}+\frac{1}{r} f_{r}-\frac{\sin 2 f}{2 r^{2}} \\
& =\frac{\left(-\sin 2\left(\phi_{\lambda}+\theta\right)+\sin 2 \phi_{\lambda}+(1+\epsilon)^{2} \sin 2 \theta\right)}{2 r^{2}} \\
& =\frac{\left(\sin \left(\left(2 \phi_{\lambda}+\theta\right)-\theta\right)-\sin \left(\left(2 \phi_{\lambda}+\theta\right)+\theta\right)+(1+\epsilon)^{2} \sin 2 \theta\right)}{2 r^{2}} \\
& =\frac{\left(-2 \cos \left(2 \phi_{\lambda}+\theta\right) \sin \theta+2(1+\epsilon)^{2} \cos \theta \sin \theta\right)}{2 r^{2}} \\
& \geq \frac{(1+\epsilon)-\cos \left(2 \phi_{\lambda}+\theta\right)}{r^{2}} \sin \theta \\
& \geq \frac{\epsilon}{r^{2}} \sin \theta=\frac{\epsilon}{r^{2}} \frac{2 \mu r^{1+\epsilon}}{\mu^{2}+r^{2+2 \epsilon}} \geq \epsilon_{1} r^{\epsilon-1} \quad \text { as long as } \epsilon_{1}=\frac{2 \mu \epsilon}{\mu^{2}+1}>0 .
\end{aligned}
$$

On the other hand, we have

$$
\frac{\partial f}{\partial t}(t, r)=\frac{\partial \phi_{\lambda(t)}(r)}{\partial t}=-\frac{2 r}{\lambda^{2}+r^{2}} \frac{d \lambda(t)}{d t}
$$

Let $\lambda(t)$ solve $d \lambda / d t=-\delta \lambda^{\epsilon}$ where $\delta>0$ to be determined:

$$
\lambda(t)=\left[\lambda_{0}^{1-\epsilon}-(1-\epsilon) \delta t\right]^{1 /(1-\epsilon)} .
$$

Then $f_{r}(t, 0) \rightarrow+\infty$ as $t \nearrow T=\lambda_{0}^{1-\epsilon} /(1-\epsilon) \delta$. Finally

$$
\frac{\partial f}{\partial t}-\tau(f) \leq \frac{2 \delta \lambda^{\epsilon} r}{\lambda^{2}+r^{2}}-\epsilon_{1} r^{\epsilon-1}=\left[\frac{2 \delta \lambda^{\epsilon} r^{2-\epsilon}}{\lambda^{2}+r^{2}}-\epsilon_{1}\right] r^{\epsilon-1} .
$$

But by Young's inequality

$$
\lambda^{\epsilon} r^{2-\epsilon} \leq C(\epsilon)\left(\lambda^{2}+r^{2}\right),
$$

and hence $f$ is a sub-solution of (1.16) for sufficiently small $\delta=\delta(\epsilon)>0$ as desired. Since $\epsilon>0$ is arbitrary, $\sup |f(0, \cdot)-\pi|$ can be taken as small as we wish

## 4. Global existence and uniqueness of partially regular weak solutions on the surface

Theorem 1.6 shows that in general, smooth and global solutions to (1.10) and (1.11) do not exist. However, the following question comes to my mind: Is there a "weak" analogue of Theorem 1.4 that will still provide a satisfactory meanings towards deciding the homotopy problem? We state an exact definition on "a global weak solution of (1.10) and (1.11):" Set $V((0, \infty) \times M ; N)=$ $L^{\infty}\left((0, \infty) ; H^{1,2}(M ; N)\right) \cap H^{1,2}\left((0, \infty) ; L^{2}(M: N)\right)$.

Definition 1.3. Let $u_{0} \in H^{1,2}(M ; N)$. If we say a map $u \in V((0, \infty) \times M ; N)$ to be "weakly evolutional harmonic map", $u$ satisfy (1.10) in $\mathcal{D}^{\prime}([0, \infty) \times M)$, $\lim _{t \rightarrow+0} u(t, \cdot)=u_{0}(\cdot)$ in the sense of $L^{2}(M)$-norm.

The following result is mainly due to Struwe [107]; the result was extended to the case $\partial M \neq \emptyset$ by Chang [16].

Theorem 1.7. Suppose that $M$ is a compact Riemann surface and $N \subset \mathbb{R}^{\hat{D}}$ is compact Riemannian manifold without boundary. Then for any $u_{0} \in H^{1,2}(M ; N)$, there exists a global weak solution $u:[0, \infty) \times M \rightarrow N$ of (1.10) and (1.11) satisfying the energy inequality and belonging to class $C^{\infty}$ on $(0, \infty) \times M$ away from finitely many points $\left(t_{\mathrm{s}, j}, x_{\mathrm{s}, j}\right)(j=1, \ldots, \mathcal{J})$. The solution $u$ is unique in this class.

At a singularity $\left(t_{\mathrm{s}}, x_{\mathrm{s}}\right), a$ (non-constant) harmonic sphere $\bar{u}: S^{2} \rightarrow N$ separates in the sense that for suitable sequences $t_{k} \nearrow t_{\mathrm{s}}, x_{k} \rightarrow x_{\mathrm{s}}, R_{k} \searrow 0$, the rescaled maps

$$
u_{k}(x)=u\left(t_{k}, x_{k}+R_{k} \bar{x}\right): B_{1}^{2}(0) \rightarrow N
$$

(in a local conformal chart around $x_{\mathrm{s}}$ ) converge to a non-constant harmonic limit $\tilde{u}: \mathbb{R}^{2} \rightarrow N$ in $H_{\text {loc }}^{2,2}\left(\mathbb{R}^{2} ; N\right)$. $\tilde{u}$ has finite energy and extends to a smooth harmonic map $\bar{u}: S^{2} \cong \overline{\mathbb{R}^{2}} \rightarrow N$.

Finally, for a suitable sequence $t_{k} \rightarrow \infty$, the sequence $\left(u\left(t_{k}, \cdot\right)\right)$ converges weakly to a smooth harmonic map $u_{\infty}: M \rightarrow N$ in $H^{1,2}(M ; N)$.

The convergence is strong away from finitely many points $x_{l}^{\infty}(l=1, \ldots, L)$ and there holds $K+L \leq \epsilon_{0}^{-1} E\left(u_{0}\right)$ where

$$
\epsilon_{0}=\inf \left\{E(\bar{u}) ; \bar{u}: S^{2} \rightarrow N \text { is a non-constant smooth harmonic map }\right\}>0
$$

is a constant depending only on $N$.
The proof of this result is based on the following inequality:
Lemma 1.4 (Ladyženskaya [74]). For any $v \in H^{1,2}\left(\mathbb{R}^{2}\right)$, $v \in L^{4}\left(\mathbb{R}^{2}\right)$ and

$$
\|v\|_{L^{4}}^{4} \leq 2\|v\|_{L^{2}}^{2}\|\nabla v\|_{L^{2}}^{2}
$$

hold.
See also Friedman [45] or Struwe [112, Lemma 3.5.7].
We now proceed with the proof of Theorem 1.7.
Positivity of $\epsilon_{0}$ : We apply Lemma 1.4 to $v=|\nabla u| \phi$, where $u$ solves (1.3) on $S^{2}$ and $\phi \in C^{\infty}\left(S^{2}\right)$ is a smooth cut-off function $0 \leq \phi \leq 1$ with support in a coordinate neighborhood on $S^{2}$ to give

$$
\begin{align*}
& \int_{S^{2}}|\nabla u|^{4} \phi^{2} d v o l_{M}  \tag{1.17}\\
& \leq C \int_{\operatorname{supp} \phi}|\nabla u|^{2} d v o l_{M}\left(\int_{S^{2}}\left|\nabla^{2} u\right|^{2} \phi^{2} d v o l_{M}+\int_{S^{2}}|\nabla u|^{2}|\nabla \phi|^{2} d v o l_{M}\right)
\end{align*}
$$

In particular, if $\left(\phi_{j}^{2}\right)$ is a smooth partition of unity subordinate to a finite cover $\left(U_{j}\right)$ of $S^{2}$ by local coordinate charts $U_{j}(j=1, \ldots, \mathcal{J})$, we obtain from (1.3), (1.17) and the Calderón-Zygmund inequality that

$$
\begin{array}{rl}
\int_{S^{2}}\left|\nabla^{2} u\right|^{2} & d v o l_{S^{2}} \leq C \int_{S^{2}}|\triangle u|^{2} d v o l_{S^{2}}+C \int_{S^{2}}|u|^{2} d \text { vol }_{S^{2}} \\
& \leq C \int_{S^{2}}|\nabla u|^{4} d v o l_{S^{2}}+C \\
& \leq C E(u)\left(\int_{S^{2}}\left|\nabla^{2} u\right|^{2} d \text { vol }_{S^{2}}+E(u)\right)+C
\end{array}
$$

with a constant $C=C(N)$. Hence the number $\epsilon_{0}$ defined in Theorem 1.7, is strictly positive. Indeed, if $E\left(u_{k}\right) \rightarrow 0$ for a sequence of harmonic maps $u_{k}: S^{2} \rightarrow N$, we obtain that $u_{k} \rightarrow$ const in $H^{2,2}\left(S^{2} ; N\right) \hookrightarrow C^{0}\left(S^{2} ; N\right)$. In particular, $u_{k}\left(S^{2}\right)$ lies in a convex geodesic ball on $N$ for large $k$. Thus $u_{k}$ must be constant, which provides a contradiction.
$L^{2}$-estimates for $\nabla^{2} u$ : By (1.17), it is important to control the energy locally. For $\Omega \subset M$, denote

$$
E(u ; \Omega)=\int_{\Omega} e(u) d v o l_{M} .
$$

Lemma 1.5. Set $R_{0}=\min \left\{1, \iota_{M}\right\}$ where $\iota_{M}$ is the convex radius of $M$. Denote $B_{R}\left(x_{0}\right)$ by the ball in a local conformal chart around $x_{0}$ with $0<2 R \leq R_{0}$. Then for any positive number $R$ with $0<2 R \leq R_{0}$, a smooth solution $u:[0, T] \times M \rightarrow N$ of (1.10) and (1.11) satisfies

$$
E\left(u(T) ; B_{R}\left(x_{0}\right)\right) \leq E\left(u_{0} ; B_{2 R}\left(x_{0}\right)\right)+\frac{C T}{R^{2}} E\left(u_{0}\right)
$$

with $C=C(M, N)$.
Proof. Let $\phi \in \mathcal{D}\left(B_{2 R}\left(x_{0}\right)\right)$ satisfy $0 \leq \phi \leq 1, \phi \equiv 1$ on $B_{R}\left(x_{0}\right),|\nabla \phi| \leq 2 / R$ and test (1.10) with $u_{t} \phi^{2}$ to obtain

$$
\begin{aligned}
& \int_{M}\left|u_{t}\right|^{2} \phi^{2} d \text { vol }_{M}+\frac{d}{d t}\left(\int_{M} e(u) \phi^{2} d v o l_{M}\right) \leq C \int_{M}|\nabla u|\left|u_{t}\right||\nabla \phi| \phi d v o l_{M} \\
& \leq \int_{M}\left|u_{t}\right|^{2} \phi^{2} d v o l_{M}+C \int_{M}|\nabla u|^{2}|\nabla \phi|^{2} d v o l_{M}
\end{aligned}
$$

Hence

$$
\frac{d}{d t}\left(\int_{M} e(u) \phi^{2} d v o l_{M}\right) \leq C R^{-2} E(u(t)) \leq C R^{-2} E\left(u_{0}\right)
$$

and the lemma follows by integration with respect to a time variable from 0 to $T$.

In particular, for any given $\epsilon_{1}>0$ and $u_{0} \in H^{1,2}(M ; N)$, there exists a number $T_{1}>0$ depending only on a maximal positive number $R_{1}$ with

$$
\sup _{x_{0} \in M} E\left(u_{0} ; B_{2 R_{1}}\left(x_{0}\right)\right)<\epsilon_{1},
$$

the geometry of $M, N$ and $E\left(u_{0}\right)$, such that any smooth solution $u$ of (1.10) and (1.11) satisfies

$$
\sup _{0 \leq t \leq T_{1}, x_{0} \in M} E\left(u(t) ; B_{R_{1}}\left(x_{0}\right)\right)<2 \epsilon_{1} .
$$

Actually, we can set $T_{1}=\left(\epsilon_{1} R_{1}^{2}\right) /\left(C E\left(u_{0}\right)\right)$ where $C$ is the constant in Lemma 1.5.
Since $M$ is compact, we can choose finite points $\left(x_{j}\right)(j=1,2, \ldots \mathcal{J})$ so that $M \subset \cup_{j=1}^{\mathcal{J}} B_{R_{j}}\left(x_{j}\right)$. Thus for any given $\epsilon_{1}>0$, let $R_{1}>0$ be determined as above and $\phi_{i}$ smooth cut-off functions subordinate to a cover of $M$ by balls $B_{2 R_{1}}\left(x_{i}\right)$ satisfying $0 \leq \phi_{i} \leq 1,\left|\nabla \phi_{i}\right| \leq 2 / R_{1}$ and $\sum_{i} \phi_{i}^{2}=1$. Then by (1.17) we have

$$
\begin{aligned}
\int_{M}|\nabla u|^{4} d v o l_{M} & =\sum_{i} \int_{M}|\nabla u|^{4} \phi_{i}^{2} d v o l_{M} \\
& \leq C \sup E\left(u(t) ; B_{2 R_{1}}\left(x_{i}\right)\right)\left(\int_{M}\left|\nabla^{2} u(t)\right|^{2} d v o l_{M}+R_{1}^{-2} E\left(u_{0}\right)\right) \\
& \leq C \epsilon_{1}\left(\int_{M}\left|\nabla^{2} u(t)\right|^{2} d \operatorname{dvo}_{M}+R_{1}^{-2} E\left(u_{0}\right)\right)
\end{aligned}
$$

for any $t$. Moreover, similar to our Bochner-type estimate (1.13), multiplying (1.10) by $\triangle_{M} u$ and integrating by parts, we have

$$
\frac{d}{d t}(E(u(t)))+\int_{M}\left|\triangle_{M} u\right|^{2} d \text { vol }_{M} \leq C \int_{M}|\nabla u|^{4} d v o l_{M} .
$$

By integrating over $\left(0, T_{1}\right)$ and combining the above estimates with the CalderónZygmund inequality, we obtain that

$$
\begin{aligned}
& \int_{0}^{T_{1}} \int_{M}\left|\nabla^{2} u\right|^{2} d t d \text { vol }_{M} \leq C \int_{0}^{T_{1}} \int_{M}\left|\triangle_{M} u\right|^{2} d t d \text { vol }_{M}+C T_{1} \\
\leq & C \epsilon_{1} \int_{0}^{T_{1}} \int_{M}\left|\nabla^{2} u\right|^{2} d t d v o l_{M}+\frac{C T_{1}}{R_{1}^{2}} E\left(u_{0}\right)+C T_{1},
\end{aligned}
$$

with a constant $C=C(M, N)$. Thus, for sufficiently small $\epsilon_{1}>0$, we obtain an a-priori bound for $u$ in the norm

$$
\|u\|_{W((0, T) \times M)}^{2}=\sup _{0<t<T} E(u(t))+\int_{0}^{T} \int_{M}\left(\left|\nabla^{2} u\right|^{2}+\left|u_{t}\right|^{2}\right) d t d v o l_{M}
$$

with $T=T_{1}$ of the form

$$
\|u\|_{W\left(\left(0, T_{1}\right) \times M\right)}^{2} \leq C\left(1+\frac{T_{1}}{R_{1}^{2}}\right) E\left(u_{0}\right)+C T_{1} .
$$

Here we use the fact that $W((0, T) \times M)$ is an admissible class for (1.10) in the sense that if $u \in W((0, T) \times M)$ solves (1.10) with finite energy initial data $u_{0} \in$ $H^{1,2}(M ; N)$, then $u \in C^{\infty}((0, T] \times M ; N)$.

Local existence: A maximal positive number $R_{1}$ can be chosen uniformly for a set of initial data which is compact in $\left\{u_{0}\right\}+\stackrel{\circ}{H}^{1,2}(M ; N)$. In particular, if $u_{0 m} \in C^{\infty}(M ; N)$ converges to $u_{0}$ in $H^{1,2}(M ; N)$ and if $\left\{u_{m}\right\}(m=1,2, \ldots)$ is the corresponding sequence of local solutions (1.10) for initial $\left\{u_{0 m}\right\}(m=1,2, \ldots)$ by the above a-priori estimate, we have $\left\|u_{m}\right\|_{W\left(\left(0, T_{1}\right) \times M\right)}^{2} \leq C\left(1+T_{1} / R_{1}^{2}\right) E\left(u_{0}\right)+$ $C T_{1}$ where $T_{1}=\left(\epsilon_{1} R_{1}^{2}\right) /\left(C E\left(u_{0}\right)\right)$ and the sequence $\left\{u_{m}\right\} \quad(m=1,2, \ldots)$, weakly converges weakly to $u \in W\left(\left(0, T_{1}\right) \times M\right)$.
$\nabla u_{m} \rightarrow \nabla u$ in $L^{2}(M)$ for almost every $t$ and then it is easy to pass to the limit in equation (1.10); $u$ then solves (1.10) classically in $\left(0, T_{1}\right) \times M$. Finally, by Lemma 1.1, $u$ achieves its initial data continuously in $H^{1,2}(M ; N)$.

Uniqueness: The space of functions with bounded $W((0, T) \times M)$-norm is a uniqueness class. Indeed, if $u$ and $v \in W((0, T) \times M)$ weakly solve (1.10) with $u(0)=u_{0}=v(0)$, their difference $w=u-v$ satisfies

$$
\left|w_{t}-\triangle_{M} w\right| \leq C|w|\left(|\nabla u|^{2}+|\nabla v|^{2}\right)+C|\nabla w|(|\nabla u|+|\nabla v|) .
$$

Multiply the above inequality by $w$ and perform the integrate by parts to verify for almost every $t \geq 0$

$$
\begin{aligned}
& \frac{1}{2} \int_{M}|w(t)|^{2} d v o l_{M}+\int_{0}^{t} \int_{M}|\nabla w|^{2} d s d v o l_{M} \\
& \quad \leq C \int_{0}^{t} \int_{M}|w|^{2}\left(|\nabla u|^{2}+|\nabla v|^{2}\right) d s d v o l_{M}
\end{aligned}
$$

$$
\begin{aligned}
&+C \int_{0}^{t} \int_{M}|w||\nabla w|(|\nabla u|+|\nabla v|) d s d v o l_{M} \\
& \leq C\left(\int_{0}^{t} \int_{M}|w|^{4} d s d v o l_{M}\right)^{1 / 2}\left(\int_{0}^{t} \int_{M}\left(|\nabla u|^{4}+|\nabla v|^{4}\right) d s d v o l_{M}\right)^{1 / 2} \\
&+C\left(\int_{0}^{t} \int_{M}|w|^{4} d s d v o l_{M}\right)^{1 / 4}\left(\int_{0}^{t} \int_{M}|\nabla w|^{2} d s d v o l_{M}\right)^{1 / 2} \\
& \times\left(\int_{0}^{t} \int_{M}\left(|\nabla u|^{4}+|\nabla v|^{4}\right) d s d v o l_{M}\right)^{1 / 4} \\
& \leq C \epsilon(t)\left[\sup _{0 \leq s \leq T_{1}} \int_{M}|w(s)|^{2} d s+\int_{0}^{t} \int_{M}|\nabla w|^{2} d s\right]
\end{aligned}
$$

where

$$
\begin{aligned}
\epsilon(t) & =\left(\int_{0}^{t} \int_{M}\left(|\nabla u|^{4}+|\nabla v|^{4}\right) d s d v o l_{M}\right)^{1 / 4} \\
& \left.\times\left(1+\left(\int_{0}^{t} \int_{M}\left(|\nabla u|^{4}+|\nabla v|^{4}\right)\right) d s d v o l_{M}\right)^{1 / 4}\right)
\end{aligned}
$$

Here we applied Lemma 1.4 to the term of $\int_{0}^{t} \int_{M}|w|^{4} d s d v o l_{M}$ in the estimates above. As in the same way as before, on account of Lemma 1.5 we estimate

$$
\epsilon(t) \rightarrow 0 \quad \text { as } \quad t \rightarrow+0
$$

Choosing $t>0$ small enough with $\|w(t)\|_{L^{2}(M)}=\sup _{0 \leq s \leq T_{1}}\|w(s)\|_{L^{2}(M)}$, the uniqueness follows.

Global continuation: The local solution $u$ constructed above can be extended until the first time $T=t_{\mathrm{s}, 1}$ such that

$$
\limsup _{t / T}\left(\sup _{x_{0}} E\left(u(t) ; B_{R}\left(x_{0}\right)\right)\right) \geq \epsilon_{1}
$$

for all $R>0$. By Lemma 1.1, $u_{t} \in L^{2}([0, T] \times M)$. Hence the $L^{2}$-limit $u_{1}=\lim _{t / T} u(t)$ exists. Let $v$ be the local solution of $(1.10)$ with initial data $v=u_{1}$ at time $T$. The composed function

$$
w(t)= \begin{cases}u(t) & 0 \leq t \leq T \\ v(t) & T \leq t\end{cases}
$$

then is a weak solution of (1.10). By iteration we obtain a weak solution $u$ on a maximal time interval $[0, \bar{T})$. If $\bar{T}<\infty$, the above arguments again permit us to extend $u$ beyond $\bar{T}$, contradicting our assumption that $\bar{T}$ was maximal. Hence $\bar{T}=\infty$.
Finiteness of the singular set: Let $t_{\mathrm{s}}=t_{\mathrm{s}, 1}>0$ be the first singular time and set

$$
\operatorname{Sing}\left(t_{\mathrm{s}}\right)=\left\{x_{0} \in M ; \limsup _{t / t_{\mathrm{s}}} E\left(u(t) ; B_{R}\left(x_{0}\right)\right)>\epsilon_{1} \text { for any } R>0\right\}
$$

$\operatorname{Sing}\left(t_{\mathrm{s}}\right)$ is finite. Indeed, let $x_{1}, \ldots, x_{J} \in \operatorname{Sing}\left(t_{\mathrm{s}}\right)$. Choose $R>0$ such that $B_{2 R}\left(x_{i}\right) \cap B_{2 R}\left(x_{j}\right)=\emptyset(i \neq j)$. Then by Lemma 1.5 for some $\tau \in\left[t_{\mathrm{s}}-\left(\epsilon_{1} R^{2}\right) /\left(2 C E\left(u_{0}\right)\right), t_{\mathrm{s}}\right)$ where C is the constant in Lemma 1.5,we obtain

$$
\begin{aligned}
K \epsilon_{1} & \leq \sum_{i=1}^{K} \limsup _{t / t_{\mathrm{s}}} E\left(u(t) ; B_{R}\left(x_{i}\right)\right) \\
& \leq \sum_{i=1}^{K}\left(E\left(u(\tau) ; B_{2 R}\left(x_{i}\right)\right)+\frac{\epsilon_{1}}{2}\right) \leq E\left(u_{0}\right)+\frac{K \epsilon_{1}}{2}
\end{aligned}
$$

and $K=\# \operatorname{Sing}\left(t_{\mathrm{s}, 1}\right) \leq 2 E\left(u_{0}\right) \epsilon_{1}^{-1}$. Set $K$ be $K_{1}$. Moreover, for $u_{1}=\lim _{t / t_{\mathrm{s}, 1}} u(t)$ we have

$$
\begin{aligned}
E\left(u_{1}\right) & =\lim _{R \backslash 0} E\left(u_{1} ; M \backslash \bigcup_{i=1}^{K_{1}} B_{2 R}\left(x_{i}\right)\right) \\
& \leq \lim _{R \backslash 0} \liminf _{t / t_{\mathrm{s}, 1}} E\left(u(t) ; M \backslash \bigcup_{i=1}^{K_{1}} B_{2 R}\left(x_{i}\right)\right) \\
& \leq \lim _{R \backslash 0} \liminf _{t / t_{\mathrm{s}, 1}}\left(E(u(t))-\sum_{i=1}^{K_{1}} E\left(u(t) ; B_{2 R}\left(x_{i}\right)\right)\right) \\
& \leq \lim _{R \backslash 0}\left(E\left(u_{0}\right)-\limsup _{t / t_{\mathrm{s}, 1}} \sum_{i=1}^{K_{1}} E\left(u(t) ; B_{2 R}\left(x_{i}\right)\right)\right) \\
& \leq E\left(u_{0}\right)-\sum_{i=1}^{K_{1}} \lim _{R \backslash 0} \limsup _{t / t_{\mathrm{s}, 1}} E\left(u(t) ; B_{R}\left(x_{i}\right)\right) \\
& \leq E\left(u_{0}\right)-K_{1} \epsilon_{1} .
\end{aligned}
$$

Similarly, let $K_{2}, K_{3}, \ldots$ be the number of concentration points at consecutive times $t_{\mathrm{s}, 2}<t_{\mathrm{s}, 3}<\ldots$ and let $u_{j}=\lim _{t / t_{\mathrm{s}, j}} u(t)$ for $j=2,3, \ldots$. Then by induction we obtain

$$
E\left(u_{j}\right) \leq E\left(u_{j-1}\right)-K_{j} \epsilon_{1} \leq \cdots \leq E\left(u_{0}\right)-\left(K_{1}+\cdots+K_{j}\right) \epsilon_{1} .
$$

Thus it follows that the total number $K_{\Sigma}$ of concentration points and at same time the number of concentration times $t_{j}$ are finite; $K_{\Sigma} \leq E\left(u_{0}\right) \epsilon_{1}^{-1}$.

Smoothness: Let $t_{\mathrm{s}}=t_{\mathrm{s}, j}$ for some $j$. To see that $u$ is smooth up to time $t_{\mathrm{s}}$ away from $\operatorname{Sing}\left(t_{\mathrm{s}}\right)$, we present an argument based on scaling, as proposed by Schoen [96] in the stationary case. For a simplicity, we discuss the smoothness in $M=\mathbb{R}^{2}$. In addition, by scaling we can assume $t_{\mathrm{s}} \geq 1$ and we shift time so that $t_{\mathrm{s}}=0$. The solution $u$ then is defined on a domain containing $[-1,0] \times M$. For any $R>0$ and $z_{0}=\left(t_{0}, x_{0}\right)$, denote

$$
Q_{R}\left(z_{0}\right)=\left\{z=(t, x) ; t_{0}-R^{2}<t<t_{0},\left|x-x_{0}\right|<R\right\},
$$

and shorten $Q_{R}(0)$ to $Q_{R}$ and $Q_{1}$ to $Q$ when no confusion may arise.

Proposition 1.3. Suppose that $u \in C^{\infty}(Q ; N)$ solves (1.10). There exist constants $C$ and $\epsilon_{2}>0$ depending only on $N$ such that if

$$
\sup _{-1 \leq t \leq 0} E\left(u(t) ; B_{1}(0)\right)<\epsilon_{2},
$$

then

$$
\sup _{Q_{1 / 2}(0)}|\nabla u(t, x)| \leq C
$$

(and corresponding bounds for higher derivatives), holds.
Proof. Choose $0 \leq \rho<1$ so that

$$
(1-\rho)^{2} \sup _{Q_{\rho}(0)} e(u)=\max _{0 \leq \sigma \leq 1}\left\{(1-\sigma)^{2} \sup _{Q_{\sigma}(0)} e(u)\right\}
$$

and let $z_{\max }=\left(t_{\max }, x_{\max }\right) \in Q_{\rho(0)}$ satisfy

$$
e(u)\left(z_{\max }\right)=\sup _{Q_{\rho}(0)} e(u)=: e_{0}
$$

Then either $e_{0}(1-\rho)^{2}<4$ in which case

$$
\sup _{Q_{1 / 2}(0)} e(u) \leq 4(1-\rho)^{2} e_{0}<16,
$$

or $e_{0}^{-\frac{1}{2}} \leq(1-\rho) / 2$. In the latter case, the scaled function

$$
v(\bar{t}, \bar{x})=u\left(t_{\max }+e_{0}^{-1} \bar{t}, x_{\max }+e_{0}^{-1 / 2} \bar{x}\right)
$$

is well defined on $Q_{1}(0)$. Moreover, $e(v)(0)=1$ and

$$
\sup _{Q_{1}(0)} e(v) \leq e_{0}^{-1} \sup _{Q_{(1+\rho) / 2}(0)} e(u) \leq e_{0}^{-1} \frac{(1-\rho)^{2} \sup _{Q_{\rho}(0)} e(u)}{((1-\rho) / 2)^{2}}=4
$$

Thus $e(v)$ satisfies a linear differential inequality

$$
e(v)_{\bar{t}}-\triangle e(v) \leq C e(v) \quad \text { on } \quad Q_{1}(0)
$$

By Lemma 1.3, we have

$$
\begin{aligned}
1=e(v)(0,0)= & \leq \sup _{Q_{1 / 2}(0)} e(v) \leq C_{\mathrm{H}} \int_{Q_{1}(0)} e(v) d \bar{t} d \bar{x} \leq e_{0}^{2} \int_{Q_{1}(0)} e(u) d t d x \\
& \leq C \sup _{-1<t<0}\left(E\left(u(t) ; B_{1}(0)\right)\right) \leq C \epsilon_{2} .
\end{aligned}
$$

This is a contradiction if we take $C_{\mathrm{H}} \epsilon_{2}<1 / 2$. Thus we conclude our claim.
Blow-up of singularities: As in the same way in Struwe [107], we use the scaling technique to analyze the singularities in more detail. Let $\left(t_{\mathrm{s}}, x_{\mathrm{s}}\right)$ be a singular point of the solution $u$ constructed above. Shift time so that $\left(t_{\mathrm{s}}, x_{\mathrm{s}}\right)=(0,0)$. Moreover after scaling we can assume that $u \in C^{\infty}\left(Q_{1}(0) \backslash\{0\} ; N\right)$. Let $\left\{R_{k}\right\}(k=1,2, \ldots)$ be
a sequence of numbers $R_{k} \in(0,1), R_{k} \searrow 0(k \rightarrow \infty)$. Set $\epsilon_{1}>0$ be as above and take sequences $\left\{t_{k}\right\}$ and $\left\{x_{k}\right\}(k=1,2, \ldots)$ satisfying $t_{k} \searrow 0$ and $x_{k} \rightarrow 0$ and

$$
E\left(u\left(t_{k}\right) ; B_{R_{k}}\left(x_{k}\right)\right)=\sup _{-1 \leq t \leq t_{k} ;(t, x) \in Q_{1}(0)} E\left(u(t) ; B_{R_{k}}(x)\right)=\frac{\epsilon_{1}}{L}
$$

where $L$ is the number of unit discs needed to cover $B_{2}(0)$. We may assume $t_{k}-4 R_{k}^{2} \geq-1$. Rescale

$$
\bar{t}=\frac{t-t_{k}}{R_{k}^{2}}, \bar{x}=\frac{x-x_{k}}{R_{k}},
$$

and set

$$
v_{k}(\bar{t}, \bar{x})=u\left(t_{k}+R_{k}^{2} \bar{t}, x_{k}+R_{k} \bar{x}\right),
$$

$v_{k}: Q_{k}=\left\{(\bar{t}, \bar{x}) \in(-4,0] \times \mathbb{R}^{2} ;\left(t_{k}+R_{k}^{2} \bar{t}, x_{k}+R_{k} \bar{x}\right) \in Q_{1}(0)\right\} \rightarrow N$. Note that by Lemma 1.1 we have

$$
\begin{gathered}
\int_{Q_{k}}\left|\left(v_{k}\right)_{\bar{t}}\right|^{2} d \bar{t} d v o l_{M} \leq \int_{t_{k}-4 R_{k}^{2}}^{t_{k}} \int_{M}\left|u_{t}\right|^{2} d t \text { dvol }_{M} \rightarrow 0 \quad(k \rightarrow \infty), \\
E\left(v_{k}(t)\right) \leq E\left(u_{0}\right), \quad-4 \leq \bar{t} \leq 0, \quad k \in N .
\end{gathered}
$$

Moreover, we obtain

$$
\begin{aligned}
\sup _{(\bar{t}, \bar{x}) \in Q_{k}} E\left(v_{k}(\bar{t}) ; B_{2}(\bar{x})\right) \leq & L \sup _{(\bar{t}, \bar{x}) \in Q_{k}} E\left(v_{k}(\bar{t}) ; B_{1}(\bar{x})\right) \\
& \leq L \sup _{(t, x) \in D_{k}} E\left(u(t) ; B_{R_{k}}(x)\right) \leq L E\left(u\left(t_{k}\right) ; B_{R_{k}}\left(x_{k}\right)\right)=\epsilon_{1} .
\end{aligned}
$$

Thus, by Proposition 1.3, the sequence $\left\{v_{k}\right\}(k=1,2, \ldots)$ is locally a priori bounded in $C^{l}$ for any $l \in \mathbb{N}$ and a sub-sequence converges strongly in $H_{\mathrm{loc}}^{1,2}\left((-1,0) \times \mathbb{R}^{2} ; N\right)$ to a smooth solution $v$ of (1.10) on $[-1,0] \times \mathbb{R}^{2}$. Moreover, from $v_{\bar{t}}=0$, it follows that $v(\bar{t}, \cdot)=: \tilde{u}$ is harmonic. Finally

$$
E\left(\tilde{u} ; B_{1}(0)\right)=\lim _{k \rightarrow \infty} E\left(v_{k}(0) ; B_{1}(0)\right)=\lim _{k \rightarrow \infty} E\left(u\left(t_{k}\right) ; B_{R_{k}}(x)\right)=\frac{\epsilon_{1}}{L},
$$

and then $\tilde{u}$ is non-constant. If $\tilde{u}: \mathbb{R}^{2} \rightarrow N$, by conformal equivalence $\mathbb{R}^{2} \cong S^{2} \backslash\{p\}$, $\tilde{u}$ induces a weakly harmonic map $\bar{u}: S^{2} \rightarrow N$. By Hélein's result, $\bar{u}$ is smooth. Thus, singularities at small scales can be seen as harmonic spheres. In particular we obtain the estimate $\epsilon_{1} \geq \epsilon_{0}$.

A similar analysis is possible at concentration points at " $t_{\mathrm{s}}=\infty$;"
see Struwe [112, Lecture III.5] for details. Moreover, it seems possible to iterate the above procedure and decompose $u$ in the limit $t / t_{\mathrm{s}}$ into its weak limit $u\left(t_{\mathrm{s}}\right)$ and a finite sum of harmonic spheres $\bar{u}_{1}, \ldots, \bar{u}_{M}$ for some positive integer $M$, similar to Struwe [106] to a related problem, we arrive at

$$
\begin{equation*}
E\left(u\left(t_{\mathrm{s}}\right)\right)+\sum_{l=1}^{M} E\left(\bar{u}_{l}\right)=\lim _{t / t_{\mathrm{s}}} E(u(t)) \tag{1.18}
\end{equation*}
$$

This analysis has been done by Ding-Tian [30]. See also Qing-Tian [91] and Wang $[\mathbf{1 1 7}]$. They call (1.18) "the energy identity."

## Extensions and generalizations

Theorem 1.7 has been extended to target manifolds $N$ with boundary by ChenMusina [23]. The same technique can be used to study the evolution problems related to other two-dimensional variational problems. For instance, in Struwe [108] and Rey [92], the evolution problem for surfaces of prescribed mean curvature is investigated; Li Ma [77] has studied the evolution of harmonic maps with free boundaries.

## 5. Existence of global, partially regular weak solutions in higher dimensional manifold

Earlier we observed that singularities must do emerge even for energy-minimizing weakly harmonic maps if $d=\operatorname{dim} M \geq 3$ and therefore for the evolution problem (1.10). The following result was obtained by Chen-Struwe [24].

Theorem 1.8. Suppose that $M$ is a d-dimensional compact manifold with $d \geq 3$ and $\partial M=\emptyset$. For any $u_{0} \in H^{1,2}(M ; N)$, there exists a distribution solution $u:[0, \infty) \times M \rightarrow N$ of (1.10) and (1.11) satisfying the energy inequality and being smooth away from a closed set $\Sigma$ such that for each $t$ the slice $\Sigma(t):=\Sigma \cap(\{t\} \times M)$ is of co-dimension more than or equal to 2 . As $t \rightarrow \infty$ suitably, $u(t)$ converges weakly to a weakly harmonic limit $u_{\infty}$ which is smooth away from a closed set $\Sigma(\infty)$ of co-dimension more than or equal to 2 .

Originally, the estimate on the co-dimension of $\Sigma$ was obtained in spacetime, the above improvement is due to X . Cheng [25]. For manifolds $M$ with boundary $\partial M \neq \emptyset$, a similar existence and an interior partial regularity result hold; see Chen [20]. Boundary regularity is open. The proof of Theorem 1.8 rests on two pillars: A penalty approximation scheme for (1.10) is developed independently by Chen [19], Keller-Rubinstein-Sternberg [73] and Shatah [100]; while a monotonicity estimate for (1.10) is due to Struwe [109].

## Penalty approximation

We discuss the case $N=S^{D-1} \subset \mathbb{R}^{D}$. Given $u_{0} \in H^{1,2}\left(M ; S^{D-1}\right)$ and $\lambda \in \mathbb{R}_{+}$; consider the Cauchy problem

$$
\begin{align*}
u_{t}-\triangle_{M} u+\lambda\left(|u|^{2}-1\right) u & =0,  \tag{1.19}\\
\left.u\right|_{t=0} & =u_{0} \tag{1.20}
\end{align*}
$$

for maps $u:[0, \infty) \times M \rightarrow \mathbb{R}^{D}$. This scheme enables us to "forget" the target constraint. We can regard all map $u: M \rightarrow \mathbb{R}^{D}$ as admissible. However, we "penalize"
violation of the constraint $|u|^{2}=1$ more and more severely as $\lambda \rightarrow \infty$. (1.19) is the $L^{2}$-gradient flow for the functional

$$
E_{\lambda}(u)=E(u)+\lambda \int_{M} \frac{\left(|u|^{2}-1\right)^{2}}{4} d v o l_{M} .
$$

Indeed, we have
Lemma 1.6. If $u_{\lambda} \in C^{\infty}\left([0, T) \times M ; \mathbb{R}^{D}\right)$ solves (1.19) and (1.20), then we have the following identity:

$$
\int_{0}^{T} \int_{M}\left|\partial_{t} u_{\lambda}\right|^{2} d t d v o l_{M}+E_{\lambda}\left(u_{\lambda}(T)\right)=E_{\lambda}\left(u_{0}\right)=E\left(u_{0}\right)
$$

holds; in particular, $u$ attains its initial data continuously in $H^{1,2}\left(M ; \mathbb{R}^{D}\right)$
Proof. Multiply (1.19) by $\partial_{t} u_{\lambda}$ and integrate to obtain the energy estimate. Since $\partial_{t} u_{\lambda} \in L^{2}([0, T) \times M)$, clearly $u_{\lambda}(t) \rightarrow u_{0}$ in $L^{2}(M)$ and weakly in $H^{1,2}(M, N)$ as $t \rightarrow+0$. Since also

$$
\limsup _{t \rightarrow+0} E\left(u_{\lambda}(t)\right) \leq \limsup _{t \rightarrow+0} E_{\lambda}\left(u_{\lambda}(t)\right) \leq E\left(u_{0}\right),
$$

we also have strong $H^{1,2}$-convergence.
Moreover, we have an $L^{\infty}$ a-priori bound.
Lemma 1.7. If $u_{\lambda} \in C^{\infty}\left([0, T) \times M ; \mathbb{R}^{D}\right)$ solves (1.19) and (1.20), then

$$
\left\|u_{\lambda}\right\|_{L^{\infty}} \leq 1 .
$$

Proof. Multiply (1.19) by $u_{\lambda}$ to obtain

$$
\left(\frac{d}{d t}-\triangle\right) \frac{\left|u_{\lambda}\right|^{2}}{2}+\left|\nabla u_{\lambda}\right|^{2}+\lambda\left(\left|u_{\lambda}\right|^{2}-1\right)\left|u_{\lambda}\right|^{2}=0 ;
$$

in particular,

$$
\left(\frac{d}{d t}-\triangle+2 \lambda\left|u_{\lambda}\right|^{2}\right)\left(\left|u_{\lambda}\right|^{2}-1\right) \leq 0
$$

The claim now follows from the parabolic maximum principle, since $|u(0)|=\left|u_{0}\right| \leq$ 1.

Thus for any $\lambda \in \mathbb{R}_{+}$we have the unique, global, smooth solution $u_{\lambda}$ of (1.19) and (1.20). Moreover,

$$
\begin{gathered}
\left\|\partial_{t} u_{\lambda}\right\|_{L^{2}([0, \infty) \times M)}^{2} \leq E\left(u_{0}\right), \quad \sup _{t} E\left(u_{\lambda}(t)\right) \leq E\left(u_{0}\right), \\
\left|u_{\lambda}\right| \leq 1, \quad \sup _{t}\left\|\left|u_{\lambda}(t)\right|^{2}-1\right\|_{L^{2}(M)}^{2} \leq \frac{4 E\left(u_{0}\right)}{\lambda} \rightarrow 0 .
\end{gathered}
$$

Thus, passing to a sub-sequence, if necessary, we can claim that for a map $u \in$ $L^{2}\left((0, \infty) ; H^{1,2}(M)\right) \cap H^{1,2}\left((0, \infty) ; L^{2}(M)\right)$

$$
\begin{gather*}
u_{\lambda} \rightarrow u \quad \text { in } L_{\mathrm{loc}}^{2}\left([0, \infty) \times M ; \mathbb{R}^{D}\right), \\
\nabla u_{\lambda} \rightarrow \nabla u \quad \text { weakly-* in } L^{\infty}\left([0, \infty) ; L^{2}(M)\right),  \tag{1.21}\\
\partial_{t} u_{\lambda} \rightarrow \partial_{t} u \quad \text { weakly in } L^{2}([0, \infty) \times M)
\end{gather*}
$$

and $|u|=1$. Relations (1.21) are not sufficient to pass to the limit $\lambda \rightarrow \infty$ in (1.19). In case $N=S^{D-1}$, however, a clever manipulation of (1.19) will do the trick.

Lemma 1.8. Suppose $N=S^{D-1} \subset \mathbb{R}^{D}$. A map $u \in V((0, \infty) \times M ; N)$ satisfies

$$
\begin{equation*}
|u|=1 \quad \text { a.e } \quad z \in(0, \infty) \times M, \tag{1.22}
\end{equation*}
$$

$$
\begin{equation*}
u_{t} \wedge u-\operatorname{div}(\nabla u \wedge u)=0, \quad \text { in the sense of } \quad \mathcal{D}^{\prime}\left((0, \infty) \times M ; \mathbb{R}^{D}\right), \tag{1.23}
\end{equation*}
$$

where " $\wedge$ " denotes the wedge product between $\mathbb{R}^{D}$-vectors, if and only if the map $u \in V((0, \infty) \times M ; N)$ is a weakly evolutional harmonic map.

Proof. If $u$ is a weakly evolutional harmonic map, an approximation argument justifies taking an exterior product between (1.10) and $\psi$, where $\psi \in \mathcal{D}((0, \infty) \times$ $M ; \wedge^{2}\left(\mathbb{R}^{D}\right)$ ), then we obtain (1.23). Conversely, suppose taht $u$ weakly solves (1.22) and (1.23); (1.23) is written by

$$
\begin{equation*}
\left(u_{t}^{i} u^{j}-u_{t}^{j} u^{i}\right)-\operatorname{div}\left(\nabla u^{i} u^{j}-\nabla u^{j} u^{i}\right)=0, \quad(i, j=1,2, \ldots, D) . \tag{1.24}
\end{equation*}
$$

Multiply (1.24) by $u^{j} \eta^{i}$ where $\eta=\left(\eta^{i}\right)(i=1,2, \ldots, D) \in \mathcal{D}\left((0, \infty) \times M ; \mathbb{R}^{D}\right)$, summing up it from 1 to $D$ with respect to $j$ we deduce that $u$ is a weakly evolutional harmonic map.

Now, taking the wedge product of (1.19) with $u_{\lambda}$, the nonlinear term of (1.19) vanishes. Because of the divergence structure of this equation and since by (1.21), we have

$$
\begin{gathered}
\partial_{t} u_{\lambda} \wedge u_{\lambda} \rightarrow \partial_{t} u \wedge u, \\
\nabla u_{\lambda} \wedge u_{\lambda} \rightarrow \nabla u \wedge u
\end{gathered}
$$

weakly in $L_{\text {loc }}^{2}([0, \infty) \times M)$, we may pass to the limit $\lambda \rightarrow \infty$ suitably and find that also $u$ satisfies (1.23). That is, by Lemma 1.6 and Lemma 1.8, $u$ is a weak solution of (1.10) and (1.11).

Note that this method extended to a homogeneous space by Hélein [64] and the regularity of the approximating maps $u_{\lambda}$ may be lost in the limit.

## The monotonicity formula

Monotonicity first were introduced as a tool in the regularity study for minimal hypersurfaces. After that, Schoen-Uhlenbeck [97] and Giaquinta-Giusti [48] observed that similar estimates hold for the energy-minimizing harmonic maps and can be used to obtain a partial regularity result for such a minimizer. We review the monotonicity for energy-minimizing harmonic maps $u: B=B_{1}(0) \rightarrow N$.

Theorem 1.9. If $u$ is energy-minimizing (for its boundary values), then for any $0<\rho<r<1$ with $B_{\rho} \subset B_{r} \subset \subset B_{1}(0)$, there holds

$$
\rho^{2-d} \int_{B_{\rho}}|\nabla u|^{2} d x \leq r^{2-d} \int_{B_{r}}|\nabla u|^{2} d x .
$$

Proof. Note that the quantity

$$
\Phi(\rho):=\Phi(\rho ; u)=\frac{\rho^{2-d}}{2} \int_{B_{\rho}}|\nabla u|^{2} d x
$$

is invariant under scaling $u(x) \rightarrow u_{R}(\bar{x})=u(R \bar{x})$, which (in case $\left.M=B_{1}(0)\right)$ also leaves (1.3) invariant. This observation allows us to give a simple proof of Theorem 1.9 for smooth harmonic maps as follows: Note that $\Phi(\rho)=\Phi(\rho ; u)=\Phi\left(1 ; u_{\rho}\right)$. Hence, for instance at $\rho=1$, we have

$$
\begin{aligned}
\frac{d \Phi(\rho)}{d \rho} & =\frac{d \Phi}{d \rho}\left(1 ; u_{\rho}\right)=\int_{B_{1}(0)}\left\langle\nabla u_{\rho}, \nabla\left(\frac{\partial u_{\rho}}{\partial \rho}\right)\right\rangle d x \\
& =\int_{\partial B_{1}(0)}\left\langle\langle x, \nabla\rangle u_{\rho}, \frac{\partial u_{\rho}}{\partial \rho}\right\rangle d \omega_{d-1}-\int_{B_{1}(0)}\left\langle\triangle u_{\rho}, \frac{\partial u_{\rho}}{\partial \rho}\right\rangle d x .
\end{aligned}
$$

Since $\partial u_{\rho} / \partial \rho=\langle x / \rho, \nabla\rangle u_{\rho} \in T_{u_{\rho}} N$, by (1.2), the last term vanishes and the boundary integral simply becomes

$$
\left.\frac{d \Phi(\rho)}{d \rho}\right|_{\rho=1}=\int_{\partial B_{1}(0)}\left|\langle x, \nabla\rangle u_{\rho}\right|^{2} d \omega_{d-1} \geq 0
$$

proving the monotonicity for smooth $u$.
Moreover, since $\Phi(\rho)$ scales as a dimension-less quantity, smallness of $\Phi(\rho)$ for some $\rho>0$ yields a-priori bounds for $u$ near the origin.

A similar result holds in the time-dependent setting. For simplicity we consider smooth solutions $u \in C^{\infty}\left([-1,0) \times \mathbb{R}^{d} ; N\right)$ of (1.10) with $E(u(t)) \leq E_{0}<\infty$ in $-1 \leq t<0$. Denote by

$$
G(t, x)=\frac{1}{(\sqrt{4 \pi|t|})^{d}} \exp \left(-\frac{|x|^{2}}{4|t|}\right), \quad t<0
$$

the fundamental solution to the backward heat equation on $\mathbb{R}_{-} \times \mathbb{R}^{d}$. Using $G$ as a weight function, we define

$$
\Phi(\rho)=\Phi(\rho ; u)=\frac{\rho^{2}}{2} \int_{\left\{-\rho^{2}\right\} \times \mathbb{R}^{d}}|\nabla u|^{2} G d x
$$

We then obtain:
Theorem 1.10 (Struwe [109]). For $u$ as above and any $0<\rho<r \leq 1$, the following holds

$$
\begin{equation*}
\Phi(\rho) \leq \Phi(r) \tag{1.25}
\end{equation*}
$$

Proof. As in the stationary case, we use invariance of (1.10) under scaling $u \rightarrow u_{R}(t, x)=u\left(R^{2} t, R x\right)$. Note that $\Phi(\rho)=\Phi(\rho ; u)=\Phi\left(1 ; u_{\rho}\right)$. Hence, at $\rho=1$, we compute

$$
\frac{d \Phi(\rho)}{d \rho}=\frac{d \Phi}{d \rho}\left(1 ; u_{\rho}\right)=\int_{\{-1\} \times \mathbb{R}^{d}}\left\langle\nabla u_{\rho}, \nabla\left(\frac{\partial u_{\rho}}{\partial \rho}\right)\right\rangle G d \bar{x} .
$$

Integrate by parts; use (1.10) and the relation $\nabla G(\bar{t}, \bar{x})=\bar{x} / 2 \bar{t} G$ to obtain

$$
\begin{aligned}
\frac{d \Phi(\rho)}{d \rho} & =\int_{\{-1\} \times \mathbb{R}^{d}}\left\langle\left(-\Delta u_{\rho}-\frac{\langle\bar{x}, \nabla\rangle u_{\rho}}{2 \bar{t}}\right), \frac{\partial u_{\rho}}{\partial \rho}\right\rangle G d \bar{x} \\
& =-\int_{\{-1\} \times \mathbb{R}^{d}}\left\langle\frac{2 \bar{t} \partial_{\bar{t}} u_{\rho}+\langle\bar{x}, \nabla\rangle u_{\rho}}{2 \bar{t}}, \frac{\partial u_{\rho}}{\partial \rho}\right\rangle G d \bar{x} \\
& =\frac{1}{2} \int_{\{-1\} \times \mathbb{R}^{d}}\left|2 \bar{t} \partial_{\bar{t}} u_{\rho}+\langle\bar{x}, \nabla\rangle u_{\rho}\right|^{2} G d \bar{x} \geq 0 .
\end{aligned}
$$

Since $E(u(t)) \leq E_{0}<\infty$, no boundary terms appear.
Remark 1.1. (1.25) is the energy inequality for (1.10) in similarity coordinates $s=-\log |t|$ and $y=x / \sqrt{|t|}$, as introduced by Giga-Kohn [49] in a different problem.

By a scaling argument as in the proof of Proposition 1.3, smallness of $\Phi(\rho)$ can be turned into an a-priori gradient bound for $u$.

Proposition 1.4 (Struwe [109]). Let us suppose that a solution $u$ of (1.10) belongs to $C^{\infty}\left([-1,0) \times \mathbb{R}^{d} ; N\right)$. There exists $\epsilon_{0}=\epsilon_{0}(d, N)>0$ such that for some positive number $R>0$ if $\Phi(R)<\epsilon_{0}$ then

$$
\sup _{Q_{\delta R}(0)}|\nabla u| \leq \frac{C}{R}
$$

holds with constants $\delta=\delta\left(d, N, E_{0}\right)>0$ and $C=C\left(d, N, E_{0}\right)$.
Proof. Scaling with $R$, we may assume $R=1$. For any $\delta>0$, choose $\rho \in(0, \delta)$ and $z_{\text {max }}=\left(t_{\text {max }}, x_{\text {max }}\right) \in Q_{\rho}$ satisfying

$$
(\delta-\rho)^{2} \sup _{Q_{\rho}} e(u)=\max _{0 \leq \sigma \leq \delta}\left\{(\delta-\sigma)^{2} \sup _{Q_{\sigma}} e(u)\right\},
$$

$$
e(u)\left(z_{\max }\right)=\sup _{Q_{\rho}} e(u)=e_{0} .
$$

First assume $e_{0}^{-1} \leq((\delta-\rho) / 2)^{2}$ and scale $v(\bar{t}, \bar{x})=u\left(t_{\max }+e_{0}^{-1} \bar{t}, x_{\max }+e_{0}^{-1 / 2} \bar{x}\right)$. Note that $v \in C^{\infty}\left(Q_{1} ; N\right)$ and

$$
\begin{aligned}
\sup _{Q_{1}} e(v)(0) & =e_{0}^{-1} \sup _{Q_{e_{0}^{-1 / 2}}\left(z_{\max }\right)} e(u) \leq e_{0}^{-1} \sup _{Q_{(\delta+\rho) / 2}} e(u) \\
& \leq 4 e_{0}^{-1} \sup _{Q_{\rho}} e(u)=4
\end{aligned}
$$

while

$$
e(v)(0)=1 .
$$

Therefore, by the Bochner inequality (1.13), we have

$$
\left(\frac{d}{d \bar{t}}-\triangle\right) e(v) \leq C e(v) \quad \text { in } \quad Q_{1}(0)
$$

Lemma 1.3 gives

$$
1=e(v)(0) \leq C_{\mathrm{H}} \int_{Q_{1}} e(v) d \bar{t} d \bar{x}=C_{\mathrm{H}} e_{0}^{d / 2} \int_{Q_{e_{0}^{-1 / 2}\left(z_{\max }\right)}} e(u) d t d x
$$

Set $G_{z_{\mathrm{s}}}(z)=G\left(z-z_{\mathrm{s}}\right)$ with $z_{\mathrm{s}}=\left(t_{\mathrm{s}}, x_{\mathrm{s}}\right)$ and choose $z_{\mathrm{s}}=z_{\max }+\left(0, e_{0}^{-1}\right)$. Then

$$
1 \leq C \int_{Q_{e_{0}^{-1 / 2}}\left(z_{\max }\right)} e(u) G_{z_{\mathrm{s}}} d t d x
$$

and by applying Theorem 1.10 for each $t \in\left[t_{\max }-e_{0}^{-1}, t_{\max }\right]$, we proceed to estimate

$$
1 \leq C \int_{\{-1\} \times \mathbb{R}^{d}} e(u) G_{z_{\mathrm{s}}} d x
$$

Now $\left|x_{\mathrm{s}}\right| \leq \delta$ and $\left|t_{\mathrm{s}}\right| \leq \delta^{2}$. Thus at $t=-1$ we can estimate

$$
\begin{aligned}
\left|G_{z_{\mathrm{s}}}-G\right| & \leq \frac{1}{\sqrt{4 \pi}^{d}}\left(\left|1-\frac{1}{{\sqrt{\left|1+t_{\mathrm{s}}\right|}}^{d} \mid}\right|+\left|\exp \left(-\frac{|x|^{2}}{4}\right)-\exp \left(-\frac{\left|x-x_{\mathrm{s}}\right|^{2}}{4\left|1+t_{\mathrm{s}}\right|}\right)\right|\right) \\
& \leq C \delta
\end{aligned}
$$

and therefore we obtain that

$$
1 \leq C \delta \int_{\{-1\} \times \mathbb{R}^{d}} e(u) d x+C \int_{\{-1\} \times \mathbb{R}^{d}} e(u) G d x \leq C_{1} \delta E_{0}+C_{1} \Phi(1),
$$

with a uniform constant $C_{1}=C_{1}(d, N)$. Choosing $\delta=1 /\left(2 C_{1} E_{0}\right)$ and $\epsilon_{0}=1 /\left(2 C_{1}\right)$, the above inequality will lead to a contradiction. Thus $(\delta-\rho)^{2} e_{0} \leq 4$ : we deduce

$$
\sup _{Q_{\delta / 2}} e(u) \leq 16 \delta^{-2} .
$$

The proof is complete.

As an application we establish the following result from Struwe [109].
Proposition 1.5. Suppose that $u_{k} \in C^{\infty}\left([-1,0) \times \mathbb{R}^{d} ; N\right)$ is a sequence of solutions to (1.10) with $E\left(u_{k}(t)\right) \leq E_{0}<\infty$ for any $t$ and for all $k \in \mathbb{N}$. Moreover, suppose $u_{k}(-1) \rightarrow u_{0}$ in $H_{l o c}^{1,2}\left(\mathbb{R}^{d} ; N\right)(k \rightarrow \infty)$ and

$$
\begin{gathered}
u_{k} \longrightarrow u \quad \text { in } L_{l o c}^{2}\left([-1,0] \times \mathbb{R}^{d}\right), \\
\partial_{t} u_{k} \longrightarrow \partial_{t} u \quad \text { in } L_{l o c}^{2}\left([-1,0] \times \mathbb{R}^{d}\right), \\
\nabla u_{k} \longrightarrow \nabla u \quad \text { in } L_{l o c}^{2}\left([-1,0] \times \mathbb{R}^{d}\right) .
\end{gathered}
$$

Then $u$ weakly solves (1.10) and (1.11) and $u$ is smooth away from a closed set $\Sigma$ of co-dimension more than or equal to 2 ; moreover, for any $R>0$ we have

$$
\begin{equation*}
\Phi(R ; u)+\int_{-1}^{-R^{2}} \int_{\mathbb{R}^{d}} \frac{\left|2 t u_{t}+\langle x, \nabla\rangle u\right|^{2}}{2|t|} G d t d x \leq \Phi(-1 ; u) . \tag{1.26}
\end{equation*}
$$

Proof. Set

$$
\Sigma=\bigcap_{R>0}\left\{z ; \liminf _{k \rightarrow \infty} \Phi_{z}\left(R ; u_{k}\right) \geq \epsilon_{0}\right\},
$$

where for any points $z_{0}=\left(t_{0}, x_{0}\right)$,

$$
\Phi_{z_{0}}\left(r ; u_{k}\right)=\frac{r^{2}}{2} \int_{\left\{t_{0}-r^{2}\right\} \times \mathbb{R}^{d}}\left|\nabla u_{k}\right|^{2} G_{z_{0}} d x \quad \text { in } \quad t_{0}-r^{2} \geq-1,
$$

$\Sigma$ is relatively closed. Indeed, if $z_{\infty} \in \bar{\Sigma}$, there exists a sequence of points $z_{l}=\left(t_{l}, x_{l}\right)$ $\in \Sigma(l=1,2, \ldots)$ such that $z_{l} \rightarrow z_{\infty}$. By definition of $\Sigma$ and the monotonicity in Theorem 1.10, we have

$$
\liminf _{l \rightarrow \infty} \liminf _{k \rightarrow \infty}\left(\frac{R^{2}}{2} \int_{\left\{t_{l}-R^{2}\right\} \times \mathbb{R}^{d}}\left|\nabla u_{k}\right|^{2} G_{z_{l}} d x\right) \geq \epsilon_{0}
$$

for any $R>0$. Since $G_{z_{l}} \rightarrow G_{z_{\infty}}$ uniformly on any compact set away from $z_{\infty}$ and since $E\left(u_{k}(t)\right) \leq E_{0}<\infty$, the limits $l \rightarrow \infty$ and $k \rightarrow \infty$ may be interchanged for any fixed $R>0$, thus we obtain

$$
\liminf _{k \rightarrow \infty} \Phi_{z_{\infty}}^{k}(R) \geq \epsilon_{0}
$$

for all $R>0$ : $z_{\infty} \in \Sigma$.
Next observe that for $z_{0} \notin \Sigma$ there is a sequence $\left\{u_{k}\right\}(k=1,2, \ldots)$ and some $R>0$ such that

$$
\Phi_{z_{0}}\left(R ; u_{k}\right)<\epsilon_{0} .
$$

Proposition 1.4 implies that

$$
\sup _{Q_{\delta R}\left(z_{0}\right)}\left|\nabla u_{k}\right| \leq \frac{C}{R}
$$

hold for a positive constant $\delta=\delta\left(d, N, E_{0}\right)>0$ uniformly in $k$ and similar bounds for higher derivatives. Thus we may pass to the limit $k \rightarrow \infty$ in (1.10) and find
that $u$ is a smooth solution of (1.10) on any compact set outside $\Sigma$. In order to assert that $u$ extends to a weak solution beyond $\Sigma$, we need to estimate the $d$-dimensional Hausdorff measure with respect to the parabolic metric

$$
d_{\mathrm{P}}((t, x),(s, y))=|t-s|^{1 / 2}+|x-y| .
$$

For a set $S \subset \mathbb{R}_{+} \times \mathbb{R}^{d}$, the latter is defined as

$$
\mathcal{H}^{d}\left(S ; d_{P}\right)=c(d) \sup _{R>0}\left\{\inf _{\text {covering }}\left\{\sum_{i} r_{i}^{d} ; S \subset \bigcup_{i} P_{r_{i}}\left(z_{i}\right), z_{i} \in S, r_{i}<R\right\}\right\},
$$

where $c(d)$ is a normalizing constant and

$$
P_{r}\left(z_{0}\right)=\left\{z=(t, x) ;\left|t-t_{0}\right|<r^{2},\left|x-x_{0}\right|<r\right\} \quad \text { with } \quad z_{0}=\left(t_{0}, x_{0}\right) .
$$

Fix a compact set $P \subset[-1,0) \times \mathbb{R}^{d}$ and let $S=P \cap \Sigma$. Fix $R>0$ and let $P_{r_{i}}\left(z_{i}\right)\left(r_{i}<\right.$ $R$ ) be a cover of $S$. Since $S$ is compact, we may assume that the cover is finite. Moreover, a simple variant of Vitali's covering lemma shows that there is a disjoint sub-family $P_{r_{i}}\left(z_{i}\right)(i \in \mathcal{J})$ such that $S \subset \cup_{i \in \mathcal{J}} P_{5 r_{i}}\left(z_{i}\right)$. Let $\bar{z}_{i}=z_{i}+\left(0, r_{i}^{2}\right)(i \in \mathcal{J})$. Since $\mathcal{J}$ is finite, there exists $k \in \mathbb{N}$ such that

$$
\begin{aligned}
\epsilon_{0} & \leq \Phi_{z_{i}}\left(\theta_{0} r_{i} ; u_{k}\right) \leq C \int_{t_{i}-4 \theta_{0}^{2} r_{i}^{2}}^{t_{i}-\theta_{r^{2}}^{2} r_{i}^{2}} \int_{\mathbb{R}^{d}}\left|\nabla u_{k}\right|^{2} G_{z_{i}} d t d x \\
& \leq C\left(\theta_{0}\right) r_{i}^{-d} \int_{Q_{r_{i}}\left(z_{i}\right)}\left|\nabla u_{k}\right|^{2} d t d x \\
& +C \theta_{0}^{-d} \exp \left(-\frac{1}{16\left(1+4 \theta_{0}\right) \theta_{0}}\right) \int_{t_{i}-4 \theta_{0}^{2} r_{i}^{2}}^{t_{i}-\theta_{0}^{2} r_{i}^{2}} \int_{\mathbb{R}^{d} \backslash B_{r_{i}}}\left|\nabla u_{k}\right|^{2} G_{\bar{z}_{i}} d t d x \\
& \leq C\left(\theta_{0}\right) r_{i}^{-d} \int_{Q_{r_{i}}\left(z_{i}\right)}\left|\nabla u_{k}\right|^{2} d t d x+C \theta_{0}^{2-d} \exp \left(-\frac{1}{16\left(1+4 \theta_{0}\right) \theta_{0}}\right) E_{0}
\end{aligned}
$$

for all $i \in \mathcal{J}$ where we used the fact that

$$
G_{z_{i}} \leq \theta_{0}^{-d} \exp \left(-\frac{1}{16\left(1+4 \theta_{0}\right) \theta_{0}}\right) G_{\bar{z}_{i}} \quad \text { on }\left[t_{i}-4 \theta_{0}^{2} r_{i}^{2}, t_{i}-\theta_{0}^{2} r_{i}^{2}\right] \times \mathbb{R}^{d} \backslash Q_{r_{i}}\left(z_{i}\right)
$$

and Theorem 1.10 to derive the 1 st inequality. Take $\theta_{0}>0$ satisfying

$$
C \theta_{0}^{2-d} \exp \left(-\frac{1}{16\left(1+4 \theta_{0}\right) \theta_{0}}\right) E_{0}<\frac{\epsilon_{0}}{2}
$$

to verify

$$
r_{i}^{d} \leq C \int_{P_{r_{i}}\left(z_{i}\right)}\left|\nabla u_{k}\right|^{2} d t d x
$$

Summing over $i \in \mathcal{J}$, we obtain

$$
\sum_{i \in \mathcal{J}} r_{i}^{d} \leq C \sum_{i \in \mathcal{J}} \int_{P_{r_{i}\left(z_{i}\right)}}\left|\nabla u_{k}\right|^{2} d t d x
$$

$$
=C \int_{\cup_{i \in \mathcal{J}} P_{r_{i}}\left(z_{i}\right)}\left|\nabla u_{k}\right|^{2} d t d x \leq C(\mathcal{J}) E_{0}
$$

with constants $C$ independent of $R>0$. Thus the $d$-dimensional Hausdorff measure of $\Sigma$ is locally finite.

In particular, for a suitable cover $\left(Q_{r_{i}}\left(z_{i}\right)\right)_{i \in \mathcal{J}}$ of $S\left(r_{i}<R\right)$, we can achieve that

$$
\mathcal{L}^{2+d}\left(\bigcup_{i \in \mathcal{J}} P_{r_{i}}\left(z_{i}\right)\right) \rightarrow 0 \quad \text { as } R \searrow 0
$$

where $\mathcal{L}^{2+d}$ denotes the Lebesgue measure on $(t, x)$ in $\mathbb{R}_{+} \times \mathbb{R}^{d}$ with respect to the parabolic metric. Now let $\phi \in \mathcal{D}\left(P_{2}(0)\right)$ satisfy $0 \leq \phi \leq 1, \phi \equiv 1$ on $P_{1}(0)$ and scale $\phi_{i}(z)=\phi\left(\left(t-t_{i}\right) / r_{i}^{2},\left(x-x_{i}\right) / r_{i}\right) \in \mathcal{D}\left(P_{2 r_{i}}\left(z_{i}\right)\right)$. Given $\psi \in \mathcal{D}\left(P_{1} ; \mathbb{R}^{D}\right)$, then $\tau=$ $\psi \inf _{i}\left(1-\phi_{i}\right)$ is a Lipschitz function and $\tau(z) \rightarrow \psi(z)$ a.e. as $R \searrow 0$. Multiplying (1.10) by $\tau$, we obtain

$$
\begin{aligned}
& \int_{-1}^{0} \int_{\mathbb{R}^{d}}\left(u_{t}-\triangle u-A(u)(\nabla u, \nabla u)\right) \psi d t d x \\
& \quad \leq C \int_{-1}^{0} \int_{\mathbb{R}^{d}}|\nabla u|\left|\nabla \inf _{i}\left(1-\phi_{i}\right)\right| d t d x+o(1) \\
& \quad \leq C\|\nabla u\|_{L^{2}\left(\cup_{i \in \mathcal{J}} P_{r_{i}}\left(z_{i}\right)\right)}\left(\int_{-1}^{0} \int_{\mathbb{R}^{d}}\left|\nabla \inf _{i}\left(1-\phi_{i}\right)\right|^{2} d t d x\right)^{1 / 2}+o(1) \\
& \quad \leq o(1)\left(\sum_{i} \int_{P_{r_{i}\left(z_{i}\right)}} r_{i}^{-2} d t d x\right)^{1 / 2}+o(1) \\
& \quad=o(1)\left(\sum_{i} r_{i}^{d}\right)^{1 / 2}+o(1) \rightarrow 0 \quad(R \searrow 0),
\end{aligned}
$$

where $o(1) \rightarrow 0$ as $R \searrow 0$ and $u$ weakly solves (1.10). Finally (1.26) follows from (1.25) and the fact that $\Phi(R ; u) \leq \liminf _{k \rightarrow \infty} \Phi\left(R ; u_{k}\right), \Phi(1 ; u)=\Phi\left(1 ; u_{0}\right)=\lim _{k \rightarrow \infty} \Phi\left(1 ; u_{k}\right)$.

The proof of Theorem 1.8 uses the fact that results similar to Theorem 1.10 and Proposition 1.4 hold for solutions $u$ to (1.10) on a compact manifold $M$, where $\Phi$ is defined with reference to a local coordinate chart $V$ and where we truncate the integrand with a smooth cut-off function $\tau \in \mathcal{D}(V)$. Set $\lambda \in \mathbb{R}_{+}$. If $U_{\delta}$ is $3 \delta$-tubular neighborhood on $N$ in $\mathbb{R}^{\hat{D}}$ and if for maps $u: M \rightarrow \mathbb{R}^{\hat{D}}, E_{\lambda}$ is

$$
E_{\lambda}(u):=E(u)+\lambda \int_{M} \chi\left(\operatorname{dist}^{2}(u, N)\right) d x,
$$

where $\chi(s)=s$ for $s \leq \delta, \chi^{\prime}(s) \geq 0, \chi(s) \equiv 2 \delta$ for $s \geq 3 \delta$, then the sequence of approximate solutions $\left\{u_{\lambda}\right\}(\lambda>0)$ to (1.10) defined by the gradient flow of $E_{\lambda}$ again satisfies an analogue of Theorem 1.10 and Proposition 1.4. Similar to Proposition
1.5, we then establish that a sub-sequence $\left\{u_{\lambda}\right\}(\lambda>0)$ converges weakly to a partially regular weak solution $u$ of (1.10) and (1.11). Moreover, inequality (1.25) holds. See Chen-Struwe [24] for details.

Let us now turn to some further consequences of the monotonicity formula.

## Nonuniqueness

Coron $[\mathbf{2 7}]$ observed that for certain weakly harmonic maps $u_{0}: B^{3} \rightarrow S^{2}$, the stationary weak solution $u(t, x)=u_{0}(x)$ of (1.10) does not satisfy (1.26), hence must be different from the solution constructed in Theorem 1.8.

We repeat his construction: Suppose $u_{0} \in H_{\mathrm{loc}}^{1,2}\left(\mathbb{R}^{3} ; S^{2}\right)$ is weakly harmonic, $u_{0}(x)=u_{0}(x /|x|)$ and consider $u(t, x)=u_{0}(x)$. Then $u$ weakly solves (1.10) and

$$
\Phi_{\bar{z}}(\rho)=\frac{1}{2 \sqrt{4 \pi}^{3} \rho} \int_{\mathbb{R}^{3}}\left|\nabla u_{0}\right|^{2} \exp \left(-\frac{|x-\bar{x}|^{2}}{4 \rho^{2}}\right) d x<\infty
$$

for any $\bar{z}=(\bar{t}, \bar{x}) \in \mathbb{R}_{+} \times \mathbb{R}^{3}$ and any $\rho>0$. Suppose that $u$ satisfies (1.25). This implies

$$
\begin{equation*}
\frac{1}{\rho} \int_{\mathbb{R}^{3}}\left|\nabla u_{0}\right|^{2} \exp \left(-\frac{|x-\bar{x}|^{2}}{4 \rho^{2}}\right) d x \leq \frac{1}{r} \int_{\mathbb{R}^{3}}\left|\nabla u_{0}\right|^{2} \exp \left(-\frac{|x-\bar{x}|^{2}}{4 r^{2}}\right) d x \tag{1.27}
\end{equation*}
$$

for any $0<\rho<r<\infty$. We show that (1.27) does not hold for a suitable map $u_{0}$. This ill-behaved map $u_{0}$ is obtained as follows. Let $\pi: S^{2} \backslash\{(0,0,1)\} \rightarrow \mathbb{R}^{2} \cong \mathbb{C}$ be the stereographic projection from the north pole $(0,0,1)$ of $S^{2}$ and let $g: \mathbb{C} \rightarrow \mathbb{C}$ be a rational map. Composing the weakly harmonic map $u: x \rightarrow x /|x|$ from Example 1.2 with $\pi$ and $g$ we obtain a map

$$
u_{0}(x)=\pi^{-1}\left(g\left(\pi\left(\frac{x}{|x|}\right)\right)\right) .
$$

Regarding $u_{0}(x)=u_{0}(x /|x|)$ as a map $u_{0}: S^{2} \rightarrow S^{2}$, by conformal invariance $u_{0}$ is harmonic; hence $u_{0}: \mathbb{R}^{3} \rightarrow S^{2}$ is weakly harmonic. By suitable choice of $g$ (for instance, $g(z)=\lambda z$ with $\lambda \in \mathbb{R}$ and $\lambda>1$ ), we can achieve that the center of mass

$$
q=\int_{S^{2}}\left|\nabla u_{0}\left(\frac{x}{|x|}\right)\right|^{2} \frac{x}{|x|} d v o l_{S^{2}} \neq 0 .
$$

(Hence the map $u_{0}$ is not minimizing for its boundary values on $B_{1}^{3}(0)$; see Brezis-Coron-Lieb [11, Remark 7.6].)

Denote

$$
\phi(\rho, \bar{x})=\frac{1}{\rho} \int_{\mathbb{R}^{3}}\left|\nabla u_{0}\right|^{2} \exp \left(-\frac{|x-\bar{x}|^{2}}{4 \rho^{2}}\right) d x
$$

for simplicity. Note that

$$
\phi(\rho, 0)=\int_{0}^{\infty}\left(\int_{S^{2}}\left|\nabla u_{0}\left(\frac{x}{|x|}\right)\right|^{2} d v o l_{S^{2}}\right) \exp \left(-\frac{|x|^{2}}{4 \rho^{2}}\right) \frac{d|x|}{\rho}\left(:=a_{0}\right)
$$

is independent of $\rho>0$. Moreover, compute

$$
\begin{aligned}
\nabla_{\bar{x}} \phi(\rho, 0) & =\int_{\mathbb{R}^{3}}\left|\nabla_{S^{2}} u_{0}\left(\frac{x}{|x|}\right)\right|^{2} \frac{x}{2 \rho^{3}} \exp \left(-\frac{|x|^{2}}{4 \rho^{2}}\right) d x \\
& =\int_{0}^{\infty}\left(\int_{S^{2}}\left|\nabla_{S^{2}} u_{0}\left(\frac{x}{|x|}\right)\right|^{2} \frac{x}{|x|} d v o l_{S^{2}}\right) \cdot \frac{\exp \left(-\frac{|x|^{2}}{4 \rho^{2}}\right)}{2 \rho^{3}}|x| d|x| \\
& =q \int_{0}^{\infty} \frac{\exp (-\sigma) d \sigma}{\rho}=\frac{q}{\rho} .
\end{aligned}
$$

Hence for $\bar{x}=t q$ and $0<\rho<r$, if $t>0$ is sufficiently small, we then obtain

$$
\phi(\rho, \bar{x})=a_{0}+t \frac{|q|^{2}}{\rho}+O\left(t^{2}\right)>\phi(r, \bar{x})=a_{0}+t \frac{|q|^{2}}{r}+O\left(t^{2}\right),
$$

contradicting (1.27). On the other hand, as in Theorem 1.8 we can construct weak solutions $\tilde{u}$ to (1.10) for initial data $u_{0}$ satisfying (1.25): This reads that $u \neq \tilde{u}$ and therefore we show nonuniqueness in the energy class of weak solutions to (1.10) and (1.11).

Note that we look at spontaneous symmetry breaking, since $u$ cannot be of the form $u(t, x)=v(t, x /|x|)$. The latter map $v$ would solve (1.10) and (1.11) on $[0, \infty) \times S^{2}$. Since $u_{0}: S^{2} \rightarrow S^{2}$ is smooth and harmonic, by local unique solvability of (1.10) and (1.11) on $[0, \infty) \times S^{2}$ for smooth data, this would imply $v(t) \equiv u_{0}$.

It is remained to discuss a class of functions satisfying (1.10) and (1.11) which possesses a unique solution. Struwe, M suggests that the class of solutions satisfying the strong monotonicity formula

$$
\Phi_{\bar{z}}(\rho) \leq \Phi_{\bar{z}}(r)
$$

for all $\bar{z}$ and all $0<\rho<r \leq \sqrt{t}$ is a likely candidate.

## Development of singularities

The most surprising aspect of the monotonicity formula is that it may be used to prove that (1.10) and (1.11) in general will develop singularities in arbitrarily short time. The existence of singularities was first established by Coron-Ghidaglia [28]; see also Grayson-Hamilton [50]. These results were based on comparison principles for the reduced harmonic map evolution problem (1.16) in the equivariant setting. A deeper reason for the formation of singularities was worked out by Chen-Ding [21]. This is related to a result by White [120].

Theorem 1.11. Let $M$ and $N$ be compact Riemannian manifolds and consider a smooth map $u_{0}: M \rightarrow N$. Then

$$
\inf \left\{E(u) ; u \in C^{\infty}(M ; N), \quad u \text { is homotopic to } u_{0}\right\}>0
$$

if and only if the restriction of $u_{0}$ to a 2-skeleton of $M$ is not homotopic to a constant.

Remark 1.2. In particular, there are examples of non-trivial homotopy classes of maps $u_{0}: M \rightarrow N$ such that

$$
\inf \left\{E(u) ; u \text { is homotopic to } u_{0}\right\}=0
$$

Example 1.6. Let $u_{1}=\mathrm{id}: S^{3} \rightarrow S^{3}$. Let $\pi: S^{3} \backslash\{(0,0,0,1)\} \rightarrow \mathbb{R}^{3}$ be the stereographic projection and let $D_{\lambda}: \mathbb{R}^{3} \rightarrow \mathbb{R}^{3}, D_{\lambda}(x)=\lambda x$ be dilation with $\lambda>0$. Then define

$$
u_{\lambda}=\pi^{-1} \circ D_{\lambda} \circ \pi: S^{3} \rightarrow S^{3} .
$$

Clearly, $u_{\lambda} \sim u_{1}=i d$ for all $\lambda>0$ and $E\left(u_{\lambda}\right) \rightarrow 0 \quad(\lambda \rightarrow \infty)$.

## Singularities of first and second kind

Let $u \in C^{\infty}\left([-1,0) \times \mathbb{R}^{d} ; N\right)$ be a solution to (1.10) with an isolated singularity at the origin and satisfying (1.25). If

$$
\begin{equation*}
|\nabla u(t, x)|^{2} \leq \frac{C}{|t|} \tag{1.28}
\end{equation*}
$$

the rescaled sequence

$$
u_{R}(\bar{t}, \bar{x})=u\left(R^{2} \bar{t}, R \bar{x}\right), \quad R>0
$$

satisfies the same estimate and hence a sub-sequence converges smoothly locally on $(-\infty, 0) \times \mathbb{R}^{d}$ to a smooth limit $\bar{u}$ as $R \searrow 0$. $\bar{u}$ satisfies (1.10). Moreover, $\bar{u} \not \equiv$ const; otherwise $\Phi(R ; u)=\Phi\left(1, u_{R}\right)<\epsilon_{0}$ for some $R>0$ and $u$ is regular at 0 . Since by (1.26) there holds

$$
\begin{aligned}
\int_{-T R^{2}}^{-\tau R^{2}} \int_{\mathbb{R}^{d}} \frac{\left|2 t \partial_{t} u+\langle x, \nabla\rangle u\right|^{2}}{2|t|} G d t d x & \leq \lim _{R \backslash 0} \int_{-T}^{-\tau} \int_{\mathbb{R}^{d}} \frac{\left|2 \bar{t} \partial_{\bar{t}} u_{R}+\langle\bar{x}, \nabla\rangle u_{R}\right|^{2}}{2|\bar{t}|} G d \bar{t} d \bar{x} \\
& =\int_{-T}^{-\tau} \int_{\mathbb{R}^{d}} \frac{\left|2 \bar{t} \partial_{\bar{t}} \bar{u}+\langle\bar{x}, \nabla\rangle \bar{u}\right|^{2}}{2|\bar{t}|} G d \bar{t} d \bar{x}=0
\end{aligned}
$$

for any $0<\tau<T<\infty$, it follows that $\bar{u}$ satisfies

$$
2 \bar{t} \bar{u}_{\bar{t}}+\bar{x} \nabla \bar{u} \equiv 0 ;
$$

that is possibly

$$
\bar{u}(\bar{t}, \bar{x})=v\left(\frac{\bar{x}}{\sqrt{|\bar{t}|}}\right)
$$

or

$$
\bar{u}(\bar{t}, \bar{x})=w\left(\frac{\bar{x}}{|\bar{x}|}\right) .
$$

Struwe, M calls the singular point satisfying (1.28) "singular point of the first kind." It is not known whether self-similar solutions $\bar{u}(t, x)=v(x / \sqrt{|t|})$ actually may exist. All other singular points are said to be "singularities of second kind." Since singularities in $d=2$ by Theorem 1.7 are related to time-independent harmonic maps $\bar{u}: S^{2} \rightarrow N$ of finite energy and since a non-constant, radially
homogeneous map $\bar{u}(x)=w(x /|x|)$ in $d=2$ has infinite energy, Theorem 1.6 of Chang-Ding-Ye [18] above shows that singularities of second kind exist for the evolution problem (1.10).

## Extensions and generalizations

Further current developments include the evolution problem to harmonic maps on general complete, non-compact manifolds (Li-Tam [78]) and to harmonic maps with symmetry (see Grotowsky [51], [52], [53] and [54]).

## 6. Notation

In this section, we collect abridged notation and function spaces used in the following chapter. Let $T$ be a positive number or $+\infty$. Set $\Omega$ be a bounded domain in $\mathbb{R}^{d}$ with a smooth boundary.

## Abridged Notation

(i) $B_{1}^{d}(0)=\left\{x=\left(x_{1}, x_{2}, \ldots, x_{d}\right) ;|x|=\sqrt{\sum_{\alpha=1}^{d}\left(x_{\alpha}\right)^{2}}<1\right\}$, we abbreviate $B_{1}^{d}(0)$ to $B_{1}$ or $B$ when no ambiguity may occur.
(ii) $Q_{T}$ is $(0, T) \times \Omega$ and $\partial Q_{T}$ (the boundary of $Q_{T}$ ) means $\{0\} \times \Omega \cup[0, T) \times \partial \Omega$.
(iii) The parabolic metric function $d\left(z, z^{\prime}\right)$ is given by

$$
d_{\mathrm{P}}\left(z, z^{\prime}\right)=\left|t-t^{\prime}\right|^{1 / 2}+\left|x-x^{\prime}\right|
$$

whenever $z=(t, x)$ and $z^{\prime}=\left(t^{\prime}, x^{\prime}\right) \in Q_{T}$, and we set

$$
\begin{aligned}
& d_{\mathrm{P}}\left(z, \partial Q_{T}\right)=\inf _{z^{\prime} \in \partial Q_{T}} d_{\mathrm{P}}\left(z, z^{\prime}\right), \\
& \operatorname{diam}(\Omega)=\sup _{x, y \in \Omega}|x-y|
\end{aligned}
$$

(iv) $\nu_{x}$ denotes the outward normal unit vector to $\Omega$ at $x \in \partial \Omega$. When no confusion may arise, we shorten $\nu_{x}$ to $\nu$.
(v) For a point $x_{0}=\left(x_{0, \alpha}\right)(\alpha=1, \ldots, d) \in \mathbb{R}^{d}$ or $z_{0}=\left(t_{0}, x_{0}\right) \in \mathbb{R}^{1+d}$ and positive numbers $\rho, \tau$, we set

$$
\left\{\begin{aligned}
B_{\rho}\left(x_{0}\right) & =\left\{x \in \mathbb{R}^{d}:\left|x-x_{0}\right|<\rho\right\} \\
C_{\rho}\left(x_{0}\right) & =\left\{x \in \mathbb{R}^{d}:\left|x_{\alpha}-x_{0, \alpha}\right|<\rho(\alpha=1, \ldots, d)\right\} \\
P_{\rho, \tau}\left(z_{0}\right) & =\left\{(t, x) \in \mathbb{R}^{1+d}: t_{0}-\tau^{2}<t \leq t_{0}+\tau^{2},\left|x-x_{0}\right|<\rho\right\}, \\
Q_{\rho, \tau}\left(z_{0}\right) & =\left\{(t, x) \in \mathbb{R}^{1+d}: t_{0}-\tau^{2}<t \leq t_{0},\left|x-x_{0}\right|<\rho\right\} \\
D_{\rho, \tau}\left(z_{0}\right) & =\left\{(t, x) \in \mathbb{R}^{1+d}: t_{0}-\tau^{2}<t \leq t_{0},\left|x_{\alpha}-x_{0, \alpha}\right|<\rho\right. \\
& (\alpha=1, \ldots, d)\}, \\
P_{\rho}\left(z_{0}\right) & =P_{\rho, \rho^{2}}\left(z_{0}\right), \quad Q_{\rho}\left(z_{0}\right)=Q_{\rho, \rho^{2}}\left(z_{0}\right) \text { and } D_{\rho}\left(z_{0}\right)=D_{\rho, \rho^{2}}\left(z_{0}\right) .
\end{aligned}\right.
$$

We call $B_{\rho}\left(x_{0}\right), C_{\rho}\left(x_{0}\right), P_{\rho}\left(z_{0}\right), Q_{\rho}\left(z_{0}\right)$ and $D_{\rho}\left(z_{0}\right)$, a ball, a cube, a full cylinder, a cylinder and a semi-cube and moreover when no confusion may
arise, we respectively abbreviate $B_{\rho}\left(x_{0}\right), C_{\rho}\left(x_{0}\right), P_{\rho}\left(z_{0}\right), Q_{\rho}\left(z_{0}\right)$ and $D_{\rho}\left(z_{0}\right)$ to $B, C, P, Q$ and $D$.
(vi) For vectors $x=\left(x_{\alpha}\right), y=\left(y_{\alpha}\right) \in \mathbb{R}^{d}, u=\left(u^{i}\right), v=\left(v^{i}\right) \in \mathbb{R}^{D}$ and any matrices $A=\left(A_{\alpha}^{i}\right), B=\left(B_{\alpha}^{i}\right) \in \mathbb{R}^{d \times D}(\alpha=1, \ldots, d ; i=1, \ldots, D),\langle\cdot, \cdot\rangle$ respectively designates the inner product given by $\langle x, y\rangle=\sum_{\alpha=1}^{d} x_{\alpha} y_{\alpha},\langle u, v\rangle=$ $\sum_{i=1}^{D} u^{i} v^{i}$ and $\langle A, B\rangle=\sum_{\alpha=1}^{d} \sum_{i=1}^{D} A_{\alpha}^{i} B_{\alpha}^{i}$. The respective norm is also given by $|u|=\sqrt{\sum_{i=1}^{D}\left(u^{i}\right)^{2}}$ and $|A|=\sqrt{\sum_{\alpha=1}^{d} \sum_{i=1}^{D}\left(A_{\alpha}^{i}\right)^{2}}$. Moreover, for any vector $x=\left(x_{\alpha}\right)(\alpha=1,2, \ldots, d)$, we use the symbol $\langle x, \nabla\rangle$ as $\sum_{\alpha=1}^{d} x_{\alpha} \partial / \partial x_{\alpha}$.
(vii) For a map $v: \mathbb{R}^{d} \rightarrow \mathbb{R}^{D}$, we denote $\nabla v$ and $\nabla^{2} v$ by

$$
\begin{aligned}
\nabla u & =\left(\frac{\partial u^{i}}{\partial x_{\alpha}}\right) \quad(\alpha=1,2, \ldots, d ; i=1,2, \ldots, D) \\
\nabla^{2} u & =\left(\frac{\partial^{2} u^{i}}{\partial x_{\alpha} \partial x_{\beta}}\right) \quad(\alpha, \beta=1,2, \ldots, d ; i=1,2, \ldots, D)
\end{aligned}
$$

In addition, a normal derivative $\partial u / \partial \nu$ is given by $\langle\nu, \nabla\rangle u$, while a tangential derivative $\nabla_{\text {tan }}$ is by $\nabla u-\nu\langle\nu, \nabla\rangle u$.
(viii) Let $\kappa$ be a positive number. For any function $u$ on $Q_{T}$, we write the truncation function of $u$ by

$$
u^{(\kappa)}=\max (u-\kappa, 0) .
$$

(ix) $A_{R}^{(\kappa)}\left(z_{0}\right)$ is the set of $Q_{R}\left(z_{0}\right)$ at which $e_{\lambda}\left(u_{\lambda}\right)>\kappa$.
(x) $\mathcal{L}^{d_{i}}(A)$ expresses the Lebesgue measure of a measurable set $A$ in $\mathbb{R}^{d_{i}}$ with respect to the canonical metric in $d_{i}=d-1, d$ and with respect to the parabolic metric in $d_{i}=d+1$.
(xi) $\bar{A}$ is the closure of $A$ where $A$ is a set in $\mathbb{R}^{d_{i}},\left(d_{i}=d, d+1\right)$.
(xii) The letters $C, C_{\text {Alphabets }}$ and $C_{\text {Alphabets }}^{\text {Number }}$ denote generic constants.

## Function spaces

(i) If $1 \leq p<\infty, L^{p}(\Omega)$ and $L^{p}\left(Q_{T}\right)$ is respectively the Banach space consisting of all $p$ th summable functions on $\Omega$ and $Q_{T}$ with the norm of $\|f\|_{L^{p}(\Omega)}=$ $\left(\int_{\Omega}|f(x)|^{p} d x\right)^{1 / p}$ and $\|\left. f\right|_{L^{p}\left(Q_{T}\right)}=\left(\int_{Q_{T}}|f(z)|^{p} d z\right)^{1 / p}$.
(ii) $L^{\infty}(\Omega)$ is the space of essentially bounded functions on $\Omega$ with the norm of $\|f\|_{L^{\infty}(\Omega)}=\underset{x \in \Omega}{\operatorname{ess} \cdot \sup }|f(x)|$.
(iii) $C^{\infty}[0, T), C^{\infty}(\Omega)$ and $C^{\infty}\left(Q_{T}\right)$ respectively means the space of infinite differentiable functions on $[0, T), \Omega$ and $Q_{T}$.
(iv) $\mathcal{D}(\Omega)$ and $\mathcal{D}\left(Q_{T}\right)$ respectively denotes the space of infinite differentiable functions with a compact support on $\Omega$ and $Q_{T}$ and $\mathcal{D}^{\prime}\left(Q_{T}\right)$ does the dual of $\mathcal{D}\left(Q_{T}\right)$.
(v) $H^{1,2}(\Omega)=\left\{f \in L^{2}(\Omega) \mid \partial f / \partial x_{\alpha} \in L^{2}(\Omega),(\alpha=1, \ldots, d)\right\}$.
(vi) $\stackrel{\circ}{H}^{1,2}(\Omega)=H^{1,2}(\Omega) \cap\{f=0$ on $\partial \Omega$ in the trace sense $\}$.

In the following, $X(\Omega)$ denotes a Banach space on $\Omega$ endowed with the norm $\|\cdot\|_{X(\Omega)}$.
(v) $X_{\text {loc }}(\Omega)=\{f \in X(K)$ for any open set $\bar{K} \subset \subset \Omega\}$.
(vi) $X\left(\Omega ; \mathbb{R}^{D}\right)=\left\{u=\left(u^{i}\right)(i=1, \ldots, D) \mid u^{i} \in X(\Omega)\right\}$.
(vii) $X\left(\Omega ; S^{D-1}\right)=\left\{u=\left(u^{i}\right)(i=1, \ldots, D) \in X\left(\Omega ; \mathbb{R}^{D}\right)| | u \mid=1\right.$ for a.e $\left.x \in \Omega\right\}$.
(viii) $L^{\infty}\left(Q_{T} ; \mathbb{R}^{D}\right)=\left\{f \mid f\right.$ is measurable from $Q_{T} \rightarrow \mathbb{R}^{D}$ with the norm of $\|f\|_{L^{\infty}\left(Q_{T}\right)}$ $=\operatorname{ess} \cdot \sup |f|\}$. $z \in Q_{T}$
(ix) $C^{0}\left(0, T ; H^{1,2}\left(\Omega ; \mathbb{R}^{D}\right)\right)=\left\{f \mid f\right.$ is continuous from $\left.[0, T) \rightarrow H^{1,2}\left(\Omega ; \mathbb{R}^{D}\right)\right\}$.
(x) $H^{1,2}\left(0, T ; X\left(\Omega ; \mathbb{R}^{D}\right)\right)$
$=\left\{f \mid f\right.$ and $\partial f / \partial t$ are measurable of $[0, T) \rightarrow X\left(\Omega ; \mathbb{R}^{D}\right)$ satisfying

$$
\left.\left(\int_{0}^{T}\|f(t)\|_{X(\Omega)}^{2} d t\right)^{1 / 2}+\left(\int_{0}^{T}\|\partial f / \partial t(t)\|_{X(\Omega)}^{2} d t\right)^{1 / 2}<\infty\right\}
$$

(xi) $H^{1,2}\left(Q_{T} ; \mathbb{R}^{D}\right)=H^{1,2}\left(0, T ; L^{2}\left(\Omega ; \mathbb{R}^{D}\right)\right) \cap L^{2}\left(0, T ; H^{1,2}\left(\Omega ; \mathbb{R}^{D}\right)\right)$.
(xii) $\stackrel{\circ}{H}^{1,2}\left(Q_{T} ; \mathbb{R}^{D}\right)=H^{1,2}\left(0, T ; L^{2}\left(\Omega ; \mathbb{R}^{D}\right)\right) \cap L^{2}\left(0, T ; \stackrel{\circ}{H}^{1,2}\left(\Omega ; \mathbb{R}^{D}\right)\right)$.
(xiii) $V\left(Q_{T} ; S^{D-1}\right)=H^{1,2}\left(0, T ; L^{2}\left(\Omega ; S^{D-1}\right)\right) \cap L^{\infty}\left(0, T ; H^{1,2}\left(\Omega ; S^{D-1}\right)\right)$.

## CHAPTER 2

## Modified strong evolutional harmonic maps

## 1. Introduction and theorem

In chapter 1, we have reviewed various results on harmonic maps and evolutional harmonic maps. In this chapter, to discuss the well-behaved solutions of the weakly evolutional harmonic maps from $(0,+\infty) \times B_{1}^{3}(0) \rightarrow S^{D-1}$, we propose a certain function class and discuss an evolutional harmonic map belonging to this function class, which will be called "modified strong evolutional harmonic maps." The similar class of solutions of evolutional harmonic maps can be seen in Feldman [43] and Chen-Li-Lin [22]. We begin with formulating "modified strong evolutional harmonic maps" from $(0,+\infty) \times B_{1}^{3}(0)$ to $S^{D-1}$. Here $B_{1}^{3}(0)$ is the open unit ball in $\mathbb{R}^{3}$ and $S^{D-1}$ denotes the ( $D-1$ )-dimensional unit sphere in $\mathbb{R}^{D}$ where $D$ is a positive integer with $D \geq 2$. In the following we abbreviate $B_{1}^{3}(0)$ to $B_{1}$. Consider the Sobolev space $H^{1,2}\left(B_{1} ; S^{D-1}\right):=\left\{u \in H^{1,2}\left(B_{1} ; \mathbb{R}^{D}\right) ;|u|=\right.$ 1 fora.e. $\left.x \in B_{1}\right\}$. When we set $Q_{\infty}=[0,+\infty) \times B_{1}$ and fix $u_{0} \in H^{1,2}\left(B_{1} ; S^{D-1}\right)$ being any given maps, "weakly evolutional harmonic maps $u$ " are to satisfy the following:

$$
\begin{array}{rlr}
u & : Q_{\infty} \rightarrow S^{D-1}, & \\
\frac{\partial u}{\partial t} & =\triangle u+|\nabla u|^{2} u & \quad \text { in } \quad Q_{\infty}, \\
u(0, x) & =u_{0}(x) & \text { in }\{0\} \times B_{1}, \\
u(t, x) & =u_{0}(x) & \text { in } \quad[0, T) \times \partial B_{1} . \tag{2.4}
\end{array}
$$

This parabolic system strictly holds in the following weak sense:

$$
\begin{align*}
& u \in V\left(Q_{\infty} ; S^{D-1}\right),  \tag{2.5}\\
& \int_{Q}\left[\left\langle\frac{\partial u}{\partial t}, \phi\right\rangle+\langle\nabla u, \nabla \phi\rangle-\langle u, \phi\rangle|\nabla u|^{2}\right] d z=0 \\
& \text { for any } \quad \phi \in \mathcal{D}\left(Q_{\infty} ; \mathbb{R}^{D}\right),  \tag{2.6}\\
& u(t, x)-u_{0}(x) \in \stackrel{H}{H}^{1,2}\left(B_{1} ; \mathbb{R}^{D}\right) \quad \text { for almost every } t \in(0,+\infty),  \tag{2.7}\\
& \lim _{t \rightarrow+0} u(t, \cdot)=u_{0}(\cdot) \quad \text { in } \quad L^{2}\left(B_{1} ; \mathbb{R}^{D}\right), \tag{2.8}
\end{align*}
$$

where the definition of various function spaces $V, \mathcal{D}, \stackrel{\circ}{H}{ }^{1,2}$ and $L^{2}$ will be given in p. 42 .

We call a map $u$ with (2.5),(2.6),(2.7) and (2.8) weakly evolutional harmonic maps; as we saw in the previous chapter, weakly evolutional harmonic maps are still not unique. To distinguish a well-behaved solution among many weakly evolutional harmonic maps, we give a new notion of solutions to the problem (2.1),(2.2), (2.3) and (2.4); we name such a solution as "modified strong evolutional harmonic map." The exact definition of modified strong evolutional harmonic map from $Q_{\infty}$ to $S^{D-1}$ is as follows: For any unit vector $\mathbf{e} \in \mathbb{R}^{3}$, and for any compact set $Q \subset \subset Q_{\infty}$, if weakly evolutional harmonic maps satisfy

$$
\begin{align*}
& \lim _{h \backslash 0} \frac{1}{h} \int_{Q}|\langle x+h \mathbf{e}, \nabla\rangle u(t, x+h \mathbf{e})-\langle x, \nabla\rangle u(z)|^{2} d z=0,  \tag{2.9}\\
& \lim _{h \searrow 0} \frac{1}{h} \int_{Q}|\nabla u(t+h, x)-\nabla u(z)|^{2} d z=0, \tag{2.10}
\end{align*}
$$

then this heat flows $u$ i.e. map $u$ satisfying (2.5), (2.6), (2.7), (2.8), (2.9) and (2.10) is said to be "modified strong evolutional harmonic map."

In this chapter, we discuss a partial regularity result on the modified strong evolutional harmonic maps. The further imposition, i.e. (2.9) and (2.10) on modified strong evolutional harmonic map $u$, is required to show that $u$ satisfies a fundamental energy estimate and a monotonicity for the scaled energy on the whole domain.

We must recall that the monotonicity for the scaled energy is a one of the key ingredients to investigate the structure of the singular set of solutions to various elliptic systems or variational problems.

We close this section by introducing a partial regularity result, which is our main theorem of this chapter. The proof of theorem is directly derived from the following two theorems: Former theorem proves a Hausdorff dimensional estimate for a singular set to modified strong evolutional harmonic map. This sort of theorem is founded in Caffarelli-Kohn-Nirenberg [14] and Giaquinta-Giusti [47]. We state this theorem without proof. On the other hand, the latter crucially is modeled on Evans [40]:

Theorem 2.1. Let $u$ be the modified strong heat flows. When we set

$$
\Sigma_{u}:=\left\{z_{0}=\left(t_{0}, x_{0}\right) \in Q_{\infty} ; \liminf _{r \backslash 0} r^{-3} \int_{Q_{r}\left(z_{0}\right)}|\nabla u(z)|^{2} d z>0\right\},
$$

then $\Sigma_{u}$ is a relatively closed set having a property of $\mathcal{H}^{3}\left(\Sigma_{u}\right)=0$ with respect to the parabolic metric.

THEOREM 2.2. There exist constants $0<\epsilon_{0}, \tau_{0}<1$ such that for any $Q_{r}\left(z_{0}\right) \subset$ $\subset Q$

$$
\begin{aligned}
& \frac{r^{-3}}{2} \int_{Q_{r}\left(z_{0}\right)}|\nabla u(z)|^{2} d z<\epsilon_{0} \quad \text { implies } \\
& \frac{\left(\tau_{0} r\right)^{-3}}{2} \int_{Q_{T_{0} r}\left(z_{0}\right)}|\nabla u(z)|^{2} d z \leq \frac{1}{2} \frac{r^{-3}}{2} \int_{Q_{r}\left(z_{0}\right)}|\nabla u(z)|^{2} d z
\end{aligned}
$$

Now we can state our main theorem in this chapter:
THEOREM 2.3 (Main theorem of this chapter). Modified strong evolutional harmonic maps are Hölder continuous on an open set in $Q_{\infty}$ whose compliment has zero 3-dimensional Hausdorff measure with respect to the parabolic metric.

## Preparation

We introduce a glossary of notation, function spaces and various results from functional analysis used only in this chapter.

Abridged Notation. Suppose $X$ be a Banach space. Let $\left\{v_{k}\right\}(k=1,2,3, \ldots)$ be a sequence of functions in $X$ and $v$ a function in $X$.

$$
\begin{aligned}
& v_{k} \stackrel{k \rightarrow \infty}{\longrightarrow} v \\
& v_{k} \stackrel{\text { in }}{ } \stackrel{X \rightarrow \infty}{\longrightarrow} v \\
& \text { in }
\end{aligned} \quad X,
$$

respectively means that $\left\{v_{k}\right\}(k=1,2,3, \ldots)$ weakly and strongly converges to $v$ in $X$.

Let $h$ be a positive number sufficiently small. For a map $u: Q_{\infty} \rightarrow \mathbb{R}^{D}$, various forward and backward difference operators are given by

$$
\begin{aligned}
& \frac{\partial^{+} u}{\partial t}(z)=\frac{1}{h}(u(t+h, x)-u(t, x)), \\
& \nabla^{-} u(z)=\left\{\begin{array}{lll}
1 / h & (u(t, x)-u(t,|x|-h, x /|x|)) & h \leq|x|, \\
1 / h & (u(t, x)-u(t, h-|x|, x /|x|)) & |x|<h,
\end{array}\right.
\end{aligned}
$$

with $x=\left(|x|, \frac{x}{|x|}\right)$.
For a map $f: Q_{\infty} \rightarrow \mathbb{R}^{D}$, we use the following notation:

$$
f_{A} f(z) d z=\frac{1}{\mathcal{L}^{3+1}(A)} \int_{A} f(z) d z, \quad f_{B} f(t, y) d y=\frac{1}{\mathcal{L}^{3}(B)} \int_{B} f(t, y) d y
$$

where $A$ and $B$ is respectively a measurable set on $\mathbb{R}^{1+3}$ and $\mathbb{R}^{3}$.

Preliminaries Lemmas. We review a few technical lemmas which will play a crucial role on the proof of our result. First we state the well-known decomposition lemma on $L^{2}$ - maps (See O.A.Ladyženskaja [74]. ).

Lemma 2.1 (Weyl Decomposition Lemma). Let $\stackrel{\circ}{\boldsymbol{J}}\left(Q_{1} ; \mathbb{R}^{3}\right)$ be a closure of $\{v \in$ $\left.\mathcal{D}\left(Q_{1}\right) ; \operatorname{div} v=0\right\}$ in $L^{2}\left(Q_{1} ; \mathbb{R}^{3}\right)$. Then for a map $f \in L^{2}\left(Q_{1} ; \mathbb{R}^{3}\right)$, there exists a map $g \in \stackrel{\circ}{\boldsymbol{J}}\left(Q_{1} ; \mathbb{R}^{3}\right)$ and a function $h \in L^{2}\left(0,1 ; H^{1,2}\left(B_{1}\right)\right)$, such that $f$ is uniquely decomposed to $f=g+\nabla h$.

To state the second lemma, we first introduce the definition and a few properties on B.M.O and the Hardy space $\mathcal{H}^{1}$. These function spaces are used to control the nonlinear term of our parabolic systems. Let $f$ be a function belonging to $L_{\text {loc }}^{1}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)$. Set

$$
\begin{gathered}
{[f]_{\text {B.M.O }}:=\sup _{x \in \mathbb{R}^{3}, r \in \mathbb{R}_{+}} f_{B_{r}(x)}\left|f-f_{x, r}\right| d y,} \\
\text { with } f_{x, r}=f_{B_{r}(x)} f(y) d y .
\end{gathered}
$$

Then we say that $f$ has bounded mean oscillation (B.M.O) provided $[f]_{\text {B.м.O }}<$ $\infty$. Also $\phi$ is any smooth function with a support in the unit ball and $\int_{\mathbb{R}^{3}} \phi(x) d x$ $=1$. Say that $f$ belongs to the Hardy space $\mathcal{H}^{1}$ if $f^{*} \in L^{1}\left(\mathbb{R}^{3}\right)$ where $f^{*}$ is defined by

$$
f^{*}(x):=\sup _{r>0}\left|f_{B_{r}(x)} f(y) \phi\left(\frac{x-y}{r}\right) d y\right| .
$$

Also, its norm is given by $\|f\|_{\mathcal{H}^{1}}:=\left\|f^{*}\right\|_{L^{1}\left(\mathbb{R}^{3}\right)}$. For the facts above, we refer to Fefferman-Stein [42], Stein [105] and Torchinsky [115]. The well-known result states that $\left(\mathcal{H}^{1}\right)^{\prime}=$ B.M.O and

$$
\begin{equation*}
\left|\int_{\mathbb{R}^{3}} f(y) g(y) d y\right| \leq C_{F S}[f]_{\text {B.M.O }}\|g\|_{\mathcal{H}^{1}} \tag{2.12}
\end{equation*}
$$

holds for any $f \in$ B.M.O and any $g \in \mathcal{H}^{1}$.
We successively introduce the following lemma by Coifman-Lions-Meyer-Sem mes [26].

Lemma 2.2 (Coifman-Lions-Meyer-Semmes [26]). Assume $f \in H^{1,2}\left(\mathbb{R}^{3}\right)$ and $g \in L^{2}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)$ with divg $=0$ in the distribution sense. Then $\langle\nabla f, g\rangle \in \mathcal{H}^{1}$ with the following inequality:

$$
\begin{equation*}
\|\langle\nabla f, g\rangle\|_{\mathcal{H}^{1}} \leq C_{C L M S}\|\nabla f\|_{L^{2}\left(\mathbb{R}^{3}\right)}\|g\|_{L^{2}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)} . \tag{2.13}
\end{equation*}
$$

Next, we prepare the fundamental energy inequality on modified strong evolutional harmonic maps. Let $z_{0}=\left(t_{0}, x_{0}\right)$ be a point in $Q_{\infty}$ and positive numbers $t_{1}, t_{2}$ and $r_{1}, r_{2}$ with $0<t_{0}-t_{2}<t_{0}-t_{1} \leq t_{0}$ and all balls $B_{r_{1}}\left(x_{0}\right)$ and $B_{r_{2}}\left(x_{0}\right)$ satisfying
$B_{r_{1}}\left(x_{0}\right) \subset \subset B_{r_{2}}\left(x_{0}\right) \subset \subset B$. We also choose two cut-off functions $\eta \in \mathcal{D}\left(B_{r_{2}}\left(x_{0}\right)\right)$ and $\chi \in C^{\infty}\left(0, t_{0}\right]$ given by

$$
\begin{gathered}
\eta(|x|)= \begin{cases}1 & \text { in } B_{r_{1}}, \\
0 & \text { outside } B_{r_{2}},\end{cases} \\
0 \leq \eta(|x|) \leq 1, \\
|\nabla \eta(|x|)| \leq 2 /\left(r_{2}-r_{1}\right), \\
\chi(t)= \begin{cases}1 & t_{0}-t_{1}<t \leq t_{0}, \\
0 & t \leq t_{0}-t_{2},\end{cases} \\
0 \leq \chi(t) \leq 1, \quad|d \chi / d t(t)| \leq 2 /\left(t_{2}-t_{1}\right) .
\end{gathered}
$$

Lemma 2.3 (An energy inequality). For modified strong evolutional harmonic map $u$, there holds

$$
\begin{align*}
& \frac{1}{2} \int_{t_{0}-t_{1}}^{t_{0}} d t \int_{B_{r_{1}}}\left|\frac{\partial u}{\partial t}(z)\right|^{2} d x+\frac{1}{2} \int_{B_{r_{1}}}\left|\nabla u\left(t_{0}, x\right)\right|^{2} d x \\
& \quad \leq\left[\frac{8}{\left(r_{2}-r_{1}\right)^{2}}+\frac{1}{\left(t_{2}-t_{1}\right)}\right] \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2} d x . \tag{2.14}
\end{align*}
$$

Finally, we show the monotonicity inequalities for the scaled energies of modified strong evolutional harmonic map.

Lemma 2.4 (A monotonicity formula). The modified strong evolutional harmonic maps $u$ satisfy the following monotonicity formula:

$$
\begin{align*}
& \frac{1}{r_{2}^{2}} \int_{t_{0}-r_{2}^{2}}^{t_{0}} \frac{d t}{r_{1}} \int_{B_{r_{1}\left(x_{0}\right)}}|\nabla u(z)|^{2} d x  \tag{2.15}\\
& \leq \frac{C_{M}}{\left(2 r_{2}\right)^{2}} \int_{t_{0}-\left(2 r_{2}\right)^{2}}^{t_{0}} \frac{d t}{2 r_{2}} \int_{B_{2 r_{2}}\left(x_{0}\right)}|\nabla u(z)|^{2} d x
\end{align*}
$$

holds for any concentric cylinders $\left(t_{0}, t_{0}-r_{2}^{2}\right) \times B_{r_{1}}\left(x_{0}\right) \subset\left(t_{0}, t_{0}-\left(2 r_{2}\right)^{2}\right) \times B_{2 r_{2}}\left(x_{0}\right)$ $\subset \subset Q_{\infty}$ and $C_{M}$ is a positive constant independent of $r_{1}, r_{2}, z_{0}, u$.

## Proof of lemma 2.3

First, fix $0<h$ and recall the weak formula (2.6); We test $\partial^{+} u / \partial t \eta^{2} \chi$ into $\phi$ in (2.6). This is always possible by taking the mollifier of $\partial^{+} u / \partial t$. Then we obtain

$$
\int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \eta^{2}(|x|) \chi(t) d x
$$

$$
\begin{aligned}
& +\int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}\left\langle\frac{\partial^{+}}{\partial t} \nabla u(z), \nabla u(z)\right\rangle \eta^{2}(|x|) \chi(t) d x \\
& +2 \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}\left\langle\nabla u(z), \frac{\partial^{+} u}{\partial t}(z) \nabla \eta(|x|)\right\rangle \eta(|x|) \chi(t) d x \\
& =\int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2}\left\langle u(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \eta^{2}(|x|) \chi(t) d x
\end{aligned}
$$

Here, a non-negativity of the right-hand side is derived from $\langle u(z), u(t+h, x)-$ $u(z)\rangle \leq 0$ because of $|u(z)|=1$, a.e $z \in Q_{\infty}$.

Thus, by applying Schwarz inequality to the 3 rd term on the left-hand side, we infer

$$
\begin{aligned}
& \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \eta^{2}(|x|) \chi(t) d x-\frac{1}{2} \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}\left|\frac{\partial^{+} u}{\partial t}(z)\right|^{2} \eta^{2}(|x|) \chi(t) d x \\
& \quad-\frac{1}{2 h} \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}|\nabla u(t+h, x)-\nabla u(t, x)|^{2} \eta^{2}(|x|) \chi(t) d x \\
& \quad+\frac{1}{2 h} \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}\left[|\nabla u(t+h, x)|^{2}-|\nabla u(t, x)|^{2}\right] \eta^{2}(|x|) \chi(t) d x \\
& \quad \leq 2 \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2}|\nabla \eta(|x|)|^{2} \chi(t) d x
\end{aligned}
$$

which implies

$$
\begin{aligned}
& \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \eta^{2}(|x|) \chi(t) d x \\
& \quad-\frac{1}{2} \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}\left|\frac{\partial^{+} u}{\partial t}(z)\right|^{2} \eta^{2}(|x|) \chi(t) d x \\
& \quad-\frac{1}{2 h} \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}|\nabla u(t+h, x)-\nabla u(t, x)|^{2} \eta^{2}(|x|) \chi(t) d x \\
& \quad+\frac{1}{2 h} \int_{t_{0}}^{t_{0}+h} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2} \eta^{2}(|x|) \chi(t) d x \\
& -\frac{1}{2 h} \int_{t_{0}-t_{2}}^{t_{0}-t_{2}+h} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2} \eta^{2}(|x|) \chi(t) d x \\
& \quad \leq \frac{1}{2} \int_{t_{0}-t_{2}+h}^{t_{0}+h} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2} \eta^{2}(|x|)\left(\frac{\chi(t)-\chi(t-h)}{h}\right) d x
\end{aligned}
$$

$$
+\frac{8}{\left(r_{2}-r_{2}\right)^{2}} \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2} \chi(t) d x
$$

By a few properties of definition on modified strong evolutional harmonic map, i.e. (2.5) and (2.10), we can pass to the limit $h \searrow 0$. Thus we can conclude the claim of this lemma.

## Proof of lemma 2.4

First of all, let us remark that our system (2.6) is invariant under translation $z \rightarrow z-z_{0}$, hence we may shift $z_{0} \rightarrow 0$. For any positive number $\delta$ sufficiently small and any positive number $r<r_{2} / 2$, we define three support functions given by

$$
\begin{aligned}
& \eta_{\delta}(x) \equiv \eta_{\delta}(|x|)= \begin{cases}1 & |x| \leq r, \\
-\frac{1}{\delta}(|x|-(r+\delta)) & r<|x| \leq r+\delta, \\
0 & r+\delta<|x|,\end{cases} \\
& \Psi_{\delta}(x) \equiv \Psi_{\delta}(|x|)= \begin{cases}\int_{|x|}^{r+\delta} t \eta_{\delta}(t) d t & |x|<r+\delta, \\
0 & r+\delta \leq|x|,\end{cases} \\
& \Psi_{0}(x) \equiv \Psi_{0}(|x|)= \begin{cases}\frac{1}{2}\left(r^{2}-|x|^{2}\right) & |x|<r, \\
0 & r \leq|x| .\end{cases}
\end{aligned}
$$

Here note that $\eta_{\delta}(|x|)$ and $\Psi_{\delta}(|x|)$ have the following relations:

$$
\begin{equation*}
\frac{d \Psi_{\delta}}{d \rho}(\rho)+\rho \eta_{\delta}(\rho)=0 \quad \text { in } \quad \rho>0 \tag{2.16}
\end{equation*}
$$

After the preparation above, we start the proof of our monotonicity for the scaled energy. To this end, recall the weak formula: The evolutional evolutional harmonic maps $u$ satisfy

$$
\begin{align*}
\int_{Q_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z), \phi(z)\right\rangle d z+ & \int_{Q_{r_{2}}}\langle\nabla u(z), \nabla \phi(z)\rangle d z  \tag{2.17}\\
& =\int_{Q_{r_{2}}}|\nabla u(z)|^{2}\langle u(z), \phi(z)\rangle d z
\end{align*}
$$

for all maps $\phi \in \mathcal{D}\left(Q_{r_{2}} ; \mathbb{R}^{D}\right)$.
As before, set a positive number $h$ with $0<h<\left|t_{0}-T\right|$. By approximations, we can take $\phi$ as follows:

$$
\phi(z)=\frac{\partial^{+} u}{\partial t}(z) \Psi_{\delta}(|x|)+|x| \nabla^{-} u(z) \eta_{\delta}(|x|) .
$$

We calculate the space gradients of $\phi$ :

$$
\begin{aligned}
\nabla \phi(z) & =\frac{\partial^{+}}{\partial t} \nabla u(z) \Psi_{\delta}(|x|)+\frac{\partial^{+} u}{\partial t}(z) \nabla \Psi_{\delta}(|x|) \\
& +\nabla\left[|x| \nabla^{-} u(z)\right] \eta_{\delta}(|x|)+|x| \nabla^{-} u(z) \nabla \eta_{\delta}(|x|) .
\end{aligned}
$$

By testing $\phi$ chosen above into (2.17), we obtain

$$
\begin{aligned}
& \int_{Q_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \Psi_{\delta}(|x|) d z+\int_{Q_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z),\right| x\left|\nabla^{-} u(z)\right\rangle \eta_{\delta}(|x|) d z \\
& +\int_{Q_{r_{2}}}\left\langle\nabla u(z), \frac{\partial^{+}}{\partial t} \nabla u(z)\right\rangle \Psi_{\delta}(|x|) d z+\int_{Q_{r_{2}}}\left\langle\nabla u(z), \frac{\partial u^{+}}{\partial t}(z) \nabla \Psi_{\delta}(|x|)\right\rangle d z \\
& +\int_{Q_{r_{2}}}\left\langle\nabla u(z), \nabla\left[|x| \nabla^{-} u(z)\right]\right\rangle \eta_{\delta}(|x|) d z \\
& +\int_{Q_{r_{2}}}\langle\nabla u(z),| x\left|\nabla^{-} u(z) \nabla \eta_{\delta}(|x|)\right\rangle d z \\
& =\int_{Q_{r_{2}}}|\nabla u(z)|^{2}\left\langle u(z), \frac{\partial^{+} u}{\partial t}(z) \Psi_{\delta}(|x|)+\right| x\left|\nabla^{-} u(z) \eta_{\delta}(|x|)\right\rangle d z
\end{aligned}
$$

We successively perform the estimates of the 3 rd term and the 5th term on the left-hand side:

$$
\begin{align*}
& \int_{Q_{r_{2}}}\left\langle\nabla u(z), \frac{\partial^{+}}{\partial t} \nabla u(z)\right\rangle \Psi_{\delta}(|x|) d z \\
& =\frac{1}{h} \int_{Q_{r_{2}}}\langle\nabla u(z), \nabla u(t+h, x)-\nabla u(z)\rangle \Psi_{\delta}(|x|) d z \\
& =-\frac{1}{2 h} \int_{Q_{r_{2}}}|\nabla u(t+h, x)-\nabla u(z)|^{2} \Psi_{\delta}(|x|) d z \\
& +\frac{1}{2 h}\left(\int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}}}|\nabla u(t+h, x)|^{2}-|\nabla u(t, x)|^{2}\right) \Psi_{\delta}(|x|) d x \\
& =-\frac{1}{2 h} \int_{Q_{r_{2}}}|\nabla u(t+h, x)-\nabla u(z)|^{2} \Psi_{\delta}(|x|) d z \\
& +\frac{1}{2 h} \int_{0}^{h} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2} \Psi_{\delta}(|x|) d x \\
& -\frac{1}{2 h} \int_{-r_{2}^{2}}^{-r_{2}^{2}+h} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2} \Psi_{\delta}(|x|) d x . \tag{2.19}
\end{align*}
$$

$$
\begin{align*}
& \int_{Q_{r_{2}}}\left\langle\nabla u(z), \nabla\left[|x| \nabla^{-} u(z)\right]\right\rangle \eta_{\delta}(|x|) d z \\
& =\int_{Q_{r_{2}}}\langle\nabla u(z), \nabla| x\left|\nabla^{-} u(z)\right\rangle \eta_{\delta}(|x|) d z \\
& +\int_{Q_{r_{2}}}\langle\nabla u(z),| x\left|\nabla \nabla^{-} u(z)\right\rangle \eta_{\delta}(|x|) d z \\
& =\int_{Q_{r_{2}}}\langle\nabla u(z), \nabla| x\left|\nabla^{-} u(z)\right\rangle \eta_{\delta}(|x|) d z \\
& +\frac{1}{2 h} \int_{-r_{2}^{2}}^{0} \int_{B_{r_{2}} \backslash B_{h}}|x|\left|\nabla u(z)-\nabla u\left(t,|x|-h, \frac{x}{|x|}\right)\right|^{2} \eta_{\delta}(|x|) d z \\
& +\frac{1}{2 h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}} \backslash B_{h}}|x||\nabla u(z)|^{2} \eta_{\delta}(|x|) d x \\
& -\frac{1}{2 h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}} \backslash B_{h}}|x|\left|\nabla u\left(t,|x|-h, \frac{x}{|x|}\right)\right|^{2} \eta_{\delta}(|x|) d x \\
& -\frac{1}{h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{h}}|x|\left\langle\nabla u(z), \nabla u(z)-\nabla u\left(t, h-|x|, \frac{x}{|x|}\right)\right\rangle \eta_{\delta}(|x|) d x \\
& =\int_{Q_{r_{2}}}\langle\nabla u(z), \nabla| x\left|\nabla^{-} u(z)\right\rangle \eta_{\delta}(|x|) d z \\
& +\frac{1}{2 h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}} \backslash B_{h}}|x|\left|\nabla u(z)-\nabla u\left(t,|x|-h, \frac{x}{|x|}\right)\right|^{2} \eta_{\delta}(|x|) d z \\
& -\frac{1}{2} \int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}} \backslash B_{h}}\left|\nabla u\left(t,|x|-h, \frac{x}{|x|}\right)\right|^{2} \nabla^{-}\left(\eta_{\delta}(|x|)|x|^{3}\right) \frac{d x}{|x|^{2}} \\
& +\frac{1}{2 h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}} \backslash B_{r_{2}-h}}|x||\nabla u(z)|^{2} \eta_{\delta}(|x|) d x \\
& -\frac{1}{2 h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{h}}|x||\nabla u(z)|^{2} \eta_{\delta}(|x|) d x \\
& +\frac{1}{h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{h}}|x|\left\langle\nabla u(z), \nabla u(z)-\nabla u\left(t, h-|x|, \frac{x}{|x|}\right)\right\rangle \eta_{\delta}(|x|) d x . \tag{2.20}
\end{align*}
$$

Combining (2.18) with (2.19) and (2.20), we infer

$$
\frac{(r+\delta)^{2}}{2} \int_{Q_{r_{2}}}\left|\frac{\partial u}{\partial t}(z)\right|^{2} \eta_{\delta}(|x|) d z
$$

$$
\begin{align*}
& +\int_{Q_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z), \frac{\partial u^{+}}{\partial t}(z)-\frac{\partial u}{\partial t}(z)\right\rangle \Psi_{\delta}(|x|) d z \\
& -\frac{1}{2 h} \int_{Q_{r_{2}}}|\nabla u(t+h, x)-\nabla u(z)|^{2} \Psi_{\delta}(|x|) d z \\
& +\frac{1}{2 h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}} \backslash B_{h}}|x|\left|\nabla u(z)-\nabla u\left(t,|x|-h, \frac{x}{|x|}\right)\right|^{2} \eta_{\delta}(|x|) d x \\
& +\int_{Q_{r_{2}}}\left(\left\langle\frac{\partial u}{\partial t}(z),\right| x\left|\nabla^{-} u(z)\right\rangle \eta_{\delta}(|x|)+\left\langle\langle x, \nabla\rangle u(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \frac{\Psi_{\delta}^{\prime}(|x|)}{|x|}\right) d z \\
& +\frac{1}{2 h} \int_{0}^{h} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2} \Psi_{\delta}(|x|) d x \\
& -\frac{1}{2 h} \int_{-r_{2}^{2}}^{-r_{2}^{2}+h} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2} \Psi_{\delta}(|x|) d x \\
& +\int_{Q_{r_{2}}}\langle\nabla u(z), \nabla| x\left|\nabla^{-} u(z)\right\rangle \eta_{\delta}(|x|) d z \\
& +\int_{Q_{r_{2}}}\langle\nabla u(z),| x\left|\nabla^{-} u(z) \nabla \eta_{\delta}(|x|)\right\rangle d z \\
& -\frac{1}{2} \int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}} \backslash B_{h}}\left|\nabla u\left(t,|x|-h, \frac{x}{|x|}\right)\right|^{2} \nabla^{-}\left(\eta_{\delta}(|x|)|x|^{3}\right) \frac{d x}{|x|^{2}} \\
& +\frac{1}{2 h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}} \backslash B_{r_{2}-h}}|x||\nabla u(z)|^{2} \eta_{\delta}(|x|) d x \\
& -\frac{1}{2 h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{h}}|x||\nabla u(z)|^{2} \eta_{\delta}(|x|) d x \\
& +\frac{1}{h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{h}}|x|\left\langle\nabla u(z), \nabla u(z)-\nabla u\left(t, h-|x|, \frac{x}{|x|}\right)\right\rangle \eta_{\delta}(|x|) d x \\
& \geq \int_{Q_{r_{2}}}|\nabla u(z)|^{2}\left\langle u(z), \frac{\partial^{+} u}{\partial t}(z) \Psi_{\delta}(|x|)+\right| x\left|\nabla^{-} u(z) \eta_{\delta}(|x|)\right\rangle d z  \tag{2.21}\\
&
\end{align*}
$$

where we used $\Psi_{\delta}(|x|) \leq(r+\delta)^{2} / 2 \cdot \eta_{\delta}(|x|)$ in the 1st term on the left-hand side.

We here estimate the 1st term on the left-side hand in (2.21) as follows: First, recall the weak formula (2.6):

$$
\int_{Q_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z), \phi(z)\right\rangle d z+\int_{Q_{r_{2}}}\langle\nabla u(z), \nabla \phi(z)\rangle d z=\int_{Q_{r_{2}}}|\nabla u(z)|^{2}\langle u(z), \phi(z)\rangle d z
$$

for any mapping $\phi \in \mathcal{D}\left(Q ; \mathbb{R}^{D}\right)$.

As before, by the approximation, we can substitute $\partial^{+} u / \partial t \eta_{\delta}$ for $\phi$ to obtain

$$
\begin{aligned}
& \int_{Q_{r_{2}}}\left|\frac{\partial u}{\partial t}(z)\right|^{2} \eta_{\delta}(|x|) d z+\int_{Q_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z), \frac{\partial^{+} u}{\partial t}(z)-\frac{\partial u}{\partial t}(z)\right\rangle \eta_{\delta}(|x|) d z \\
& +\int_{Q_{r_{2}}}\left\langle\nabla u(z), \frac{\partial^{+}}{\partial t} \nabla u(z)\right\rangle \eta_{\delta}(|x|) d z+\int_{Q_{r_{2}}}\left\langle\langle x, \nabla\rangle u(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \frac{\eta_{\delta}^{\prime}(|x|)}{|x|} d z \\
& =\int_{Q_{r_{2}}}|\nabla u(z)|^{2}\left\langle u(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \eta_{\delta}(|x|) d z .
\end{aligned}
$$

A similar calculation modifies the term above to

$$
\begin{aligned}
& \int_{Q_{r_{2}}}\left|\frac{\partial u}{\partial t}(z)\right|^{2} \eta_{\delta}(|x|) d z=-\int_{Q_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z), \frac{\partial^{+} u}{\partial t}(z)-\frac{\partial u}{\partial t}(z)\right\rangle \eta_{\delta}(|x|) d z \\
& +\frac{1}{2 h} \int_{Q_{r_{2}}}|\nabla u(t+h, x)-\nabla u(z)|^{2} \eta_{\delta}(|x|) d z \\
& -\frac{1}{2 h} \int_{Q_{r_{2}}}\left(|\nabla u(t+h, x)|^{2}-|\nabla u(z)|^{2}\right) \eta_{\delta}(|x|) d z \\
& -\int_{Q_{r_{2}}}\left\langle\langle x, \nabla\rangle u(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \frac{\eta_{\delta}^{\prime}(|x|)}{|x|} d z \\
& +\int_{Q_{r_{2}}}|\nabla u(z)|^{2}\left\langle u(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \eta_{\delta}(|x|) d z \\
& =-\int_{Q_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z), \frac{\partial^{+} u}{\partial t}(z)-\frac{\partial u}{\partial t}(z)\right\rangle \eta_{\delta}(|x|) d z \\
& +\frac{1}{2 h} \int_{Q_{r_{2}}}|\nabla u(t+h, x)-\nabla u(z)|^{2} \eta_{\delta}(|x|) d z \\
& -\frac{1}{2 h} \int_{0}^{h} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2} \eta_{\delta}(|x|) d x \\
& +\frac{1}{2 h} \int_{-r_{2}^{2}}^{-r_{2}^{2}+h} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2} \eta_{\delta}(|x|) d x \\
& -\int_{Q_{r_{2}}}\left\langle\langle x, \nabla\rangle u(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \frac{\eta_{\delta}^{\prime}(|x|)}{|x|} d z \\
& +\int_{Q_{r_{2}}}|\nabla u(z)|^{2}\left\langle u(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \eta_{\delta}(|x|) d z .
\end{aligned}
$$

We substitute (2.22) for (2.21), which leads to

$$
\begin{align*}
& \int_{Q_{r_{2}}}\left\langle\frac{\partial u}{\partial t}(z), \frac{\partial^{+} u}{\partial t}(z)-\frac{\partial u}{\partial t}(z)\right\rangle\left(\Psi_{\delta}(|x|)-\frac{(r+\delta)^{2}}{2} \eta_{\delta}(|x|)\right) d z \\
& -\frac{1}{2 h} \int_{Q_{r_{2}}}|\nabla u(t+h, x)-\nabla u(z)|^{2}\left(\Psi_{\delta}(|x|)-\frac{(r+\delta)^{2}}{2} \eta_{\delta}(|x|)\right) d z \\
& \left.+\frac{1}{2 h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}} \backslash B_{h}}|x| \right\rvert\, \nabla u(z)-\nabla u\left(t,|x|-h,\left.\frac{x}{|x|}\right|^{2} \eta_{\delta}(|x|) d x\right. \\
& +\int_{Q_{r_{2}}}\left(\left\langle\frac{\partial u}{\partial t}(z),\right| x\left|\nabla^{-} u(z)\right\rangle \eta_{\delta}(|x|) d z\right. \\
& \left.\quad+\left\langle\langle x, \nabla\rangle u(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \frac{\Psi_{\delta}^{\prime}(|x|)}{|x|}\right) d z \\
& +\frac{1}{2 h} \int_{0}^{h} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2}\left(\Psi_{\delta}(|x|)-\frac{(r+\delta)^{2}}{2} \eta_{\delta}(|x|)\right) d x \\
& -\frac{1}{2 h} \int_{-r_{2}^{2}}^{-r_{2}^{2}+h} d t \int_{B_{r_{2}}}|\nabla u(z)|^{2}\left(\Psi_{\delta}(|x|)-\frac{(r+\delta)^{2}}{2} \eta_{\delta}(|x|)\right) d x \\
& +\int_{Q_{r_{2}}}\langle\nabla u(z), \nabla| x\left|\nabla^{-} u(z)\right\rangle \eta_{\delta}(|x|) d z \\
& +\int_{Q_{r_{2}}}\langle\nabla u(z),| x\left|\nabla^{-} u(z)\right\rangle \nabla \eta_{\delta}(|x|) d z \\
& -\frac{1}{2} \int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}} \backslash B_{h}} \left\lvert\, \nabla u\left(t,|x|-h, \frac{x}{|x|}\right)^{2} \nabla^{-}\left(\eta_{\delta}(|x|)|x|^{3}\right) \frac{d x}{|x|^{2}}\right. \\
& +\frac{1}{2 h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{r_{2}} \backslash B_{r_{2}-h}}|x||\nabla u(z)|^{2} \eta_{\delta}(|x|) d x \\
& -\frac{(r+\delta)^{2}}{2} \int_{Q_{r_{2}}}\left\langle\langle x, \nabla\rangle u(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle \frac{\eta_{\delta}^{\prime}(|x|)}{|x|} d z \\
& +\frac{1}{h} \int_{-r_{2}^{2}}^{0} d t \int_{B_{h}}|x|\left\langle\nabla u(z), \nabla u(z)-\nabla u\left(t, h-|x|, \frac{x}{|x|}\right)\right\rangle \eta_{\delta}(|x|) d x \\
& \geq \int_{Q_{r_{2}}}|\nabla u(z)|^{2}\left\langle u(z), \frac{\partial^{+} u}{\partial t}(z)\right\rangle\left(\Psi_{\delta}(|x|)-\frac{(r+\delta)^{2}}{2} \eta_{\delta}(|x|)\right) d z \\
& +\int_{Q_{r_{2}}}|\nabla u(z)|^{2}\langle u(z),| x\left|\nabla^{-} u(z)\right\rangle \eta_{\delta}(|x|) d z \geq 0 .  \tag{2.23}\\
& +r_{0}
\end{align*}
$$

A non-negativity on the last 2-terms in (2.23) follows from $\langle u(z), u(t+h, x)-$ $u(z)\rangle \leq 0,\langle u(z), u(z)-u(t, \pm(|x|-h), x /|x|)\rangle \geq 0$, and $\Psi_{\delta}(|x|) \leq(r+\delta)^{2} / 2 \cdot \eta_{\delta}(|x|)$.

We now pass to the limit $h \searrow 0$ in (2.23): By recalling a few properties of definition of modified strong evolutional harmonic map: (2.5), (2.9), (2.10) and by a property of cut-functions, we infer

$$
\begin{aligned}
& +\frac{1}{2} \int_{B_{r_{2}}}|\nabla u(0, x)|^{2}\left(\Psi_{\delta}(|x|)-\frac{(r+\delta)^{2}}{2} \eta_{\delta}(|x|)\right) d x \\
& -\frac{1}{2} \int_{B_{r_{2}}}\left|\nabla u\left(-r_{2}^{2}, x\right)\right|^{2}\left(\Psi_{\delta}(|x|)-\frac{(r+\delta)^{2}}{2} \eta_{\delta}(|x|)\right) d x \\
& +\int_{Q_{r_{2}}}|\nabla u(z)|^{2} \eta_{\delta}(|x|) d z \\
& -\frac{3}{2} \int_{Q_{r_{2}}}|\nabla u(z)|^{2} \eta_{\delta}(|x|) d z-\frac{1}{2} \int_{Q_{r_{2}}}|\nabla u(z)|^{2}|x| \eta_{\delta}^{\prime}(|x|) d z \\
& +\int_{Q_{r_{2}}}|\langle x, \nabla\rangle u(z)|^{2} \frac{\eta_{\delta}^{\prime}(|x|)}{|x|} d z \\
& -\frac{(r+\delta)^{2}}{2} \int_{Q_{r_{2}}}\left\langle\langle x, \nabla\rangle u(z), \frac{\partial u}{\partial t}(z)\right\rangle \frac{\eta_{\delta}^{\prime}(|x|)}{|x|} d z \geq 0 .
\end{aligned}
$$

Finally, taking the limit $\delta \backslash 0$, we conclude

$$
\begin{aligned}
& \frac{1}{2} \int_{B_{r}}|\nabla u(0, x)|^{2}\left(\Psi_{0}(|x|)-\frac{r^{2}}{2}\right) d x-\frac{1}{2} \int_{B_{r}}\left|\nabla u\left(-r_{2}^{2}, x\right)\right|^{2}\left(\Psi_{0}(|x|)-\frac{r^{2}}{2}\right) d x \\
& -\frac{1}{2} \int_{Q_{r, r_{2}}}|\nabla u(z)|^{2} d z+\frac{r}{2} \int_{-r_{2}^{2}}^{0} d t \int_{\partial B_{r}}|\nabla u(z)|^{2} d \mathcal{H}^{2} \\
& +\frac{r}{2} \int_{-r_{2}^{2}}^{0} d t \int_{\partial B_{r}}\left\langle\langle x, \nabla\rangle u(z), \frac{\partial u}{\partial t}(z)\right\rangle d \mathcal{H}^{2}-\frac{1}{r} \int_{-r_{2}^{2}}^{0} d t \int_{\partial B_{r}}|\langle x, \nabla\rangle u(z)|^{2} d \mathcal{H}^{2} \\
& =\frac{1}{2} \int_{B_{r}}|\nabla u(0, x)|^{2}\left(\Psi_{0}(|x|)-\frac{r^{2}}{2}\right) d x-\frac{1}{2} \int_{B_{r}}\left|\nabla u\left(-r_{2}^{2}, x\right)\right|^{2}\left(\Psi_{0}(|x|)-\frac{r^{2}}{2}\right) d x \\
& -\frac{1}{2} \int_{Q_{r, r_{2}}}|\nabla u(z)|^{2} d z+\frac{r}{2} \int_{-r_{2}^{2}}^{0} d t \int_{\partial B_{r}}|\nabla u(z)|^{2} d \mathcal{H}^{2} \\
& +\frac{r^{3}}{16} \int_{-r_{2}^{2}}^{0} d t \int_{\partial B_{r}}\left|\frac{\partial u}{\partial t}(z)\right|^{2} d \mathcal{H}^{2} \\
& -\frac{1}{r} \int_{-r_{2}^{2}}^{0} d t \int_{\partial B_{r}}\left|\langle x, \nabla\rangle u(z)-\frac{r^{2}}{4} \frac{\partial u}{\partial t}(z)\right|^{2} d \mathcal{H}^{2} \geq 0 .
\end{aligned}
$$

Multiplying the above by $r^{-2}$, we deduce

$$
\begin{aligned}
& \frac{1}{2} \int_{B_{r}}\left|\nabla u\left(-r_{2}^{2}, x\right)\right|^{2}\left(-\frac{\Psi_{0}(|x|)}{r^{2}}+\frac{1}{2}\right) d x+\frac{r}{16} \int_{-r_{2}^{2}}^{0} d t \int_{\partial B_{r}}\left|\frac{\partial u}{\partial t}(z)\right|^{2} d \mathcal{H}^{2} \\
& -\frac{1}{2 r^{2}} \int_{Q_{r, r_{2}}}|\nabla u(z)|^{2} d z+\frac{1}{2 r} \int_{-r_{2}^{2}}^{0} d t \int_{\partial B_{r}}|\nabla u(z)|^{2} d \mathcal{H}^{2} \\
& -\frac{1}{r^{3}} \int_{-r_{2}^{2}}^{0} d t \int_{\partial B_{r}}\left|\langle x, \nabla\rangle u(z)-\frac{r^{2}}{4} \frac{\partial u}{\partial t}(z)\right|^{2} d \mathcal{H}^{2} \geq 0
\end{aligned}
$$

We thus show that for a.e. $r>0$ with $0<r<r_{2}$,

$$
\begin{aligned}
& -\frac{1}{2} \int_{B_{r}}\left|\nabla u\left(-r_{2}^{2}, x\right)\right|^{2}\left(\frac{\Psi_{0}(|x|)}{r^{2}}-\frac{1}{2}\right) d x \\
& +\frac{r}{16} \int_{-r_{2}^{2}}^{0} \int_{\partial B_{r}}\left|\frac{\partial u}{\partial t}(z)\right|^{2} d z+\frac{1}{2} \frac{d}{d r}\left(\frac{1}{r} \int_{Q_{r, r_{2}}}|\nabla u(z)|^{2} d z\right)
\end{aligned}
$$

$$
\begin{equation*}
\geq \frac{1}{r^{3}} \int_{-r_{2}^{2}}^{0} d t \int_{\partial B_{r}}\left|\langle x, \nabla\rangle u(z)-\frac{r^{2}}{4} \frac{\partial u}{\partial t}(z)\right|^{2} d \mathcal{H}^{2} \geq 0 \tag{2.24}
\end{equation*}
$$

holds.
We integrate (2.24) from $r_{1}$ to $r_{2}$ with respect to $r$, which obtains

$$
\begin{aligned}
& \frac{r_{2}}{4} \int_{B_{r_{2}}}\left|\nabla u\left(-r_{2}^{2}, x\right)\right|^{2} d x+\frac{r_{2}}{16} \int_{Q_{r_{2}}}\left|\frac{\partial u}{\partial t}(z)\right|^{2} d z \\
& +\frac{1}{2 r_{2}} \int_{Q_{r_{2}}}|\nabla u(z)|^{2} d z \geq \frac{1}{2 r_{1}} \int_{Q_{r_{1}, r_{2}}}|\nabla u(z)|^{2} d z .
\end{aligned}
$$

We apply Lemma 2.3 to the 1st and the the 2nd term on the left-hand side above to complete our proof.

## 2. Proof of theorem

### 2.1. Proof of theorem 2.2

We prove the claim of this theorem by contradiction: Were our statement false, there would exist a sequence of cubes $\left\{Q_{R_{k}}\left(z_{k}\right)\right\}(k=1,2, \ldots)$ in $Q_{\infty}$ such that

$$
\begin{aligned}
& \frac{R_{k}^{-3}}{2} \int_{Q_{R_{k}}\left(z_{k}\right)}|\nabla u(z)|^{2} d z<\frac{1}{k} \quad \text { whereas } \\
& \frac{\left(\tau_{0} R_{k}\right)^{-3}}{2} \int_{Q_{\tau_{0} R_{k}}\left(z_{k}\right)}|\nabla u(z)|^{2} d z
\end{aligned}
$$

$$
\begin{equation*}
>\frac{R_{k}^{-3}}{2} \int_{Q_{R_{k}(z)}}|\nabla u(z)|^{2} d z \quad \text { would hold. } \tag{2.25}
\end{equation*}
$$

We rescale the variables $z=(t, x)$ to the unit cubes $Q_{1}(0) \subset \mathbb{R}^{1+3}$ as follows:

$$
\begin{gathered}
\bar{t}=\frac{1}{R_{k}^{2}}\left(t-t_{k}\right), \quad \bar{x}=\frac{1}{R_{k}}\left(x-x_{k}\right), \quad \bar{z}=(\bar{t}, \bar{x}), \\
\lambda_{k}=\sqrt{\frac{R_{k}^{-3}}{2} \int_{Q_{R_{k}}\left(z_{k}\right)}|\nabla u(z)|^{2} d z,} \\
u_{Q_{6 / 8 R_{k}}\left(z_{k}\right)}=f_{Q_{6 / 8 R_{k}\left(z_{k}\right)}} u\left(z^{\prime}\right) d z^{\prime}, \quad v_{k}(\bar{z})=\frac{1}{\lambda_{k}}\left[u(z)-u_{\left.Q_{6 / 8 R_{k}}\left(z_{k}\right)\right] .}\right.
\end{gathered}
$$

From the change of variables, (2.25) becomes

$$
\begin{equation*}
\lambda_{k}^{2} \leq \frac{1}{k}, \quad \frac{\tau_{0}^{-3}}{2} \int_{Q_{\tau_{0}}(0)}\left|\nabla v_{k}(\bar{z})\right|^{2} d \bar{z}>1 . \tag{2.26}
\end{equation*}
$$

Also, choose $w \in \mathcal{D}\left(Q_{7 / 8}(0) ; \mathbb{R}^{D}\right)$ and set

$$
w_{k}(z)=w\left(\frac{t-t_{k}}{R_{k}^{2}}, \frac{x-x_{k}}{R_{k}}\right) \in \mathcal{D}\left(Q_{7 R_{k} / 8}\left(z_{k}\right) ; \mathbb{R}^{D}\right)
$$

We substitute $w_{k}$ for $\phi$ in (2.6), which gives

$$
\begin{align*}
& \int_{Q_{7 / 8 R_{k}}\left(z_{k}\right)}\left\langle\frac{\partial u}{\partial t}(z), w_{k}(z)\right\rangle d z+\int_{Q_{7 / 8 R_{k}}\left(z_{k}\right)}\left\langle\nabla u(z), \nabla w_{k}(z)\right\rangle d z \\
& =\int_{Q_{7 / 8 R_{k}}\left(z_{k}\right)}|\nabla u(z)|^{2}\left\langle u(z), w_{k}(z)\right\rangle d z . \tag{2.27}
\end{align*}
$$

From definition of $v_{k}: u(z)=\lambda_{k} v_{k}(\bar{z})+u_{Q_{6 / 8 R_{k}}\left(z_{k}\right)}$, we find that $v_{k}$ satisfies

$$
\begin{align*}
& \int_{Q_{7 / 8}(0)}\left\langle\frac{\partial v_{k}}{\partial \bar{t}}(\bar{z}), w(\bar{z})\right\rangle d \bar{z}+\int_{Q_{7 / 8}(0)}\left\langle\nabla v_{k}(\bar{z}), \nabla w(\bar{z})\right\rangle d \bar{z} \\
& =\lambda_{k} \int_{Q_{7 / 8}(0)}\left|\nabla v_{k}(\bar{z})\right|^{2}\langle u(\bar{z}), w(\bar{z})\rangle d \bar{z} . \tag{2.28}
\end{align*}
$$

From lemma 2.3, we obtain

$$
\begin{align*}
& \frac{1}{2} \int_{Q_{6 / 8 R_{k}}\left(z_{k}\right)}\left|\frac{\partial u}{\partial t}(z)\right|^{2} d z+\frac{1}{2} \int_{B_{6 / 8 R_{k}}\left(x_{k}\right)}|\nabla u(t, x)|^{2} d x \\
& \leq C \int_{Q_{7 / 8 R_{k}}\left(z_{k}\right)}|\nabla u(z)|^{2} d z \tag{2.29}
\end{align*}
$$

for almost all $t$ with $t_{k}-\left(6 / 8 R_{k}\right)^{2}<t \leq t_{k}$.
By transferring the variables $z=(t, x)$ to $\bar{z}=(\bar{t}, \bar{x})$, we find that the above (2.29) becomes

$$
\begin{align*}
& \frac{1}{2} \int_{Q_{6 / 8}(0)}\left|\frac{\partial v_{k}}{\partial \bar{t}}(\bar{z})\right|^{2} d \bar{z}+\frac{1}{2} \int_{B_{6 / 8}(0)}\left|\nabla v_{k}(\bar{t}, \bar{x})\right|^{2} d \bar{x}  \tag{2.30}\\
& \leq C \int_{Q_{7 / 8}(0)}\left|\nabla v_{k}(\bar{z})\right|^{2} d \bar{z} \leq C,
\end{align*}
$$

with a.e $\bar{t}$ in $\left(-(6 / 8)^{2}, 0\right]$.
Thus, there exists a subsequence $\left\{v_{k(i)}\right\}$ of $\left\{v_{k}\right\} \in V\left(Q_{6 / 8}(0) ; \mathbb{R}^{D}\right)(i=1,2, \ldots)$ and a mapping $v \in V\left(Q_{6 / 8}(0) ; \mathbb{R}^{D}\right)$ such that

$$
\left\{\begin{array}{lll}
\nabla v_{k(i)}(\bar{z}) & \stackrel{k \rightarrow \infty}{-} \nabla v(\bar{z}) & \text { in } L^{2}\left(Q_{6 / 8}(0) ; \mathbb{R}^{D}\right)  \tag{2.31}\\
\frac{\partial v_{k(i)}}{\partial t}(\bar{z}) & \stackrel{k \rightarrow \infty}{-} \frac{\partial v}{\partial t}(\bar{z}) & \text { in } L^{2}\left(Q_{6 / 8}(0) ; \mathbb{R}^{D}\right)
\end{array}\right.
$$

In view of these facts $(2.28),(2.30)$ and (2.31), we deduce that

$$
\int_{Q_{6 / 8}(0)}\left\langle\frac{\partial v}{\partial \bar{t}}(\bar{z}), w(\bar{z})\right\rangle d \bar{z}+\int_{Q_{6 / 8}(0)}\langle\nabla v(\bar{z}), \nabla w(\bar{z})\rangle d \bar{z}=0
$$

holds for all $w \in \mathcal{D}\left(Q_{6 / 8}(0) ; \mathbb{R}^{D}\right)$. This shows that the map above $v$ is the solution of the linear heat equations, i.e. $v$ satisfies

$$
\begin{equation*}
\frac{\partial v}{\partial t}(\bar{z})-\Delta v(\bar{z})=0 \quad \text { locally } \quad \text { in } \quad Q_{6 / 8}(0) \tag{2.32}
\end{equation*}
$$

Thus Lemma 1.3 implies that for any positive number $\tau_{0}<1 / 2$,

$$
\|\nabla v\|_{L^{\infty}\left(Q_{\tau_{0}}(0)\right)} \leq C_{H}\left[f_{Q_{6 / 8}(0)}|\nabla v(\bar{z})|^{2} d \bar{z}\right]^{1 / 2}
$$

holds where $C_{H}$ is a universal positive constant.
Now, we assume

$$
\begin{equation*}
\nabla v_{k}(\bar{z}) \xrightarrow{k \rightarrow \infty} \nabla v(\bar{z}) \quad \text { in } \quad L^{2}\left(Q_{1 / 2}(0) ; \mathbb{R}^{3 \times D}\right) . \tag{2.33}
\end{equation*}
$$

Thus, from assumption (2.26), we deduce that

$$
\begin{gathered}
\frac{1}{2}<\frac{1}{2 \tau_{0}^{3}} \int_{Q_{\tau_{0}}(0)}|\nabla v(\bar{z})|^{2} d \bar{z} \quad \text { implies } \\
\frac{1}{2}<\frac{1}{2 \tau_{0}^{3}} \int_{Q_{\tau_{0}}(0)}|\nabla v(\bar{z})|^{2} d \bar{z} \leq \frac{1}{2 \tau_{0}^{3}}\left|Q_{\tau_{0}}(0)\right|| | \nabla v \|_{L^{\infty}\left(Q_{\tau_{0}}(0)\right)}^{2} \\
\leq C_{H}^{2} \frac{\left|Q_{1}\right|}{\left|Q_{6 / 8}\right|} \frac{\tau_{0}^{2}}{2} \int_{Q_{6 / 8}(0)}|\nabla v(\bar{z})|^{2} d \bar{z}<\frac{1}{4},
\end{gathered}
$$

as long as $0<\tau_{0}<\frac{1}{2}\left(\frac{4}{3}\right)^{5 / 2} \frac{1}{C_{H}}$.
Since $\tau_{0}$ is any positive number with $\tau_{0}<1 / 2$, then the above choice of $\tau_{0}$ gives a contradiction.

### 2.2. Proof of theorem 2.3

Since $r^{-3} \int_{Q_{r}\left(z_{0}\right)}|\nabla u(z)|^{2} d z$ is continuous function with respect to $z_{0}$, if $z_{0} \in Q / \Sigma_{u}$, there exists an open cube $Q_{r_{0}}\left(z_{0}\right)$ with $Q_{2 r_{0}}\left(z_{0}\right) \subset \subset Q_{\infty}$ such that for any $z \in$ $Q_{r_{0}}\left(z_{0}\right)$,

$$
r_{0}^{-3} \int_{Q_{r_{0}}(z)}|\nabla u(\bar{z})|^{2} d \bar{z} \leq \epsilon_{0} .
$$

By using (2.11), a standard iteration technique implies that

$$
\int_{Q_{r}(z)}|\nabla u(\bar{z})|^{2} d \bar{z} \leq \frac{1}{\tau_{0}^{3}}\left(\frac{r}{r_{0}}\right)^{3+\log 2 / \log \left(1 / \tau_{0}\right)} \int_{Q_{r_{0}}(z)}|\nabla u(\bar{z})|^{2} d \bar{z}
$$

holds for any $r<r_{0} / 2$.
By using Lemma 2.3, we then infer

$$
\begin{aligned}
& r^{2} \int_{Q_{r / 2}(z)}\left|\frac{\partial u}{\partial t}(\bar{z})\right|^{2} d \bar{z}+\int_{Q_{r / 2}(z)}|\nabla u(\bar{z})|^{2} d \bar{z} \\
& \leq C\left(\frac{r}{r_{0}}\right)^{3+\log 2 / \log \left(1 / \tau_{0}\right)} \int_{Q_{2 r_{0}\left(z_{0}\right)}}|\nabla u(\bar{z})|^{2} d \bar{z}
\end{aligned}
$$

Then it consequently follows from Campanato $[\mathbf{1 5}]$ that $u \in C^{\alpha}\left(Q / \Sigma_{u} ; \mathbb{R}^{3}\right)$ with $\alpha=1 / 2 \log 2 / \log \left(1 / \tau_{0}\right)$.

## 3. Compactness of the blow-up sequence

The reminder of this paper is to show the compactness of a blow-up sequence. This compactness is our main technical result. To this end, we first prepare the inequality of Poincaré type:

Lemma 2.5. In any $\bar{t}$ in $\left(-(6 / 8)^{2}, 0\right]$, $v_{k}$ satisfies

$$
\begin{equation*}
\left\|v_{k}(\bar{t}, \cdot)\right\|_{L^{2}\left(B_{6 / 8}(0)\right)} \leq C, \tag{2.34}
\end{equation*}
$$

where $C$ is a positive constant depending only on $D$.
Proof. Recall definition of $v_{k}$ :

$$
\begin{align*}
& \left\|v_{k}(\bar{t}, \cdot)\right\|_{L^{2}\left(B_{6 / 8(0)}\right)} \\
& \quad=\frac{1}{\lambda_{k}}\left[\int_{B_{6 / 8}(0)}\left|u(\bar{t}, \bar{x})-\int_{Q_{6 / 8}(0)} u(\bar{s}, \bar{y}) d \bar{s} d \bar{y}\right|^{2} d \bar{x}\right]^{1 / 2} \\
& \leq \frac{1}{\lambda_{k}}\left[\int_{B_{6 / 8}(0)}\left|u(\bar{t}, \bar{x})-\int_{B_{6 / 8}(0)} u(\bar{t}, \bar{y}) d \bar{y}\right|^{2} d \bar{x}\right]^{1 / 2} \\
& + \\
& \frac{1}{\lambda_{k}}\left[\int_{B_{6 / 8}(0)}\left|f_{Q_{6 / 8}(0)}(u(\bar{t}, \bar{y})-u(\bar{s}, \bar{y})) d \bar{s} d \bar{y}\right|^{2} d \bar{x}\right]^{1 / 2}  \tag{2.35}\\
& \leq C| | \nabla v_{k}(\bar{t}, \cdot)\left\|_{L^{2}\left(B_{6 / 8}(0)\right)}+C\right\| \partial_{t} v_{k} \|_{L^{2}\left(Q_{6 / 8}(0)\right)} \leq C,
\end{align*}
$$

where we used Lemma 2.3 and $1 / 2 \int_{Q_{1}}\left|\nabla v_{k}\right|^{2} d \bar{z}=1$.
Now we are in the position to state main lemma:
Lemma 2.6. Let $v_{k}(k=1,2, \ldots)$ and $v$ be maps appearing in the previous section.

$$
\text { Then } \quad \nabla v_{k}(\bar{z}) \xrightarrow{k \rightarrow \infty} \nabla v(\bar{z}) \quad \text { in } \quad L^{2}\left(Q_{1 / 2}(0) ; \mathbb{R}^{3 \times D}\right) \text {. }
$$

Proof. To prove the strong convergence of $\left\{\nabla v_{k}\right\}(k=1,2, \ldots)$, first recall (2.28), (2.32):

$$
\begin{align*}
& \int_{Q_{6 / 8}(0)}\left\langle\frac{\partial v_{k}}{\partial \bar{t}}(\bar{z}), w(\bar{z})\right\rangle d \bar{z}+\int_{Q_{6 / 8}(0)}\left\langle\nabla v_{k}(\bar{z}), \nabla w(\bar{z})\right\rangle d \bar{z}  \tag{2.36}\\
& =\lambda_{k} \int_{Q_{6 / 8}(0)}\left|\nabla v_{k}(\bar{z})\right|^{2}\langle u(\bar{z}), w(\bar{z})\rangle d \bar{z},
\end{align*}
$$

and

$$
\begin{equation*}
\int_{Q_{6 / 8}(0)}\left\langle\frac{\partial v}{\partial t}(\bar{z}), w(\bar{z})\right\rangle d \bar{z}+\int_{Q_{6 / 8}(0)}\langle\nabla v(\bar{z}), \nabla w(\bar{z})\rangle d \bar{z}=0, \tag{2.37}
\end{equation*}
$$

where $w$ is any mapping of $\mathcal{D}\left(Q_{6 / 8}(0) ; \mathbb{R}^{D}\right)$.
After subtracted (2.37) from (2.36), we have

$$
\begin{align*}
& \int_{Q_{6 / 8}(0)}\left\langle\frac{\partial}{\partial \bar{t}}\left(v_{k}(\bar{z})-v(\bar{z})\right), w(\bar{z})\right\rangle d \bar{z} \\
& +\int_{Q_{6 / 8}(0)}\left\langle\nabla\left(v_{k}(\bar{z})-v(\bar{z})\right), \nabla w(\bar{z})\right\rangle d \bar{z}  \tag{2.38}\\
& =\lambda_{k} \int_{Q_{6 / 8}(0)}\left|\nabla v_{k}(\bar{z})\right|^{2}\langle u(\bar{z}), w(\bar{z})\rangle d \bar{z} .
\end{align*}
$$

By the approximation, the same identity obtains for $w \in L^{2}\left(-(6 / 8)^{2}, 0 ; \stackrel{\circ}{H^{1,2}}\right.$ $\left.\left(B_{6 / 8}(0) ; \mathbb{R}^{D}\right)\right) \cap L^{\infty}\left(Q_{6 / 8}(0) ; \mathbb{R}^{D}\right)$. Fix $\phi \in C^{\infty}\left(-(6 / 8)^{2}, 0 ; \quad C^{\infty}\left(B_{6 / 8}(0) ; \mathbb{R}_{+}\right)\right)$ satisfying

$$
\begin{aligned}
& \phi(\bar{z})= \begin{cases}1 & \text { in } \quad Q_{4 / 8}(0), \\
0 & \text { outside } \mathbb{R}^{1+3} / Q_{5 / 8}(0),\end{cases} \\
& 0 \leq \phi(\bar{z}) \leq 1,|\nabla \phi(\bar{z})| \leq 16, \\
& \left|\nabla^{2} \phi(\bar{z})\right| \leq 128,\left|\partial_{t} \phi(\bar{z})\right| \leq 128 .
\end{aligned}
$$

Substituting $\left(v_{k}-v\right) \phi^{3}$ for $w$ in the identity (2.38), we obtain

$$
\begin{aligned}
& \left.\frac{1}{2} \int_{B_{6 / 8}(0)}\left|v_{k}(\bar{z})-v(\bar{z})\right|^{2} \phi^{3}(\bar{z}) d \bar{x}\right|_{t=-(6 / 8)^{2}} ^{0} \\
& \quad-\frac{3}{2} \int_{Q_{6 / 8}(0)}\left|v_{k}(\bar{z})-v(\bar{z})\right|^{2} \phi^{2}(\bar{z}) \frac{\partial \phi}{\partial \bar{t}}(\bar{z}) d \bar{z} \\
& \quad+\int_{Q_{6 / 8}(0)}\left|\nabla\left(v_{k}(\bar{z})-v(\bar{z})\right)\right|^{2} \phi^{3}(\bar{z}) d \bar{z} \\
& \quad+3 \int_{Q_{6 / 8}(0)}\left\langle\nabla\left(v_{k}(\bar{z})-v(\bar{z})\right) \phi^{3 / 2}(\bar{z}),\left(v_{k}(\bar{z})-v(\bar{z})\right) \phi^{1 / 2}(\bar{z}) \nabla \phi(\bar{z})\right\rangle d \bar{z} \\
& \quad=\lambda_{k} \int_{Q_{6 / 8}(0)}\left|\nabla v_{k}(\bar{z})\right|^{2}\left\langle u(\bar{z}),\left(v_{k}(\bar{z})-v(\bar{z})\right) \phi^{3}(\bar{z})\right\rangle d \bar{z} .
\end{aligned}
$$

We here apply Schwartz inequality to the 4th term on the left-hand side above and invoke Hélein's trick (See Hélein [64].) on the right-hand side; We obtain

$$
\begin{align*}
& \frac{1}{2} \int_{Q_{6 / 8}(0)}\left|\nabla\left(v_{k}(\bar{z})-v(\bar{z})\right)\right|^{2} \phi^{3}(\bar{z}) d \bar{z} \\
& \leq \frac{1}{2} \int_{Q_{6 / 8}(0)}\left|v_{k}(\bar{z})-v(\bar{z})\right|^{2}\left(3 \phi^{2}(\bar{z}) \frac{\partial \phi}{\partial \bar{t}}(\bar{z})+9 \phi(\bar{z})|\nabla \phi(\bar{z})|^{2}\right) d \bar{z} \\
& +\lambda_{k} \int_{Q_{6 / 8}(0)}\left|\nabla v_{k}(\bar{z})\right|^{2}\left\langle u(\bar{z}),\left(v_{k}(\bar{z})-v(\bar{z})\right) \phi^{3}(\bar{z})\right\rangle d \bar{z} \\
& =\frac{1}{2} \int_{Q_{6 / 8}(0)}\left|v_{k}(\bar{z})-v(\bar{z})\right|^{2}\left(3 \phi^{2}(\bar{z}) \frac{\partial \phi}{\partial \bar{t}}(\bar{z})+9 \phi(\bar{z})|\nabla \phi(\bar{z})|^{2}\right) d \bar{z} \\
& -\lambda_{k} \sum_{i, j=1}^{D} \int_{Q_{6 / 8}(0)}\left\langle v_{k}^{i}(\bar{z}) \nabla \phi(\bar{z}),\left(v_{k}^{j}(\bar{z})-v^{j}(\bar{z})\right) \phi(\bar{z})\right. \\
& \left.\quad \times \phi(\bar{z})\left(u^{j}(\bar{z}) \nabla v_{k}^{i}(\bar{z})-u^{i}(\bar{z}) \nabla v_{k}^{j}(\bar{z})\right)\right\rangle d \bar{z} \\
& +\lambda_{k} \sum_{i, j=1}^{D} \int_{Q_{6 / 8}(0)}\left\langle\nabla\left(v_{k}^{i}(\bar{z}) \phi(\bar{z})\right),\left(v_{k}^{j}(\bar{z})-v^{j}(\bar{z})\right) \phi(\bar{z})\right. \\
& \left.\quad \times \phi(\bar{z})\left(u^{j}(\bar{z}) \nabla v_{k}^{i}(\bar{z})-u^{i}(\bar{z}) \nabla v_{k}^{j}(\bar{z})\right)\right\rangle d \bar{z} . \tag{2.39}
\end{align*}
$$

We proceed to estimate (2.39). For this purpose, we implement Lemma 2.1 to the 3rd term on the right-hand side in (2.39): When we set $\mathbb{B}_{k}^{i, j}=\left(B_{\alpha, k}^{i, j}\right)$ $(\alpha=1,2,3)$ as $B_{\alpha, k}^{i, j}(\bar{z})=\left(u^{j} \nabla_{\alpha} v_{k}^{i}-u^{i} \nabla_{\alpha} v_{k}^{j}\right) \phi$, there exists a map $\mathbb{C}_{k}^{i, j} \in$ $L^{2}\left(Q_{6 / 8}(0) ; \mathbb{R}^{3}\right)$ and a function $\phi_{k}^{i, j} \in L^{2}\left(-(6 / 8)^{2}, 0 ; \stackrel{\circ}{H}^{1,2}\left(B_{6 / 8}(0) ; \mathbb{R}^{3}\right)\right)$ such that

$$
\begin{aligned}
& \mathbb{B}_{k}^{i, j}=\mathbb{C}_{k}^{i, j}+\nabla \phi_{k}^{i, j} \quad \text { in } Q_{6 / 8}(0), \\
& \text { with } \quad \mathbb{C}_{k}^{i, j} \in \boldsymbol{J} \text {, } \\
& \left\{\begin{array}{llll}
\triangle \phi_{k}^{i, j} & =\operatorname{div} \mathbb{B}_{k}^{i, j} \quad \text { in } \quad L^{2}\left(Q_{6 / 8}(0)\right), \\
\partial \phi_{k}^{i, j} / \partial n & =0 & \text { on } & \partial B_{6 / 8}(0), \\
\text { a.et. }
\end{array}\right.
\end{aligned}
$$

Here we must remark that $\operatorname{div} \mathbb{B}_{k}^{i, j}$ does belong to $L^{2}\left(Q_{6 / 8}(0)\right)$. Indeed, since $v_{k}$ satisfies (2.36),

$$
\begin{aligned}
\operatorname{div} \mathbb{B}_{k}^{i, j} & =\sum_{\alpha=1}^{3} \nabla_{\alpha}\left[\left(u^{j} \nabla_{\alpha} v_{k}^{i}-u^{i} \nabla_{\alpha} v_{k}^{j}\right) \phi\right] \\
& =\left(u^{j} \triangle v_{k}^{i}-u^{i} \triangle v_{k}^{j}\right) \phi+\left\langle u^{j} \nabla v_{k}^{i}-u^{i} \nabla v_{k}^{j}, \nabla \phi\right\rangle \\
& =\left(u^{j} \partial_{\bar{t}} v_{k}^{i}-u^{i} \partial_{\bar{t}} v_{k}^{j}\right) \phi+\left\langle u^{j} \nabla v_{k}^{i}-u^{i} \nabla v_{k}^{j}, \nabla \phi\right\rangle\left(:=D_{k}^{i, j}\right) \quad \text { in } \quad \mathcal{D}^{\prime}\left(Q_{6 / 8}(0)\right)
\end{aligned}
$$

holds. In the following, we write $\phi_{k}^{i, j}=\triangle^{-1} D_{k}^{i, j}$.

Thus, (2.39) becomes

$$
\begin{aligned}
& \frac{1}{2} \int_{Q_{6 / 8}(0)}\left|\nabla\left(v_{k}(\bar{z})-v(\bar{z})\right)\right|^{2} \phi^{3}(\bar{z}) d \bar{z} \\
& \leq \frac{1}{2} \int_{Q_{6 / 8}(0)}\left|v_{k}(\bar{z})-v(\bar{z})\right|^{2}\left(3 \phi^{2}(\bar{z}) \frac{\partial \phi}{\partial t}(\bar{z})+9 \phi(\bar{z})|\nabla \phi(\bar{z})|^{2}\right) d \bar{z} \\
& -\lambda_{k} \sum_{i, j=1}^{D} \int_{Q_{6 / 8}(0)}\left\langle v_{k}^{i}(\bar{z}) \nabla \phi(\bar{z}),\left(v_{k}^{j}(\bar{z})-v^{j}(\bar{z})\right) \phi(\bar{z}) \mathbb{B}_{k}^{i, j}(\bar{z})\right\rangle d \bar{z} \\
& +\lambda_{k} \sum_{i, j=1}^{D} \int_{Q_{6 / 8}(0)}\left\langle\nabla\left(v_{k}^{i}(\bar{z}) \phi(\bar{z})\right),\left(v_{k}^{j}(\bar{z})-v^{j}(\bar{z})\right) \phi(\bar{z}) \mathbb{C}_{k}^{i, j}(\bar{z})\right\rangle d \bar{z} \\
& +\lambda_{k} \sum_{i, j=1}^{D} \int_{-(6 / 8)^{2}}^{0} d \bar{t} \int_{\mathbb{R}^{3}}\left\langle\nabla\left(v_{k}^{i}(\bar{z}) \phi(\bar{z})\right),\left(v_{k}^{j}(\bar{z})-v^{j}(\bar{z})\right) \phi(\bar{z}) \nabla\left(\triangle^{-1} D_{k}^{i, j}(\bar{z})\right)\right\rangle d \bar{x} \\
& =\left(R_{1}^{k}\right)+\left(R_{2}^{k}\right)+\left(R_{3}^{k}\right)+\left(R_{4}^{k}\right) .
\end{aligned}
$$

From now we begin with estimating $\left(R_{j}^{k}\right),(j=1,2,3,4)$. First, since $\left\|\nabla v_{k}\right\|_{L^{2}}$ ${ }_{\left(Q_{6 / 8}(0)\right)}$ and $\left\|\partial v_{k} / \partial \bar{t}\right\|_{L^{2}\left(Q_{6 / 8}(0)\right)}$ are uniform bounded with respect to $k$, RellichKondrachov theorem reads

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left(R_{1}^{k}\right)=0 \tag{2.40}
\end{equation*}
$$

Next, we perform the estimates of $\left(R_{2}^{k}\right)$ as follows: By using Hölder inequality and Sobolev imbedding theorem $\stackrel{\circ}{H}^{1,2}\left(Q_{6 / 8}(0)\right) \hookrightarrow L^{4}\left(Q_{6 / 8}(0)\right)$, we infer

$$
\begin{aligned}
&\left(R_{2}^{k}\right) \leq \lambda_{k} \sum_{i, j=1}^{D}\left(\int_{Q_{6 / 8}(0)}\left|v_{k}^{i}(\bar{z})\right|^{4}|\nabla \phi(\bar{z})|^{4} d \bar{z}\right)^{1 / 4} \\
& \times\left(\int_{Q_{6 / 8}(0)}\left|v_{k}^{j}(\bar{z})-v_{j}(\bar{z})\right|^{4} d \bar{z}\right)^{1 / 4}\left(\int_{Q_{6 / 8}(0)}\left|\mathbb{B}_{k}^{i, j}(\bar{z})\right|^{2} d \bar{z}\right)^{1 / 2} \\
&=C \lambda_{k}\left\|v_{k}\right\|_{L^{4}\left(Q_{6 / 8}(0)\right)} \\
& \times\left(\left\|v_{k}\right\|_{L^{4}\left(Q_{6 / 8}(0)\right)}+\liminf _{k \rightarrow \infty}\left\|v_{k}\right\|_{\left.L^{4}\left(Q_{6 / 8}(0)\right)\right)}\right)\left\|\nabla v_{k}\right\|_{L^{2}\left(Q_{6 / 8}(0)\right)} \\
& \leq C \lambda_{k}\left(\left\|\nabla v_{k}\right\|_{L^{2}\left(Q_{6 / 8}(0)\right)}+\left\|\partial_{\bar{t}} v_{k}\right\| \|_{L^{2}\left(Q_{6 / 8}(0)\right)}\right) \\
& \quad \times\left[\left(\left\|\nabla v_{k}\right\|_{L^{2}\left(Q_{6 / 8}(0)\right)}+\liminf _{k \rightarrow \infty}\left\|\nabla v_{k}\right\|_{L^{2}\left(Q_{6 / 8}(0)\right)}\right)\right.
\end{aligned}
$$

$$
\begin{align*}
& \left.+\left(\left\|\partial_{\bar{t}} v_{k}\right\|_{L^{2}\left(Q_{6 / 8}(0)\right)}+\liminf _{k \rightarrow \infty}\left\|\partial_{\bar{t}} v_{k}\right\|_{L^{2}\left(Q_{6 / 8}(0)\right)}\right)\right] \\
& \times\left\|\nabla v_{k}\right\|_{L^{2}\left(Q_{6 / 8}(0)\right)} \leq C \lambda_{k} . \tag{2.41}
\end{align*}
$$

The last evaluations directly follow from Lemma 2.3, definition of $v_{k}$ and $1 / 2 \int_{Q_{1}(0)}\left|\nabla v_{k}\right|^{2} \quad d z=1$.

We next perform the estimates of $\left(R_{3}^{k}\right)$ and $\left(R_{4}^{k}\right)(k=1,2, \ldots)$ : We apply Lemma 2.2 to $\nabla v_{k}^{i} \phi \mathbb{C}_{k}^{i, j}$. This is possible because of $v_{k}^{i} \phi \in H^{1,2}\left(B_{6 / 8}(0)\right)$ for a.e $t$ and $\mathbb{C}_{k}^{i, j} \in L^{2}\left(B_{6 / 8}(0)\right)$ with $\operatorname{div} \mathbb{C}_{k}^{i, j}=0$ in $\mathcal{D}^{\prime}\left(B_{6 / 8}(0) ; \mathbb{R}^{3}\right)$ for a.e $t$. Also note that $\phi$ vanishes outside $B_{5 / 8}(0)$, and $v, v_{k}$ belong to $L^{\infty}\left(Q_{5 / 8}(0) ; \mathbb{R}^{D}\right)$. Then by using $\left(\mathcal{H}^{1}\right)^{\prime}=$ B.M.O, i.e. (2.12), we infer the following inequality:

$$
\begin{aligned}
& \left(R_{3}^{k}\right):=\lambda_{k} \sum_{i, j=1}^{D} \int_{-(6 / 8)^{2}}^{0} d \bar{t} \int_{\mathbb{R}^{3}}\left\langle\nabla\left(v_{k}^{i}(\bar{z}) \phi(\bar{z})\right),\left(v_{k}^{j}(\bar{z})-v^{j}(\bar{z})\right) \phi(\bar{z}) \mathbb{C}_{k}^{i, j}(\bar{z})\right\rangle d \bar{x} \\
& \leq \lambda_{k} C_{\mathrm{FS}} \sum_{i, j=1}^{D} \int_{-(6 / 8)^{2}}^{0}\left\|\nabla\left(v_{k}^{i} \phi\right) \mathbb{C}_{k}^{i, j}\right\|_{\mathcal{H}^{1}}\left[\left(v_{k}^{j}-v^{j}\right) \phi\right]_{\text {B.M.O }} d \bar{t} . \\
& \leq \lambda_{k} C_{\mathrm{FS}} C_{\mathrm{CLMS}} \sum_{i, j=1}^{D} \int_{-(6 / 8)^{2}}^{0}\left\|\nabla\left(v_{k}^{i} \phi\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}\left\|\mathbb{B}_{k}^{i, j}-\nabla\left(\triangle^{-1} D_{k}^{i, j}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)} \\
& \times\left[\left(v_{k}^{j}-v^{j}\right) \phi\right]_{\text {B.м.O }} d \bar{t} \\
& \leq 2 \lambda_{k} C_{\mathrm{FS}} C_{\mathrm{CLMS}} \underset{-(6 / 8)^{2}<t \leq 0}{\operatorname{ess} \cdot \sup ^{2}}\left\|\nabla\left(v_{k} \phi\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)} \\
& \times \sum_{i, j=1}^{D}\left(\int_{-(6 / 8)^{2}}^{0}\left(\left\|B_{k}^{i, j}\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}^{2}+\left\|\nabla\left(\triangle^{-1} D_{k}^{i, j}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}^{2}\right) d \bar{t}\right)^{1 / 2} \\
& \times\left(\int_{-(6 / 8)^{2}}^{0}\left[\left(v_{k}-v\right) \phi\right]_{\text {B.M.O }}^{2} d \bar{t}\right)^{1 / 2} \\
& =2 \lambda_{k} C_{\mathrm{FS}} C_{\mathrm{CLMS}} \times\left(R_{3.1}^{k}\right) \times\left(R_{3.2}^{k}\right) \times\left(R_{3.3}^{k}\right) .
\end{aligned}
$$

First, by using Lemma 2.3 and lemma 2.5, we obtain

Next, we estimate $\left(R_{3.2}^{k}\right)$ : We invoke a continuity of $\nabla \triangle^{-1}$ from $L^{2}$ to $L^{2}$. Then we obtain

$$
\left(R_{3.2}^{k}\right)=\sum_{i, j=1}^{D}\left(\int_{-(6 / 8)^{2}}^{0} d \bar{t} \int_{B_{6 / 8}(0)}\left|u^{i}(\bar{z}) \nabla v_{k}^{j}(\bar{z})-u^{j}(\bar{z}) \nabla v_{k}^{i}(\bar{z})\right|^{2} d \bar{x}\right.
$$

$$
\begin{aligned}
& \left.+\int_{-(6 / 8)^{2}}^{0} d \bar{t} \int_{B_{6 / 8}(0)}\left|\nabla\left(\triangle^{-1} D_{k}^{i, j}\right)(\bar{z})\right|^{2} d \bar{x}\right)^{1 / 2} \\
& \leq \sum_{i, j=1}^{D}\left(\int_{-(6 / 8)^{2}}^{0} d \bar{t} \int_{B_{6 / 8}(0)}\left|u^{i}(\bar{z}) \nabla v_{k}^{j}(\bar{z})-u^{j}(\bar{z}) \nabla v_{k}^{i}(\bar{z})\right|^{2} d \bar{x}\right)^{1 / 2} \\
& +C_{R H} \sum_{i, j=1}^{D}\left(\int_{-(6 / 8)^{2}}^{0} d \bar{t} \int_{B_{6 / 8}(0)}\left|D_{k}^{i, j}(\bar{z})\right|^{2} d \bar{x}\right)^{1 / 2} .
\end{aligned}
$$

Once we recall definition of $D_{k}^{i, j}$, we then proceed to estimate $\left(R_{3.2}^{k}\right)$ as follows:

$$
\begin{align*}
& \left(R_{3.2}^{k}\right) \leq \sum_{i, j=1}^{D}\left(\int_{-(6 / 8)^{2}}^{0} d \bar{t} \int_{B_{6 / 8}(0)}\left|u^{j}(\bar{z}) \nabla v_{k}^{i}(\bar{z})-u^{i}(\bar{z}) \nabla v_{k}^{j}(\bar{z})\right|^{2} d \bar{x}\right)^{1 / 2} \\
& +C \sum_{i, j=1}^{D}\left(\int_{-(6 / 8)^{2}}^{0} d \bar{t} \int_{B_{6 / 8}(0)}\left|u^{j}(\bar{z}) \partial_{t} v_{k}^{i}(\bar{z})-u^{i}(\bar{z}) \partial_{t} v_{k}^{j}(\bar{z})\right|^{2} d \bar{x}\right)^{1 / 2} \\
& +C \sum_{i, j=1}^{D}\left(\int_{-(6 / 8)^{2}}^{0} d \bar{t} \int_{B_{6 / 8}(0)}\left|\left\langle u^{j}(\bar{z}) \nabla v_{k}^{i}(\bar{z})-u^{i}(\bar{z}) \nabla v_{k}^{j}(\bar{z}), \nabla \phi(\bar{z})\right\rangle\right|^{2} d \bar{x}\right)^{1 / 2} \\
& \quad \leq C\left\|\nabla v_{k}\right\|_{L^{2}\left(Q_{6 / 8}(0)\right)}^{2}+C\left\|\partial_{t} v_{k}\right\|_{L^{2}\left(Q_{6 / 8}(0)\right)}^{2} \leq C . \tag{2.42}
\end{align*}
$$

Finally, ( $R_{3.3}^{k}$ ) will be estimated from above. By definition of B.M.O, we can always assume that there exist sequences of positive numbers $\left\{r_{\nu}\right\}$ with $0<r_{\nu}$ $<1 / 8$ and points $\left\{x_{\nu}\right\}$ in $B_{6 / 8}(0)(\nu=1,2, \ldots)$ such that

$$
\begin{aligned}
& \left(R_{3.3}^{k}\right)=\left(\int_{-(6 / 8)^{2}}^{0} d \bar{t} \lim _{\nu \rightarrow \infty}\left(f_{B_{r_{\nu}}\left(x_{\nu}\right)}\left|\left(v_{k}(\bar{z})-v(\bar{z})\right) \phi(\bar{z})-\left(\left(v_{k}-v\right) \phi\right)_{B_{r_{\nu}}\left(x_{\nu}\right)}\right| d \bar{x}\right)^{2}\right)^{1 / 2} \\
& \leq \liminf _{\nu \rightarrow \infty}\left(\int_{-(6 / 8)^{2}}^{0} d \bar{t} f_{B_{r_{\nu}\left(x_{\nu}\right)}}\left|\left(v_{k}(\bar{z})-v(\bar{z})\right) \phi(\bar{z})-\left(\left(v_{k}-v\right) \phi\right)_{B_{r_{\nu}}\left(x_{\nu}\right)}\right|^{2} d \bar{x}\right)^{1 / 2} \\
& \leq C \liminf _{\nu \rightarrow \infty}\left(\int_{-(6 / 8)^{2}}^{0} \frac{d \bar{t}}{r_{\nu}} \int_{B_{r_{\nu}\left(x_{\nu}\right)}}\left|\nabla\left(\left(v_{k}(\bar{z})-v(\bar{z})\right) \phi(\bar{z})\right)\right|^{2} d \bar{x}\right)^{1 / 2} \\
& \leq C \liminf _{\nu \rightarrow \infty}\left(\int_{-(6 / 8)^{2}}^{0} \frac{d \bar{t}}{r_{\nu}} \int_{B_{r_{\nu}\left(x_{\nu}\right)}}\left|\nabla\left(v_{k}(\bar{z})-v(\bar{z})\right) \phi(\bar{z})\right|^{2} d \bar{x}\right)^{1 / 2} \\
& +C \liminf _{\nu \rightarrow \infty}^{0}\left(\int_{-(6 / 8)^{2}}^{0} \frac{d \bar{t}}{r_{\nu}} \int_{B_{r_{\nu}\left(x_{\nu}\right)}}\left|v_{k}(\bar{z})-v(\bar{z})\right|^{2}|\nabla \phi(\bar{z})|^{2} d \bar{x}\right)^{1 / 2} .
\end{aligned}
$$

Successively, using Lemma 2.4 to the 1st term and Hölder inequality to the 2nd term, we infer

$$
\begin{aligned}
& \left(R_{3.3}^{k}\right) \leq C \liminf _{\nu \rightarrow \infty}\left(\int_{-(6 / 8)^{2}}^{0} \frac{d \bar{t}}{r_{\nu}} \int_{B_{r_{\nu}}\left(x_{\nu}\right)}\left|\nabla v_{k}(\bar{z})\right|^{2} d \bar{x}\right)^{1 / 2} \\
& +C \liminf _{\nu \rightarrow \infty}\left(\int_{-(6 / 8)^{2}}^{0} \frac{d \bar{t}}{r_{\nu}} \int_{B_{r_{\nu}\left(x_{\nu}\right)}}|\nabla v(\bar{z})|^{2} d \bar{x}\right)^{1 / 2} \\
& +C \liminf _{\nu \rightarrow \infty}^{0}\left(\int_{-(6 / 8)^{2}}^{0} d \bar{t}\left(\int_{B_{r_{\nu}\left(x_{\nu}\right)}}\left|v_{k}(\bar{z})-v(\bar{z})\right|^{3}|\nabla \phi(\bar{z})|^{3} d \bar{x}\right)^{2 / 3}\right)^{1 / 2} \\
& \leq C+C\left(\int_{-(6 / 8)^{2}}^{0} d \bar{t}\left(\int_{B_{6 / 8}(0)}\left|v_{k}(\bar{z})-v(\bar{z})\right|^{6}|\nabla \phi(\bar{z})|^{6} d \bar{x}\right)^{1 / 3}\right)^{1 / 2}
\end{aligned}
$$

We apply Sobolev imbedding theorem $\stackrel{\circ}{H}^{1,2}\left(B_{6 / 8}(0)\right) \hookrightarrow L^{6}\left(B_{6 / 8}(0)\right)$ to the 2nd term; We can continue to estimate ( $R_{3.3}^{k}$ ) as follows.

$$
\begin{aligned}
\left(R_{3.3}^{k}\right) & =C+C\left(\int_{Q_{6 / 8}(0)}\left|\nabla\left(v_{k}(\bar{z})-v(\bar{z})\right)\right|^{2}|\nabla \phi(\bar{z})|^{2} d \bar{z}\right)^{1 / 2} \\
& +C\left(\int_{Q_{6 / 8}(0)}\left|v_{k}(\bar{z})-v(\bar{z})\right|^{2}\left|\nabla^{2} \phi(\bar{z})\right|^{2} d \bar{z}\right)^{1 / 2}
\end{aligned}
$$

From Lemma 2.5, it consequently follows

$$
\begin{equation*}
\left(\mathrm{R}_{3 . i}\right) \leq C \quad(i=1,2,3) . \tag{2.43}
\end{equation*}
$$

Finally, we perform the estimates of $\left(R_{4}^{k}\right)$ : For this purpose, note that

$$
\left|\nabla \triangle^{-1} D_{k}^{i, j}(\bar{t}, \bar{x})\right| \leq \frac{1}{2 \pi} \int_{B_{6 / 8}(0)}|\bar{x}-\bar{y}|^{-2}\left|D_{k}^{i, j}(\bar{t}, \bar{y})\right| d \bar{y} .
$$

In addition, Riesz-Hölder inequality implies

$$
\left\|\nabla \triangle^{-1} D_{k}^{i, j}\right\|_{L^{3}\left(B_{6 / 8}(0)\right)} \leq C\left\|D_{k}^{i, j}\right\|_{L^{2}\left(B_{6 / 8}(0)\right)}
$$

for a.e. $t$.
Then we implement Hölder inequality, Sobolev inequality and Riesz-Hölder inequality to obtain

$$
\begin{aligned}
& \left(R_{4}^{k}\right) \leq \lambda_{k} \sum_{i, j=1}^{D} \int_{-(6 / 8)^{2}}^{0} d \bar{t}\left\|\nabla\left(v_{k}^{i} \phi\right)\right\|_{L^{2}\left(B_{6 / 8}(0)\right)}\left\|\left(v_{k}^{j}-v^{j}\right) \phi\right\|_{L^{6}\left(B_{6 / 8}(0)\right)} \\
& \quad \times\left\|\nabla\left(\triangle^{-1} D_{k}^{i, j}\right)\right\|_{L^{3}\left(B_{6 / 8}(0)\right)} \\
& \leq C \lambda_{k} \sum_{i, j=1}^{D} \int_{-(6 / 8)^{2}}^{0} d \bar{t}\left\|\nabla\left(v_{k}^{i} \phi\right)\right\|_{L^{2}\left(B_{6 / 8}(0)\right)}\left\|\nabla\left(\left(v_{k}^{j}-v_{j}\right) \phi\right)\right\|_{L^{2}\left(B_{6 / 8}(0)\right)}\left\|D_{k}^{i, j}\right\|_{L^{2}\left(B_{6 / 8}(0)\right)} .
\end{aligned}
$$

As in the same way as in the estimates of $\left(R_{3}^{k}\right)$, we conclude the estimates of $\left(R_{4}^{k}\right)$ :

$$
\begin{align*}
\left(R_{4}^{k}\right) \leq & C \lambda_{k} \underset{-(6 / 8)^{2}<t \leq 0}{\operatorname{ess} \cdot \sup ^{2}}\left(\left\|\nabla v_{k} \phi\right\|_{L^{2}\left(B_{6 / 8}(0)\right)}+\left\|v_{k} \nabla \phi\right\|_{L^{2}\left(B_{6 / 8}(0)\right)}\right) \\
\times & \underset{-(6 / 8)^{2}<t \leq 0}{\operatorname{ess} \cdot \sup ^{2}}\left(\left\|\nabla v_{k} \phi\right\|_{L^{2}\left(B_{6 / 8}(0)\right)}+\left\|v_{k} \nabla \phi\right\|_{L^{2}\left(B_{6 / 8}(0)\right)}\right. \\
& \left.+\|\nabla v \phi\|_{L^{2}\left(B_{6 / 8}(0)\right)}+\|v \nabla \phi\|_{L^{2}\left(B_{6 / 8}(0)\right)}\right) \\
& \times \sum_{i, j=1}^{D}\left\|D_{k}^{i, j}\right\|_{L^{2}\left(Q_{6 / 8}(0)\right)} \leq C \lambda_{k} . \tag{2.44}
\end{align*}
$$

From (2.40), (2.41), (2.43) and (2.44), we conclude

$$
\int_{Q_{4 / 8}(0)}\left|\nabla\left(v_{k}(\bar{z})-v(\bar{z})\right)\right|^{2} d \bar{z}=O\left(\lambda_{k}\right),
$$

which completes the proof of Lemma 2.6.

## CHAPTER 3

## Evolutional Ginzburg-Landau mappings

## 1. Introduction

In chapter I, section 5, we observed that to construct "a weakly evolutional harmonic map into a sphere," Chen [19] plied a penalty scheme. The corresponding elliptic system:

$$
\triangle u+\lambda\left(|u|^{2}-1\right) u=0 \quad u: B_{1}(0) \rightarrow \mathbb{R}^{\hat{D}}, \lambda \in \mathbb{R}_{+}
$$

are called "Ginzburg-Landau systems," which stem from superconductors and superfluids such as helium II in physics. For the physical background, ask to Bethuel-Brezis-Hélein [5] and Neu [88]. Main interest of Ginzburg-Landau systems in physics, is to investigate the zero points of it because zero points are translated into the normal state in the superconductivity state. In this chapter we mainly study the relation between zero sets of solutions of Ginzburg-Landau systems and the singular set of weakly evolutional harmonic maps into a sphere that are constructed by passing to the limit of a subsequence of $\lambda \rightarrow \infty$ of $u_{\lambda}$ which is a solution to (3.1), (3.2) and (3.3). We start this chapter by stating our problem exactly:

Let $d$ and $D$ be positive integers greater than or equal to 3 and $\lambda$ a positive integer. Suppose that $\Omega \subset \mathbb{R}^{d}$ is a domain. For any fixed positive number $T$, the parabolic cylinder $Q_{T}$ is defined by $Q_{T}=(0, T) \times \Omega \subset \mathbb{R}^{1+d}$.

The evolutional Ginzburg-Landau mappings $u_{\lambda}=\left(u_{\lambda}^{1}, \cdots, u_{\lambda}^{D}\right): Q_{T} \rightarrow \mathbb{R}^{D}$ are given as the solutions to the following parabolic systems:

$$
\begin{array}{lr}
\frac{\partial u_{\lambda}}{\partial t}=\triangle u_{\lambda}-\lambda\left(\left|u_{\lambda}\right|^{2}-1\right) u_{\lambda} & \text { for } \quad z=(t, x) \in Q_{T}, \\
u_{\lambda}(0, x)=u_{0}(0, x) & \text { for } \quad t=0, \quad x \in \Omega, \\
u_{\lambda}(t, x)=u_{0}(t, x) & \text { for } \quad t \in[0, T), \quad x \in \partial \Omega \tag{3.3}
\end{array}
$$

where $u_{0}=\left(u_{0}^{1}, \cdots, u_{0}^{D}\right): \overline{Q_{T}} \rightarrow \mathbb{R}^{D}$ with $\left|u_{0}\right|=\sqrt{\sum_{i=1}^{D}\left|u_{0}^{i}\right|^{2}}=1$ for a.e. $z=(t, x)$ $\in \partial Q_{T}$.

This system (3.1) is the $L^{2}$-gradient flow for the Ginzburg-Landau energy

$$
\begin{equation*}
E_{\lambda}(u):=\frac{1}{2} \int_{\Omega}\left(|\nabla u|^{2}+\frac{\lambda}{2}\left(|u|^{2}-1\right)^{2}\right) d x . \tag{3.4}
\end{equation*}
$$

In the following, we call $e_{\lambda}\left(u_{\lambda}\right)$ the energy-density of the evolutional GinzburgLandau mappings defined by

$$
\begin{equation*}
e_{\lambda}\left(u_{\lambda}\right)=\frac{1}{2}\left(\left|\nabla u_{\lambda}\right|^{2}+\frac{\lambda}{2}\left(\left|u_{\lambda}\right|^{2}-1\right)^{2}\right) . \tag{3.5}
\end{equation*}
$$

This chapter studies the evolutional Ginzburg-Landau mappings on $Q_{T}=$ $(0, T) \times \Omega$ when $\Omega$ is a bounded star-shaped domain with respect to the origin in $\mathbb{R}^{d}(d \geq 3)$ with the following properties:
(i) $\partial \Omega$ is of $C^{4}$-boundary.
(ii) $\gamma(x):=\inf _{\lambda>0, \lambda x \notin \partial \Omega} \lambda x$ belongs to $C^{1}(\bar{\Omega})$.
(iii) The inner product between each point $x \in \partial \Omega$ and the outward normal unit vector $\nu_{x}$ at $x \in \partial \Omega$, denoted by $\left\langle x, \nu_{x}\right\rangle$, is greater than 2 .
We prove that the energy density $e_{\lambda}\left(u_{\lambda}\right)$ of the evolutional Ginzburg-Landau mappings $u_{\lambda}$ is uniformly bounded with respect to the parameter $\lambda$ if the scaled energy of the evolutional Ginzburg-Landau mappings is uniformly small. After it, we indicate that these energy estimates much concern the behavior of the evolutional Ginzburg-Landau mappings near the so-called cluster set of zero points of the evolutional Ginzburg-Landau mappings $u_{\lambda}$. The uniform bounded estimates to an energy density $e_{\lambda}\left(u_{\lambda}\right)$ may be firstly obtained by Chen-Struwe [24] in case of $\Omega=\mathbb{R}^{d}$ with $d \geq 2$ and $D \geq 2$.

This chapter is organized as follows: In section 2 , we mention existence and uniqueness results to our initial - boundary value problem. Section 3 collects the technical auxiliary lemmas: We establish a fundamental energy estimate, a Bochner type formula, the monotonicity inequality for the energy density and a Fefferman-Phong type inequality; Section 4 first applies $\epsilon$-regularity theory to the scaled energy of the evolutional Ginzburg-Landau mappings. The proof of the theorem above is performed by reductio ad absurdum. Successively we discuss a certain estimate related to a behavior near zero sets of the evolutional GinzburgLandau mappings. Finally, we study an alternative approach to prove the uniform boundedness of $e_{\lambda}\left(u_{\lambda}\right)$ on the cylinder where the scaled energy is uniformly small with respect to $\lambda$. The benefit of this method is the point that we can explicitly estimate a certain constant appeared in the statement of the theorem. We state this result as the third theorem.

## 2. Existence and uniqueness

In this section we first formulates our problem exactly and we next establish the existence and uniqueness theorems to the problem. Set $d$ and $D$ be positive numbers greater than 2 . Let $u_{0}$ be a map belonging to $C^{0}\left(0, T ; W^{1,2}\left(\Omega ; \mathbb{R}^{D}\right)\right)$ with
$\left.u_{0}\right|_{\partial \Omega}$ (A trace to $\left.\partial \Omega\right) \in C^{\infty}\left([0, T) \times \partial \Omega ; \mathbb{R}^{D}\right)$ and $\left|u_{0}\right|=\sqrt{\sum_{i=1}^{D}\left(u_{0}^{i}\right)^{2}}=1$ on $\partial Q_{T}$.

Definition 3.1. If we say $u_{\lambda}: Q_{T} \rightarrow \mathbb{R}^{D}$ to be evolutional Ginzburg-Landau system. a smooth map $u_{\lambda}$ satisfies (3.1) classically, (3.2) and (3.3) in the sense that $\lim _{t \rightarrow+0}\left\|u_{\lambda}(t, \cdot)-u_{0}(t, \cdot)\right\|_{L^{2}(\Omega)}=0$ and $u_{\lambda}(t, \cdot)-u_{0}(t, \cdot) \in \stackrel{\circ}{H^{1,2}}\left(\Omega ; \mathbb{R}^{D}\right)$ for a.e. $t \in(0, T)$.

To the initial-boundary value problems (3.1), (3.2) and (3.3), we show
Theorem 3.1. There uniquely exists the evolutional Ginzburg-Landau system $u_{\lambda}$ such that

$$
\begin{align*}
& u_{\lambda} \in C^{\infty}([0, T) \times \bar{\Omega})  \tag{3.6}\\
& \left|u_{\lambda}\right| \leq 1 \quad \text { in } Q_{T}  \tag{3.7}\\
& \frac{1}{2} \int_{Q_{T}}\left|\frac{\partial u_{\lambda}}{\partial t}(z)\right|^{2} d z+\frac{1}{4} \underset{0 \leq t \leq T}{\operatorname{ess} \cdot \sup } \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x  \tag{3.8}\\
& \quad \leq \frac{\epsilon_{0}}{2} \int_{0}^{T} d t \int_{\partial \Omega}\left(\langle x, \nu\rangle+|x|^{2}\right)\left|\nabla_{\tan } u_{0}(z)\right|^{2} d \mathcal{H}^{d-1} \\
& \quad+\frac{1}{\epsilon_{0}} \int_{0}^{T} d t \int_{\partial \Omega}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2} d \mathcal{H}^{d-1}+\int_{\Omega}\left|\nabla u_{0}(0, x)\right|^{2} d x
\end{align*}
$$

with $\epsilon_{0}=\min \left(1 /\left(2 \operatorname{diam}(\Omega)^{2}\right), 1 /\left(1+\|\nabla \gamma\|_{L^{\infty}}^{2} \operatorname{diam}(\Omega)^{2}\right)\right)$.

## Proof of Theorem 3.1

For the time being, suppose that evolutional Ginzburg-Landau mappings exist and these satisfy

$$
\begin{equation*}
\lim _{h \backslash 0_{0<t \leq h}} \sup _{\Omega} \int_{\Omega}\left|\nabla u_{\lambda}(t, x)\right|^{2} d x=\int_{\Omega}\left|\nabla u_{0}(0, x)\right|^{2} d x . \tag{3.9}
\end{equation*}
$$

Then we preliminarily verify the uniqueness, the boundedness (3.7) and the fundamental energy inequalities (3.8). To this end, assume the existences of two evolutional Ginzburg-Landau mappings $u_{\lambda}$ and $v_{\lambda}$ : these maps $u_{\lambda}$ and $v_{\lambda}$ satisfy

$$
\begin{align*}
& \frac{\partial u_{\lambda}}{\partial t}(z)=\Delta u_{\lambda}(z)-\lambda\left(\left|u_{\lambda}(z)\right|^{2}-1\right) u_{\lambda}(z) \quad \text { in } \quad Q_{T},  \tag{3.10}\\
& \frac{\partial v_{\lambda}}{\partial t}(z)=\triangle v_{\lambda}(z)-\lambda\left(\left|v_{\lambda}(z)\right|^{2}-1\right) v_{\lambda}(z) \quad \text { in } \quad Q_{T},  \tag{3.11}\\
& u_{\lambda}(0, x)=v_{\lambda}(0, x)=u_{0}(0, x) \quad \text { in } \quad\{0\} \times \Omega, \tag{3.12}
\end{align*}
$$

$$
\begin{equation*}
u_{\lambda}(z)=v_{\lambda}(z)=u_{0}(t, x) \quad \text { in } \quad(0, T) \times \partial \Omega . \tag{3.13}
\end{equation*}
$$

Subtracting (3.11) from (3.10), multiplying $\phi \in C_{0}^{\infty}\left(Q_{T} ; \mathbb{R}^{D}\right)$ and integrating it over $Q_{T}$, we have

$$
\begin{align*}
& \int_{Q_{T}}\left\langle\frac{\partial}{\partial t}\left(u_{\lambda}(z)-v_{\lambda}(z)\right), \phi(z)\right\rangle d z+\int_{Q_{T}}\left\langle\nabla\left(u_{\lambda}(z)-v_{\lambda}(z)\right), \nabla \phi(z)\right\rangle d z \\
& =-\lambda \int_{Q_{T}}\left\langle\left(\left|u_{\lambda}(z)\right|^{2}-1\right) u_{\lambda}(z)-\left(\left|v_{\lambda}(z)\right|^{2}-1\right) v_{\lambda}(z), \phi(z)\right\rangle d z \tag{3.14}
\end{align*}
$$

Noting $u_{\lambda}-v_{\lambda}=0$ on $\partial Q_{T}$, we substitute $\phi$ in (3.14) for $\left(u_{\lambda}-v_{\lambda}\right) e^{-2 \lambda t}$ to obtain

$$
\begin{align*}
& \frac{1}{2} \int_{Q_{T}} \frac{\partial}{\partial t}\left|u_{\lambda}(z)-v_{\lambda}(z)\right|^{2} e^{-2 \lambda t} d z \\
& +\int_{Q_{T}}\left|\nabla\left(u_{\lambda}(z)-v_{\lambda}(z)\right)\right|^{2} e^{-2 \lambda t} d z \\
& =-\lambda \int_{Q_{T}}\left(\left|u_{\lambda}(z)\right|^{4}+\left|v_{\lambda}(z)\right|^{4}\right. \\
& \left.\quad-\left(\left|u_{\lambda}(z)\right|^{2}+\left|v_{\lambda}(z)\right|^{2}\right)\left\langle u_{\lambda}(z), v_{\lambda}(z)\right\rangle\right) e^{-2 \lambda t} d z \\
& +\lambda \int_{Q_{T}}\left|u_{\lambda}(z)-v_{\lambda}(z)\right|^{2} e^{-2 \lambda t} d z \tag{3.15}
\end{align*}
$$

By using Schwarz inequality to the 1st term on the right-hand side, we arrive at

$$
\begin{align*}
& \frac{1}{2} \int_{\Omega}\left|u_{\lambda}(T, x)-v_{\lambda}(T, x)\right|^{2} e^{-2 \lambda T} d x+\int_{Q_{T}}\left|\nabla\left(u_{\lambda}(z)-v_{\lambda}(z)\right)\right|^{2} e^{-2 \lambda t} d z \\
& -\left.\frac{\lambda}{2} \int_{Q_{T}}| | u_{\lambda}(z)\right|^{2}-\left.\left|v_{\lambda}(z)\right|^{2}\right|^{2} e^{-2 \lambda t} d z \leq 0 \tag{3.16}
\end{align*}
$$

Thus, we deduce $u_{\lambda} \equiv v_{\lambda}$ in $Q_{T}$.
Second, we show (3.7): We multiply (3.1) by $\left(\left|u_{\lambda}\right|^{2}-1\right)^{(0)} u_{\lambda}$ and integrate it on $Q_{T}$ with respect to $z$. Then by recalling $\left|u_{0}\right|=1$ on $\partial Q_{T}$, we obtain

$$
\begin{aligned}
& \frac{1}{4} \int_{\Omega \cap\left\{\left|u_{\lambda}\right| \geq 1\right\}}\left(\left|u_{\lambda}(T, x)\right|^{2}-1\right)^{2} d x \\
& +\int_{Q_{T} \cap\left\{\left|u_{\lambda}\right| \geq 1\right\}}\left|\nabla u_{\lambda}(z)\right|^{2}\left(\left|u_{\lambda}(z)\right|^{2}-1\right)^{(0)} d z \\
& +\left.\left.\frac{1}{2} \int_{Q_{T} \cap\left\{\left|u_{\lambda}\right| \geq 1\right\}}|\nabla| u_{\lambda}(z)\right|^{2}\right|^{2} d z
\end{aligned}
$$

$$
+\lambda \int_{Q_{T} \cap\left\{\left|u_{\lambda}\right| \geq 1\right\}}\left(\left|u_{\lambda}(z)\right|^{2}-1\right)^{2}\left|u_{\lambda}(z)\right|^{2} d z=0
$$

Thus we conclude $\mathcal{L}^{d+1}\left(\left\{z \in Q_{T} ;\left|u_{\lambda}\right| \geq 1\right\}\right)=0:\left|u_{\lambda}\right| \leq 1$ for a.e. $z \in Q_{T}$. Since $u_{\lambda} \in C^{2}\left(Q_{T}\right),\left|u_{\lambda}\right| \leq 1$ on $z \in Q_{T}$.

Next, we prove (3.8). For this purpose, we first estimate $\int_{0}^{T} d t \int_{\partial \Omega}\left|\partial u_{\lambda} / \partial \nu(t, x)\right|^{2}$ $d \mathcal{H}^{d-1}$ : We multiply (3.1) by $\partial u_{\lambda} / \partial t\left(\gamma^{2}(x)-|x|^{2}\right) / 2+\langle x, \nabla\rangle u_{\lambda}$, integrating it on $(h, t) \times \Omega \subset Q_{T}$ over $z$ to imply

$$
\begin{aligned}
0 & =\frac{1}{2} \int_{h}^{t} d t \int_{\Omega}\left|\frac{\partial u_{\lambda}}{\partial t}(z)\right|^{2}\left(\gamma^{2}(x)-|x|^{2}\right) d x \\
& -\frac{1}{2} \int_{h}^{t} d t \int_{\Omega}\left\langle\Delta u_{\lambda}(z), \frac{\partial u_{\lambda}}{\partial t}(z)\right\rangle\left(\gamma^{2}(x)-|x|^{2}\right) d x \\
& +\frac{\lambda}{8} \int_{h}^{t} d t \int_{\Omega} \frac{\partial}{\partial t}\left(\left|u_{\lambda}(z)\right|^{2}-1\right)^{2}\left(\gamma^{2}(x)-|x|^{2}\right) d x \\
& -\int_{h}^{t} d t \int_{\Omega}\left\langle\triangle u_{\lambda}(z),\langle x, \nabla\rangle u_{\lambda}(z)\right\rangle d x \\
& +\frac{\lambda}{4} \int_{h}^{t} d t \int_{\Omega}\langle x, \nabla\rangle\left(\left|u_{\lambda}(z)\right|^{2}-1\right)^{2} d x .
\end{aligned}
$$

Repeating the integral by parts and taking the limit $h \searrow 0$ and noting $\nabla=$ $\nu \partial / \partial \nu+\nabla_{\text {tan }}$, we have

$$
\begin{aligned}
0 & =\frac{1}{2} \int_{Q_{t}}\left|\frac{\partial u_{\lambda}}{\partial t}(z)\right|^{2}\left(\gamma^{2}(x)-|x|^{2}\right) d z \\
& +\frac{1}{2} \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(z)\left(\gamma^{2}(x)-|x|^{2}\right) d x-\frac{1}{4} \int_{\Omega}\left|\nabla u_{0}(h, x)\right|^{2}\left(\gamma^{2}(x)-|x|^{2}\right) d x \\
& +\int_{Q_{t}}\left\langle\langle\nabla \gamma(x), \nabla\rangle u_{\lambda}(z), \frac{\partial u_{\lambda}}{\partial t}(z)\right\rangle \gamma(x) d z \\
& +\frac{2-d}{2} \int_{Q_{t}}\left|\nabla u_{\lambda}(z)\right|^{2} d z-\frac{\lambda d}{4} \int_{Q_{t}}\left(\left|u_{\lambda}(z)\right|^{2}-1\right)^{2} d z \\
& -\int_{0}^{t} d t \int_{\partial \Omega}\langle x, \nu\rangle\left|\frac{\partial u_{\lambda}}{\partial \nu}(z)\right|^{2} d \mathcal{H}^{d-1}-\int_{0}^{t} d t \int_{\partial \Omega}\left\langle\frac{\partial u_{\lambda}}{\partial \nu}(z),\left\langle x, \nabla_{\tan }\right\rangle u_{0}(z)\right\rangle d \mathcal{H}^{d-1} \\
& +\frac{1}{2} \int_{0}^{t} d t \int_{\partial \Omega}\langle x, \nu\rangle\left|\nabla u_{\lambda}(z)\right|^{2} d \mathcal{H}^{d-1} .
\end{aligned}
$$

Thus we infer

$$
\begin{aligned}
& \frac{1}{2} \int_{0}^{t} d t \int_{\partial \Omega}\left|\frac{\partial u_{\lambda}}{\partial \nu}(z)\right|^{2} d \mathcal{H}^{d-1} \\
& \leq \frac{\operatorname{diam}(\Omega)^{2}}{2} \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x \\
& +\frac{1+| | \nabla \gamma \|_{L^{\infty}}^{2}}{2} \operatorname{diam}(\Omega)^{2} \int_{Q_{t}}\left|\frac{\partial u_{\lambda}}{\partial t}(z)\right| d z \\
& +\frac{3-d}{2} \int_{Q_{t}}\left|\nabla u_{\lambda}(z)\right|^{2} d z-\frac{\lambda d}{4} \int_{Q_{t}}\left(\left|u_{\lambda}(z)\right|^{2}-1\right)^{2} d z \\
& +\frac{1}{2} \int_{0}^{t} d t \int_{\partial \Omega}\left(\langle x, \nu\rangle+|x|^{2}\right)\left|\nabla_{\tan } u_{0}(z)\right|^{2} d \mathcal{H}^{d-1}
\end{aligned}
$$

By using (3.17), we complete (3.8). Similarly as above, a multiplier of (3.1) by $\partial u_{\lambda} / \partial t$, an integration of it over $(h, t) \times \Omega \subset Q_{T}$, the integral by parts and the limit $h \searrow 0$ read

$$
\begin{align*}
& \int_{Q_{t}}\left|\frac{\partial u_{\lambda}}{\partial t}(z)\right|^{2} d z+\frac{1}{2} \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x \\
& =\int_{0}^{t} d t \int_{\partial \Omega}\left\langle\frac{\partial u_{\lambda}}{\partial \nu}(z), \frac{\partial u_{0}}{\partial t}(z)\right\rangle d x+\frac{1}{2} \int_{\Omega}\left|\nabla u_{0}(0, x)\right|^{2} d x \\
& \leq \frac{\epsilon_{0}}{2} \int_{0}^{t} d t \int_{\partial \Omega}\left|\frac{\partial u_{\lambda}}{\partial \nu}(z)\right|^{2} d \mathcal{H}^{d-1}+\frac{1}{2 \epsilon_{0}} \int_{0}^{t} d t \int_{\partial \Omega}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2} d \mathcal{H}^{d-1} \\
& +\frac{1}{2} \int_{\Omega}\left|\nabla u_{0}(0, x)\right|^{2} d x \tag{3.18}
\end{align*}
$$

for any positive $\epsilon_{0}$.
By substituting (3.17) for (3.18) and taking $\epsilon_{0}$ as

$$
\epsilon_{0}=\frac{1}{2\left(1+\|\nabla \gamma\|_{L^{\infty}}^{2}\right) \operatorname{diam}(\Omega)^{2}},
$$

we have

$$
\begin{aligned}
& \frac{1}{2} \int_{Q_{t}}\left|\frac{\partial u_{\lambda}}{\partial t}(z)\right|^{2} d z+\frac{1}{2} \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x \\
& \leq \frac{\epsilon_{0}}{2}\left(\operatorname{diam}(\Omega)+\operatorname{diam}(\Omega)^{2}\right) \int_{0}^{t} d t \int_{\partial \Omega}\left|\nabla_{\tan } u_{0}(z)\right| d \mathcal{H}^{d-1} \\
& +\frac{1}{2 \epsilon_{0}} \int_{0}^{t} d t \int_{\partial \Omega}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2} d \mathcal{H}^{d-1}+\frac{1}{2} \int_{\Omega}\left|\nabla u_{0}(0, x)\right|^{2} d x
\end{aligned}
$$

for any $t \in(0, T)$.
From now on, we prove the existence of the evolutional Ginzburg-Landau system: We begin with constructing an approximation map of the evolutional Ginzburg-Landau system: Let $v^{(0)}$ be the solution of

$$
\begin{aligned}
& \frac{\partial v^{(0)}}{\partial t}(z)-\Delta v^{(0)}(z)=0 \quad \text { in } \quad Q_{T}, \\
& v^{(0)}(0, x)=u_{0}(0, x) \quad \text { at } \quad\{0\} \times \Omega, \\
& v^{(0)}(t, x)=u_{0}(t, x) \quad \text { on } \quad(0, T) \times \partial \Omega .
\end{aligned}
$$

Set $X=\left\{v \in C^{\infty}\left(\left(0, t_{\lambda}\right) \times \Omega\right) ;\|v\|_{L^{\infty}\left(\left(0, t_{\lambda}\right) \times \Omega\right)} \leq 1,\left.v(z)\right|_{\partial \Omega}=0, v(0, x)=0\right\}$ with a certain positive number $t_{\lambda}$ depending only on $\lambda$. Assume that $v^{(j)}(j=$ $0,1, \ldots, k-1$ ) exists in $X$.

Then $v^{(k)}$ is decided by

$$
\begin{aligned}
v^{(k)}(z)= & \mathcal{A} v^{(k-1)}(z)=-\lambda \int_{0}^{t} d s \int_{\Omega} U(t-s ; x, y)\left(\left|v^{(k-1)}(s, y)+v^{(0)}(s, y)\right|^{2}-1\right) \\
& \times\left(v^{(k-1)}(s, y)+v^{(0)}(s, y)\right) d y
\end{aligned}
$$

where $U(t ; x, y)(t>0, x, y \in \bar{\Omega})$ is the fundamental solution of

$$
\begin{aligned}
& \frac{\partial w}{\partial t}(z)-\Delta w(z)=0 \quad(t>0, x \in \Omega) \\
& w(t, x)=0 \quad \text { on } \quad(0, T) \times \partial \Omega
\end{aligned}
$$

By employing Ladyzhenskaya-Solonnikov-Uralceva [75] and Friedman [45, Theorem 6 in Chap III], a choice of $t_{\lambda}$ implies that $\mathcal{A}$ is a contraction operator from $X$ to $X$ : If we define $u_{\lambda}$ by $v^{(\infty)}+v^{(0)}$, then we easily show that the mapping $u_{\lambda}$ satisfies (3.1), (3.2), (3.3) (3.6) and (3.9). By virtue of an energy inequality (3.8), we can extend $u_{\lambda}$ constructed above in $\left(0, t_{\lambda}\right) \times \Omega$ to $Q_{T}$.

## 3. Theorems

After the preparation in the former chapter, we can state our main theorems of this chapter. To this end, we need to introduce more symbols:
(i) $\Phi_{R}^{1}\left(z_{0}\right)$ and $\Phi_{R}^{2}\left(z_{0}\right)$ will be given in Corollary 3.1.
(ii) For any positive number $t, \delta(t):=\sqrt{(12(d-2)+1)|\log t|}$.
(iii) $\mathbf{N}:=\cup_{\lambda=1}^{\infty} \mathbf{N}_{\lambda}$ with $\mathbf{N}_{\lambda}:=\left\{z_{0} \in Q_{T} ; u_{\lambda}\left(z_{0}\right)=0\right\}$.
(iv) If we say a point $z_{0}$ to belong to $\mathbf{N}^{\text {CL }}$, it means the following: there exist sequences of positive integers $\lambda(j)$ and of points $z_{\lambda(j)} \in \mathbf{N}_{\lambda(j)}$ with $\lambda(1)<$ $\lambda(2)<\cdots<\infty$ such that $z_{\lambda(j)} \rightarrow z_{0}$ as $j \rightarrow \infty$.
(v) Reg : $=\bigcup_{\lambda_{0}=1}^{\infty} \bigcup_{R>0} \bigcap_{\lambda=\lambda_{0}}^{\infty}\left\{z_{0} \in Q_{T} ; \Phi_{R}^{1}\left(t_{0}+2(R / 4)^{2}, x_{0}\right)<\epsilon_{1}\right.$ with $\left(t_{0}+\right.$ $\left.\left.2(R / 4)^{2}-4 R^{2}, t_{0}+2(R / 4)^{2}+4 R^{2}\right) \times B_{(1+\delta(R)) R}\left(x_{0}\right) \subset \subset Q_{T}\right\}$ for a positive number $\epsilon_{1}$.
THEOREM 3.2. Then there exists a positive constant $\epsilon_{1}$ depending only on $d$ such that if for a point $z_{0}=\left(t_{0}, x_{0}\right)$ and a cylinder $\left(t_{0}+(R / 4)^{2}-4 R^{2}, t_{0}+\right.$ $\left.(R / 4)^{2}+4 R^{2}\right) \times B_{(1+\delta(R)) R}\left(x_{0}\right) \subset \subset Q_{T}$, the evolutional Ginzburg-Landau system $u_{\lambda}$ satisfies

$$
\begin{equation*}
\Phi_{R}^{1}\left(t_{0}+(R / 4)^{2}, x_{0}\right)<\epsilon_{1} \quad \text { then, } \sup _{Q_{R / 4}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)<64 R^{-2} . \tag{3.19}
\end{equation*}
$$

Next theorem is
Theorem 3.3.

$$
\begin{equation*}
\mathbf{N}^{\mathrm{CL}} \bigcap \operatorname{Reg}=\emptyset, \quad \text { i.e. } \quad \mathbf{N}^{\mathrm{CL}} \subset \text { CReg. } \tag{3.20}
\end{equation*}
$$

Remark 3.1. By using (3.20), as in the similar way as in the proof of ChenStruwe [24], we find

$$
\mathcal{H}^{d}\left(\mathbf{N}^{\mathrm{CL}}\right) \leq \mathcal{H}^{d}(\text { CReg })<\infty .
$$

Remark 3.2. Let $B^{d}$ be the $d$-dimensional unit ball and $u_{0}$ an initial-boundary mapping of the evolutional Ginzburg-Landau system satisfying

$$
\begin{aligned}
& u_{0} \in W^{1,2}\left(B^{d} ; S^{d-1}\right) \\
& \left.u_{0}\right|_{\partial B^{d}} \in C^{\infty}\left(\partial B^{d} ; S^{d-1}\right), \\
& u_{0}\left(\partial B^{d}\right) \text { is not homotopic to a constant map. }
\end{aligned}
$$

Here note that by Bethuel-Zheng [9], such $u_{0}$ exists. From the theory of degree of a mapping (See for example, Nirenberg [89].), the evolutional Ginzburg-Landau system $u_{\lambda}$ must have at least one zero point in $B^{d}$ at each $t \in(0, T)$ if $\left.u_{\lambda}\right|_{\partial B^{d}}=$ $\left.u_{0}\right|_{\partial B^{d}}$ has a non-zero degree. This shows $\mathbf{N}_{\lambda} \neq \emptyset$ and furthermore if $u_{\lambda}$ has a finite zero point in $B^{d}$ at each $t(0<t<T), \mathbf{N}_{\lambda}$ may be finite in 2-dimensional Hausdorff dimension with respect to the parabolic metric. While, as showing in the previous remark, $\mathbf{N}^{\mathrm{CL}}$ has at most finite $d$-dimensional Hausdorff measure. These observations draw me to the question how sharply the Hausdorff measure of $\mathbf{N}^{\mathrm{CL}}$ depends on the Hausdorff dimension of the zero set of the evolutional Ginzburg-Landau system with the initial-boundary value. Recently several literatures study a zero set of solutions of various equations. For instance, to second-order elliptic equations, it is studied by Caffarelli-Friedman [13] and Hardt-Simon [62] and to the heat equations on an analytic compact Riemann manifold, it by Lin [80].

From Lemma 3.4 stated below, Giaquinta [46] and Ladyzhenskaya-SolonnikovUralceva [75], the 3rd theorem follows

Theorem 3.4. Let $u_{\lambda}$ be the evolutional Ginzburg-Landau system. Then for any point $z_{0}=\left(t_{0}, x_{0}\right)$ and a cylinder $\left(t_{0}+(R / 4)^{2}-4 R^{2}, t_{0}+(R / 4)^{2}+4 R^{2}\right) \times B_{(1+\delta(R)) R}\left(x_{0}\right)$,

$$
\Phi_{R}^{2}\left(z_{0}\right) \leq \min \left(\frac{1}{64 \cdot 24 \cdot C_{\mathrm{FP}}} \cdot \frac{d}{d+2},\left(\frac{1}{C_{\mathrm{RH}}^{3}}\right)^{d / \delta_{0}(d+2)}\left(\frac{1}{4}\right)^{(d+2) /(d+1)\left(1+\delta_{0}\right) / \delta_{0}^{2}} \frac{1}{C_{\mathrm{RH}}^{1}}\right)
$$

where

$$
\begin{aligned}
C_{\mathrm{RH}}^{1}= & \frac{C_{\mathrm{SO}}}{\tau^{2}\left(1-\tau^{2}\right)}, \\
C_{\mathrm{RH}}^{2}= & \frac{C_{\mathrm{SO}}}{d\left(2 \tau^{2}-1\right)}\left(\frac{3 d}{d+2} \cdot \frac{8 \tau}{1-\tau}+4 d \frac{16 \tau^{2}}{\left(1-\tau^{2}\right)}+\frac{8 d}{(d+2)^{2}} \cdot \frac{16 \tau^{2}}{(1-\tau)^{2}}\right. \\
& \left.+\frac{d}{(d+2)^{2}} \cdot \frac{16 \tau^{2}}{(1-\tau)^{2}}+\frac{64}{d+2}\right), \\
C_{\mathrm{RH}}^{3} & =4^{1 / d}\left(4^{4} C_{\mathrm{RH}}^{2}+\frac{(64 d)}{(d+2)} 3^{2(1+2 / d)}\right),
\end{aligned}
$$

$\tau=1 / 2(1+\sqrt{2}), C_{\mathrm{FP}}$ is the nonlinear Fefferman-Phong's constant appears in Lemma 3.4 and $C_{\mathrm{SO}}$ is the best Sobolev constant, implies

$$
\begin{equation*}
\sup _{Q_{R / 4}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) \leq 2 / R^{2} \tag{3.21}
\end{equation*}
$$

## 4. Technical lemmas

We review a few technical lemmas which will play a crucial role on the proof of our results. The first lemma is as follows:

Lemma 3.1. Let $u_{\lambda}$ be the evolutional Ginzburg-Landau mappings. Then we have

$$
\begin{align*}
& \frac{\partial\left|u_{\lambda}\right|^{2}}{\partial t}-\triangle\left|u_{\lambda}\right|^{2}+2 \lambda\left(\left|u_{\lambda}\right|^{2}-1\right)\left|u_{\lambda}\right|^{2} \leq 0  \tag{3.22}\\
& \left(\frac{\partial}{\partial t}-\triangle\right) e_{\lambda}\left(u_{\lambda}\right)+f_{\lambda}\left(u_{\lambda}\right) \leq 16 e_{\lambda}^{2}\left(u_{\lambda}\right)  \tag{3.23}\\
& \quad \text { with } \quad f_{\lambda}\left(u_{\lambda}\right)=\frac{1}{2}\left(\left|\nabla^{2} u_{\lambda}\right|^{2}+\left.4 \lambda\left|u_{\lambda}\right|^{2}|\nabla| u_{\lambda}\right|^{2}\right)
\end{align*}
$$

We successively present the second lemma:
Lemma 3.2 (A local energy inequality). Let $z_{0}=\left(t_{0}, x_{0}\right)$ be a point in $Q_{T}$ and set positive numbers $t_{1}, t_{2}$ and $r_{1}$, $r_{2}$ with $0<t_{0}-t_{2}<t_{0}-t_{1} \leq t_{0}$ and $r_{1}<r_{2}$ with $C_{2 r_{2}}\left(x_{0}\right) \subset \subset \Omega$. Then the evolutional Ginzburg-Landau system $u_{\lambda}$ satisfies

$$
\begin{align*}
& \frac{1}{2} \int_{t_{0}-t_{1}}^{t_{0}} d t \int_{B_{r_{1}}}\left|\frac{\partial u_{\lambda}}{\partial t}(z)\right|^{2} d x+\int_{B_{r_{1}}} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x  \tag{3.24}\\
& \leq\left[\frac{32}{\left(r_{2}-r_{1}\right)^{2}}+\frac{4}{\left(t_{2}-t_{1}\right)}\right] \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{B_{r_{2}}} e_{\lambda}\left(u_{\lambda}\right)(z) d x \\
& \frac{1}{2} \int_{t_{0}-t_{1}}^{t_{0}} d t \int_{C_{r_{1}}}\left|\frac{\partial u_{\lambda}}{\partial t}(z)\right|^{2} d x+\int_{C_{r_{1}}} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x \\
& \leq\left[\frac{32}{\left(r_{2}-r_{1}\right)^{2}}+\frac{4}{\left(t_{2}-t_{1}\right)}\right] \int_{t_{0}-t_{2}}^{t_{0}} d t \int_{C_{r_{2}}} e_{\lambda}\left(u_{\lambda}\right)(z) d x
\end{align*}
$$

for any time $t$ with $t_{0}-t_{1}<t \leq t_{0}$.
Next, we state the monotonicity inequality for the scaled energies of the evolutional Ginzburg-Landau mappings

Lemma 3.3 (A monotonicity formula). Let $u_{\lambda}$ be the evolutional GinzburgLandau mappings Then the following inequality holds:

$$
\begin{align*}
& \frac{1}{r_{1}{ }^{d}} \int_{t_{0}-r_{1}^{2}}^{t_{0}} d t \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(z) e^{\frac{\left|x-x_{0}\right|^{2}}{4\left(t-t_{0}\right)}} d x \\
& \leq \frac{1}{r_{2}^{d}{ }^{d}} \int_{t_{0}-r_{2}^{2}}^{t_{0}} d t \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(z) e^{\frac{\left|x-x_{0}\right|^{2}}{4\left(t-t_{0}\right)}} d x \\
& +\frac{r_{2}}{d+1}\left(\sup _{x \in \partial \Omega}\left(|x|+\frac{|x|^{2}}{\epsilon_{0}}\right) \sup _{z \in \partial Q_{T}}\left|\nabla_{\tan } u_{0}(z)\right|^{2}\right. \\
& \left.\quad+2 \sup _{z \in \partial Q_{T}}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2}\right) \mathcal{L}^{d-1}(\partial \Omega) \\
& \quad \times \sup _{0 \leq s<\infty} \max \left(s^{1-d}, s^{5-d}\right) \exp \left(-\frac{1}{4 s^{2}} \inf _{x \in \partial \Omega}|x|^{2}\right) \tag{3.26}
\end{align*}
$$

for any point $z_{0}=\left(t_{0}, x_{0}\right) \in Q_{T}$ and any positive numbers $r_{1}, r_{2}$ with $r_{1}<r_{2}$. Here $\epsilon_{0}=\min _{x \in \partial \Omega}\left(\left\langle x, \nu_{x}\right\rangle / 2-1\right)$.

To prove the next lemma and Theorem 3.4, we prepare the following corollary; this corollary is easily derived from Lemma 3.2 and Lemma 3.3:

Corollary 3.1. Give two parabolic cylinders $Q_{R}\left(z_{0}\right) \subset\left(t_{0}-4 R^{2}, t_{0}+4 R^{2}\right)$ $\times B_{(1+\delta(R)) R}\left(x_{0}\right) \subset \subset Q_{T}$ with $R<e^{-d /(d+2)}$. For any point $\bar{z}_{0}=\left(\bar{t}_{0}, \bar{x}_{0}\right) \in Q_{R}\left(z_{0}\right)$ and any positive number $r<R$, we have

$$
r^{-d} \int_{Q_{r}\left(\bar{z}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z
$$

$$
\begin{aligned}
& \leq\left(8+\frac{2^{1-d}}{3}\right) e^{1 / 4} R^{-d} \int_{t_{0}-3 R^{2}}^{t_{0}+R^{2}} d t \int_{B_{(1+\delta(R)) R}\left(x_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d x \\
& +\left(8+\frac{2^{1-d}}{3}\right) e^{1 / 4} \frac{R^{2-d}}{2} \exp \left(-\frac{\delta^{2}(R)}{4}\right) \underset{0 \leq t \leq T}{\operatorname{ess} \cdot \sup } \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x \\
& +\frac{R}{2}\left(\sup _{x \in \partial \Omega}\left(|x|+\frac{|x|^{2}}{\epsilon_{0}}\right) \sup _{z \in \partial Q_{T}}\left|\nabla_{\tan } u_{0}(z)\right|^{2}\right. \\
& \left.+2 \sup _{z \in \partial Q_{T}}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2}\right) \mathcal{L}^{d-1}(\partial \Omega)
\end{aligned}
$$

$$
\begin{equation*}
\times \sup _{0 \leq s<\infty} \max \left(s^{1-d}, s^{5-d}\right) \exp \left(-\frac{1}{4 s^{2}} \inf _{x \in \partial \Omega}|x|^{2}\right)\left(=: \Phi_{R}^{1}\left(z_{0}\right)\right) \tag{3.27}
\end{equation*}
$$

$$
\underset{\bar{t}_{0}-r^{2}<t \leq \bar{t}_{0}}{\text { ess.sup }} r^{2-d} \int_{C_{r}\left(\bar{x}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x
$$

$$
\leq 36 \sqrt{3} e^{1 / 4} R^{-d} \int_{t_{0}-4 R^{2}}^{t_{0}+R^{2}} d t \int_{C_{(1+\delta(R)) R}\left(x_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d x
$$

$$
+10 \sqrt{3} R^{2-d} \exp \left(-\frac{\delta^{2}(R)}{12}\right) \underset{0 \leq t \leq T}{\operatorname{ess} \cdot \sup } \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x
$$

$$
+5 \sqrt{3} R\left(\sup _{x \in \partial \Omega}\left(|x|+\frac{|x|^{2}}{\epsilon_{0}}\right) \sup _{z \in \partial Q_{T}}\left|\nabla_{\tan } u_{0}(z)\right|^{2}\right.
$$

$$
\left.+2 \sup _{z \in \partial Q_{T}}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2}\right) \mathcal{L}^{d-1}(\partial \Omega)
$$

$$
\begin{equation*}
\times \sup _{0 \leq s \leq \infty} \max \left(s^{1-d}, s^{5-d}\right) \exp \left(-\frac{1}{4 s^{2}} \inf _{x \in \partial \Omega}|x|^{2}\right)\left(:=\bar{\Phi}_{R}^{2}\left(z_{0}\right)\right) \tag{3.28}
\end{equation*}
$$

for the number $\epsilon_{0}=\min _{x \in \partial \Omega}\left(\left\langle x, \nu_{x}\right\rangle / 2-1\right)$.
By employing Corollary 3.1, we can prove the following inequality. This inequality can be regarded as a sort of the weighted Poincaré inequality. In the following convenience, we set $\Phi_{R}^{2}\left(z_{0}\right)=: \bar{\Phi}_{R}^{2}\left(z_{0}\right)+1 / R^{d} \int_{D_{R}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z$ :

Lemma 3.4 (Nonlinear Fefferman-Phong inequality). Let $\eta$ be a non-negative smooth function with a compact support on a cube $D_{R}\left(z_{0}\right)$ and $\sup _{D_{R}\left(z_{0}\right)} \eta(z) \leq 1$. Then, for the Ginzburg-Landau energy density $e_{\lambda}\left(u_{\lambda}\right)$,

$$
\begin{align*}
& \int_{D_{R}\left(z_{0}\right)}\left|\left(\sqrt{e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)}\right)^{p} \eta(z)\right|^{2+2 / p} d z \leq C_{F P} \Phi_{R}^{2}\left(z_{0}\right) \\
& \quad \times \int_{D_{R}\left(z_{0}\right)}\left|\nabla\left(\left(\sqrt{e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)}\right)^{p} \eta(z)\right)\right|^{2} d z \tag{3.29}
\end{align*}
$$

holds where $p=1,1+2 / d$ and $C_{F P}$ is a positive constant independent of $\kappa$, $R, z_{0}, u_{\lambda}$ and $\eta$.

## Proof of lemma 3.1

The inequality (3.22) directly follows from multiplying (3.1) by $u_{\lambda}$.
On the other hand, (3.23) can be proved as follows: Taking the gradients of the both sides of (3.1) and multiplying it by $\nabla u_{\lambda}$, we have

$$
\begin{align*}
& \frac{1}{2}\left(\frac{\partial}{\partial t}-\triangle\right)\left|\nabla u_{\lambda}\right|^{2} \\
& +\left|\nabla^{2} u_{\lambda}\right|^{2}+\left.2 \lambda\left|u_{\lambda}\right|^{2}|\nabla| u_{\lambda}\right|^{2}+\lambda\left(\left|u_{\lambda}\right|^{2}-1\right)\left|\nabla u_{\lambda}\right|^{2}=0 \quad \text { in } Q_{T} . \tag{3.30}
\end{align*}
$$

The similar way as above, namely a multiplier of (3.1) by $\lambda\left(\left|u_{\lambda}\right|^{2}-1\right) u_{\lambda}$ leads to

$$
\begin{align*}
& \frac{\lambda}{4}\left(\frac{\partial}{\partial t}-\triangle\right)\left(\left|u_{\lambda}\right|^{2}-1\right)^{2}+2 \lambda\left|u_{\lambda}\right|^{2}|\nabla| u_{\lambda}| |^{2} \\
& +\lambda\left(\left|u_{\lambda}\right|^{2}-1\right)\left|\nabla u_{\lambda}\right|^{2}+\lambda^{2}\left(\left|u_{\lambda}\right|^{2}-1\right)^{2}\left|u_{\lambda}\right|^{2}=0 \tag{3.31}
\end{align*}
$$

Adding (3.30) with (3.31), we infer

$$
\begin{aligned}
& \frac{1}{2}\left(\frac{\partial}{\partial t}-\triangle\right)\left(\left|\nabla u_{\lambda}\right|^{2}+\frac{\lambda}{2}\left(\left|u_{\lambda}\right|^{2}-1\right)^{2}\right) \\
& +\left|\nabla^{2} u_{\lambda}\right|^{2}+4 \lambda\left|u_{\lambda}\right|^{2}|\nabla| u_{\lambda}| |^{2} \\
& =-2 \lambda\left(\left|u_{\lambda}\right|^{2}-1\right)\left|\nabla u_{\lambda}\right|^{2}-\lambda^{2}\left(\left|u_{\lambda}\right|^{2}-1\right)^{2}\left|u_{\lambda}\right|^{2} \\
& \leq\left(\left|u_{\lambda}\right|^{2}+\left(\left|u_{\lambda}\right|^{2}-1\right)^{2}\right)^{-1}\left|\nabla u_{\lambda}\right|^{4}+\lambda^{2}\left(\left|u_{\lambda}\right|^{2}-1\right)^{4} \\
& \leq 16\left(\frac{1}{2}\left|\nabla u_{\lambda}\right|^{2}+\frac{\lambda}{4}\left(\left|u_{\lambda}\right|^{2}-1\right)^{2}\right)^{2} .
\end{aligned}
$$

Proof of lemma 3.2

We multiply (3.1) by $\partial_{t} u_{\lambda} \eta^{2} \chi$, integrate it over $\left(t_{0}-t_{2}, t_{0}\right) \times B_{r_{2}}$ and $\left(t_{0}-t_{2}, t\right) \times$ $B_{r_{2}}$ for any $t \in\left(t_{0}-t_{2}, t_{0}\right)$ with respect to $z$ and perform the integral by parts to conclude (3.24). Here two smooth cut-off functions $\eta$ and $\chi$ are given by

$$
\begin{aligned}
& \eta(|x|)= \begin{cases}1 & \text { in } B_{r_{1}}, \\
0 & \text { outside } B_{r_{2}},\end{cases} \\
& 0 \leq \eta(|x|) \leq 1, \quad|\nabla \eta(|x|)| \leq 2 /\left(r_{2}-r_{1}\right), \\
& \chi(t)= \begin{cases}1 & t_{0}-t_{1}<t \leq t_{0}, \\
0 & t \leq t_{0}-t_{2},\end{cases} \\
& 0 \leq \chi(t) \leq 1, \quad|d \chi / d t(t)| \leq 2 /\left(t_{2}-t_{1}\right) .
\end{aligned}
$$

We can prove the desired inequality (3.25) as in the same way as above.

## Proof of lemma 3.3

First of all, let us remark that our system (3.1) is invariant under translation $z \rightarrow z-z_{0}$, hence we may shift $z_{0} \rightarrow 0$.

We mean $\phi$ by

$$
\phi(z)=\frac{\partial u_{\lambda}}{\partial t}(z) 2 t e^{\frac{|x|^{2}}{4 t}}+\langle x, \nabla\rangle u_{\lambda}(z) e^{\frac{|x|^{2}}{4 t}} .
$$

multiplier of (3.1) by $\phi$ implies

$$
\begin{align*}
0= & \left|\frac{\partial u_{\lambda}}{\partial t}\right|^{2} 2 t e^{\frac{|x|^{2}}{4 t}}+\left\langle\frac{\partial u_{\lambda}}{\partial t},\langle x, \nabla\rangle u_{\lambda}\right\rangle e^{\frac{|x|^{2}}{4 t}} \\
& -\left\langle\Delta u_{\lambda}, \frac{\partial u_{\lambda}}{\partial t}\right\rangle 2 t e^{\frac{|x|^{2}}{4 t}}-\left\langle\Delta u_{\lambda},\langle x, \nabla\rangle u_{\lambda}\right\rangle e^{\frac{|x|^{2}}{4 t}} \\
& +\frac{\lambda}{4} \frac{\partial}{\partial t}\left(\left|u_{\lambda}\right|^{2}-1\right)^{2} 2 t e^{\frac{|x|^{2}}{4 t}}+\frac{\lambda}{4}\langle x, \nabla\rangle\left(\left|u_{\lambda}\right|^{2}-1\right)^{2} 2 t e^{\frac{|x|^{2}}{4 t}} . \tag{3.33}
\end{align*}
$$

We integrate (3.33) on $\left(-r^{2}, 0\right) \times \Omega$ to obtain

$$
\begin{aligned}
& 0=\int_{-r^{2}}^{0} d t \int_{\Omega}\left|\frac{\partial u_{\lambda}}{\partial t}(z)\right|^{2} 2 t e^{\frac{|x|^{2}}{4 t}} d z \\
& +\int_{-r^{2}}^{0} d t \int_{\Omega}\left\langle\frac{\partial u_{\lambda}}{\partial t}(z),\langle x, \nabla\rangle u_{\lambda}(z)\right\rangle e^{\frac{|x|^{2}}{4 t}} d x \\
& -\int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left\langle\frac{\partial u_{\lambda}}{\partial \nu}(z), \frac{\partial u_{\lambda}}{\partial t}(z)\right\rangle 2 t e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \\
& +\frac{1}{2} \int_{-r^{2}}^{0} d t \int_{\Omega} \frac{\partial}{\partial t}\left|\nabla u_{\lambda}(z)\right|^{2} 2 t e^{\frac{\mid x x^{2}}{4 t}} d x
\end{aligned}
$$

$$
\begin{aligned}
& +\int_{-r^{2}}^{0} d t \int_{\Omega}\left\langle\left\langle\nabla e^{\frac{|x|^{2}}{4 t}}, \nabla u_{\lambda}(z)\right\rangle, \frac{\partial u_{\lambda}}{\partial t}(z)\right\rangle 2 t d x \\
& -\int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left\langle\frac{\partial u_{\lambda}}{\partial \nu}(z),\langle x, \nabla\rangle u_{\lambda}(z)\right\rangle e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \\
& +\frac{2-d}{2} \int_{-r^{2}}^{0} d t \int_{\Omega}\left|\nabla u_{\lambda}(z)\right|^{2} e^{\frac{|x|^{2}}{4 t}} d x \\
& -\frac{1}{2} \int_{-r^{2}}^{0} d t \int_{\Omega}\langle x, \nabla\rangle e^{\frac{|x|^{2}}{4 t}}\left|\nabla u_{\lambda}(z)\right|^{2} d x \\
& +\frac{1}{2} \int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left\langle x, \nu_{x}\right\rangle\left|\nabla u_{\lambda}(z)\right|^{2} e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \\
& +\int_{-r^{2}}^{0} d t \int_{\Omega}\left\langle\left\langle\nabla e^{\frac{|x|^{2}}{4 t}}, \nabla u_{\lambda}(z)\right\rangle,\langle x, \nabla\rangle u_{\lambda}(z)\right\rangle d x \\
& +\frac{\lambda}{4} \int_{-r^{2}}^{0} d t \int_{\Omega} \frac{\partial}{\partial t}\left(\left|u_{\lambda}(z)\right|^{2}-1\right)^{2} 2 t e^{\frac{|x|^{2}}{4 t}} d x \\
& -\frac{d \lambda}{4} \int_{-r^{2}}^{0} d t \int_{\Omega}\left(\left|u_{\lambda}(z)\right|^{2}-1\right)^{2} e^{\frac{|x|^{2}}{4 t}} d x \\
& -\frac{\lambda}{4} \int_{-r^{2}}^{0} d t \int_{\Omega}\langle x, \nabla\rangle e^{\frac{|x|^{2}}{4 t}}\left(\left|u_{\lambda}(z)\right|^{2}-1\right)^{2} d x \\
& =-2 \int_{-r^{2}}^{0} d t \int_{\Omega}\left|\frac{\partial u_{\lambda}}{\partial t}(z) \sqrt{|t|}-\frac{\langle x, \nabla\rangle}{2 \sqrt{|t|}} u_{\lambda}(z)\right|^{2} e^{\frac{|x|^{2}}{4 t}} d x \\
& -\int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left|\frac{\partial u_{0}}{\partial t}(z)\right| t\left|-\frac{\partial u_{\lambda}}{\partial \nu}(z)\right|^{2} e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \\
& +\int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left\langle\frac{\partial u_{\lambda}}{\partial \nu}(z), \frac{\partial u_{\lambda}}{\partial \nu}(z)-\langle x, \nabla\rangle u_{\lambda}(z)\right\rangle e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \\
& +\frac{1}{2} \int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left\langle x, \nu_{x}\right\rangle\left|\nabla u_{\lambda}(z)\right|^{2} e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \\
& +\int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2} t^{2} e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \\
& +\int_{-r^{2}}^{0} d t \int_{\Omega} \frac{\partial e_{\lambda}}{\partial t}\left(u_{\lambda}\right)(z) 2 t e^{\frac{|x|^{2}}{4 t}} d x \\
& +(2-d) \int_{-r^{2}}^{0} d t \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(z) e^{\frac{|x|^{2}}{4 t}} d x \\
& -\int_{-r^{2}}^{0} d t \int_{\Omega}\langle x, \nabla\rangle e^{\frac{|x|^{2}}{4 t}} e_{\lambda}\left(u_{\lambda}\right)(z) d x
\end{aligned}
$$

$$
\begin{equation*}
-\frac{\lambda}{4} \int_{-r^{2}}^{0} d t \int_{\Omega}\left(\left|u_{\lambda}\right|^{2}-1\right)^{2} e^{\frac{|x|^{2}}{4 t}} d x \tag{3.34}
\end{equation*}
$$

Since

$$
\begin{aligned}
& -\frac{\partial e^{\frac{|x|^{2}}{4 t}}}{\partial t} 2 t-\langle x, \nabla\rangle e^{\frac{|x|^{2}}{4 t}}=0, \\
& \nabla u_{\lambda}=\nu_{x}\left\langle\nu_{x}, \nabla\right\rangle u_{\lambda}+\nabla_{\tan } u_{\lambda},
\end{aligned}
$$

using Schwarz's inequality, we arrive at

$$
\begin{aligned}
& -2 \int_{-r^{2}}^{0} d t \int_{\Omega}\left|\frac{\partial u_{\lambda}}{\partial t}(z)-\frac{\langle x, \nabla\rangle}{2|t|} u_{\lambda}(z)\right|^{2}|t| e^{\frac{|x|^{2}}{4 t}} d x \\
& -\int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left|\frac{\partial u_{0}}{\partial t}(z)\right| t\left|-\frac{\partial u_{\lambda}}{\partial \nu}(z)\right|^{2} e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \\
& +\int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left(1+\frac{\epsilon_{0}}{2}-\frac{\left\langle x, \nu_{x}\right\rangle}{2}\right)\left|\frac{\partial u_{\lambda}}{\partial \nu}(z)\right|^{2} e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \\
& +\int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2} t^{2} e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \\
& +\frac{1}{2} \int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left(\left\langle x, \nu_{x}\right\rangle+\frac{1}{\epsilon_{0}}|x|^{2}\right)\left|\nabla_{\tan } u_{0}(z)\right|^{2} e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1}
\end{aligned}
$$

$$
+\left.\int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(z) 2 t e^{\frac{|x|^{2}}{4 t}} d x\right|_{t=-r^{2}} ^{0}-d \int_{-r^{2}}^{0} d t \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(z) e^{\frac{|x|^{2}}{4 t}} d x \geq 0
$$

with any positive number $\epsilon_{0}$.
Dividing (3.35) by $r^{-d-1}$ and recalling a property of $\partial \Omega$, i.e. $1+\epsilon_{0} / 2<$ $\left\langle x, \nu_{x}\right\rangle / 2$ on $x \in \partial \Omega$ as long as $\epsilon_{0}<2 \min _{x \in \partial \Omega}\left(\left\langle x, \nu_{x}\right\rangle / 2-1\right)$, we conclude

$$
\begin{align*}
& \frac{d}{d r}\left(r^{-d} \int_{-r^{2}}^{0} d t \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(z) e^{\frac{|x|^{2}}{4 t}} d x\right) \\
& +\frac{r^{-d-1}}{2} \int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left(\langle x, \nu\rangle+\frac{1}{\epsilon_{0}}|x|^{2}\right)\left|\nabla_{\tan } u_{0}(z)\right|^{2} e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \\
& +r^{-d-1} \int_{-r^{2}}^{0} d t \int_{\partial \Omega}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2} t^{2} e^{\frac{|x|^{2}}{4 t}} d \mathcal{H}^{d-1} \geq 0 \tag{3.36}
\end{align*}
$$

We integrate (3.36) from $r_{1}$ to $r_{2}$ with respect to $r$ to deduce the desired estimates.

## Proof of Corollary 3.1

Substituting respectively $\sqrt{2} r, \sqrt{2} R$ and $\bar{t}_{0}+r^{2}$ for $r_{1}, r_{2}$ and $t_{0}$ in Lemma 3.3 and noting $e^{-1 / 4} \leq \exp \left(\left|x-\bar{x}_{0}\right|^{2} /\left(4\left(t-\left(\bar{t}_{0}+r^{2}\right)\right)\right)\right)$ in $\bar{t}_{0}-r^{2}<t \leq \bar{t}_{0}$, we have

$$
\begin{align*}
& \quad r^{-d} \int_{\bar{t}_{0}-r^{2}}^{\bar{t}_{0}} d t \int_{B_{r}\left(\bar{x}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d x \\
& \leq e^{1 / 4} 2 d / 2 r^{-d} \int_{\bar{t}_{0}+r^{2}-(\sqrt{2} r)^{2}}^{\bar{t}_{0}+r^{2}} d t \int_{B_{r}\left(\bar{x}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) \exp \left(\frac{\left|x-\bar{x}_{0}\right|^{2}}{4\left(t-\left(\bar{t}_{0}+r^{2}\right)\right)}\right) d x \\
& \leq e^{1 / 4} 2^{d / 2}(\sqrt{2} R)^{-d} \int_{\bar{t}_{0}+r^{2}-(\sqrt{2} R)^{2}}^{\bar{t}_{0}+r^{2}} d t \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(z) \exp \left(\frac{\left|x-\bar{x}_{0}\right|^{2}}{4\left(t-\left(\bar{t}_{0}+r^{2}\right)\right)}\right) d x \\
& +\frac{2^{d / 2} R}{d+1}\left(\sup _{x \in \partial \Omega}\left(|x|+\frac{|x|^{2}}{\epsilon_{0}}\right) \sup _{z \in \partial Q_{T}}\left|\nabla_{\tan } u_{0}(z)\right|^{2}+2 \sup _{z \in \partial Q_{T}}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2}\right) \\
& \quad \times \mathcal{L}^{d-1}(\partial \Omega) \sup _{0 \leq s \leq \infty} \max \left(s^{1-d}, s^{5-d}\right) \exp \left(-\frac{1}{4 s^{2}} \inf _{x \in \partial \Omega}|x|^{2}\right) \\
& \leq e^{1 / 4} R^{-d} \int_{t_{0}-3 R^{2}}^{t_{0}+R^{2}} d t \int_{B_{(1+\delta(R)) R}\left(x_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d x \\
& +2 e^{1 / 4} R^{2-d} \exp \left(-\frac{\delta^{2}(R)}{8}\right) \operatorname{ess} \cdot \sup _{0 \leq t \leq T} \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x \\
& +\frac{R}{d+1}\left(\sup _{x \in \partial \Omega}\left(|x|+\frac{|x|^{2}}{\epsilon_{0}}\right) \sup _{z \in \partial Q_{T}}\left|\nabla_{\tan } u_{0}(z)\right|^{2}+2 \sup _{z \in \partial Q_{T}}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2}\right) \\
& \quad \times \mathcal{L}^{d-1}(\partial \Omega) \sup _{0 \leq s \leq \infty}^{\max \left(s^{1-d}, s^{5-d}\right) \exp \left(-\frac{1}{4 s^{2}} \inf _{x \in \partial \Omega}|x|^{2}\right)} \\
& \quad\left(=: \Phi_{R}^{1}\left(z_{0}\right)\right) . \tag{3.37}
\end{align*}
$$

Here note $r \leq R$ and $\bar{t}_{0} \in\left(t_{0}-R^{2}, t_{0}\right)$.
On the other hand, we use $e^{-1 / 4} \leq \exp \left(\left|x-\bar{x}_{0}\right|^{2} /\left(4\left(t-\left(\bar{t}_{0}+r^{2}\right)\right)\right)\right)$ for each $t$ $\in\left(\bar{t}_{0}-r^{2}, \bar{t}_{0}\right)$ and we respectively take $\sqrt{3} r, \sqrt{3} R$ and $\bar{t}_{0}+r^{2}$ as $r_{1}, r_{2}$ and $t_{0}$ in Lemma 3.3. Then we can estimate $r^{-d} \int_{\bar{t}_{0}-2 r^{2}}^{\bar{t}_{0}} d t \int_{C_{2 r}\left(\bar{x}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d x$ as follows:

$$
\begin{aligned}
& r^{-d} \int_{\bar{t}_{0}-2 r^{2}}^{\bar{t}_{0}} d t \int_{C_{r}\left(\bar{x}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d x \\
& \leq e^{1 / 4} 3^{d / 2}(\sqrt{3} r)^{-d} \int_{\bar{t}_{0}+r^{2}-(\sqrt{3} r)^{2}}^{\bar{t}_{0}+r^{2}} d t \int_{C_{r}\left(\bar{x}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) \exp \left(\frac{\left|x-\bar{x}_{0}\right|^{2}}{4\left(t-\left(\bar{t}_{0}+r^{2}\right)\right)}\right) d x \\
& \leq e^{1 / 4} 3^{d / 2}(\sqrt{3} R)^{-d} \int_{\bar{t}_{0}+r^{2}-(\sqrt{3} R)^{2}}^{\bar{t}_{0}+r^{2}} d t \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(z) \exp \left(\frac{\left|x-\bar{x}_{0}\right|^{2}}{4\left(t-\left(\bar{t}_{0}+r^{2}\right)\right)}\right) d x
\end{aligned}
$$

$$
\begin{aligned}
+ & \frac{\sqrt{3} R}{d+1}\left(\sup _{x \in \partial \Omega}\left(|x|+\frac{|x|^{2}}{\epsilon_{0}}\right) \sup _{z \in \partial Q_{T}}\left|\nabla_{\tan } u_{0}(z)\right|^{2}+2 \sup _{z \in \partial Q_{T}}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2}\right) \mathcal{L}^{d-1}(\partial \Omega) \\
& \times \sup _{0 \leq s \leq \infty} \max \left(s^{1-d}, s^{5-d}\right) \exp \left(-\frac{1}{4 s^{2}} \inf _{x \in \partial \Omega}|x|^{2}\right) \\
\leq & e^{1 / 4} R^{-d} \int_{\bar{t}_{0}+r^{2}-(\sqrt{3} R)^{2}}^{\bar{t}_{0}+r^{2}} d t \int_{B_{\delta(R) R}\left(\bar{x}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) \exp \left(\frac{\left|x-\bar{x}_{0}\right|^{2}}{4\left(t-\left(\bar{t}_{0}+r^{2}\right)\right)}\right) d x \\
+ & e^{1 / 4} 3 R^{2-d} \exp \left(-\frac{\delta^{2}(R)}{12}\right) \operatorname{ess} \cdot \sup _{0 \leq t \leq T} \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x \\
+ & \frac{3 R}{d+1}\left(\sup _{x \in \partial \Omega}\left(|x|+\frac{|x|^{2}}{\epsilon_{0}}\right) \sup _{z \in \partial Q_{T}}\left|\nabla_{\tan } u_{0}(z)\right|^{2}+2 \sup _{z \in \partial Q_{T}}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2}\right) \mathcal{L}^{d-1}(\partial \Omega) \\
& \times \sup _{0 \leq s \leq \infty} \max \left(s^{1-d}, s^{5-d}\right) \exp \left(-\frac{1}{4 s^{2}} \inf _{x \in \partial \Omega}|x|^{2}\right) .
\end{aligned}
$$

We must remark that $r \leq R, \bar{t}_{0} \in\left(t_{0}-R^{2}, t_{0}\right)$ and $\bar{x}_{0} \in B_{R}\left(x_{0}\right)$; Then we obtain

$$
\begin{align*}
& r^{-d} \int_{\bar{t}_{0}-2 r^{2}}^{\bar{t}_{0}} d t \int_{C_{2 r}\left(\bar{x}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d x \\
& \leq e^{1 / 4} R^{-d} \int_{t_{0}-4 R^{2}}^{t_{0}+R^{2}} d t \int_{B_{(1+\delta(R)) R}\left(x_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d x \\
& +e^{1 / 4} 3 R^{2-d} \exp \left(-\frac{\delta^{2}(R)}{12}\right) \underset{0 \leq t \leq T}{\operatorname{ess} \cdot \sup } \int_{\Omega} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x \\
& +\frac{3 R}{d+1}\left(\sup _{x \in \partial \Omega}\left(|x|+\frac{|x|^{2}}{\epsilon_{0}}\right) \sup _{z \in \partial Q_{T}}\left|\nabla_{\tan } u_{0}(z)\right|^{2}\right. \\
& \left.+2 \sup _{z \in \partial Q_{T}}\left|\frac{\partial u_{0}}{\partial t}(z)\right|^{2}\right) \mathcal{L}^{d-1}(\partial \Omega) \\
& \quad \times \sup _{0 \leq s \leq \infty} \max \left(s^{1-d}, s^{5-d}\right) \exp \left(-\frac{1}{4 s^{2}} \inf _{x \in \partial \Omega}|x|^{2}\right) \quad\left(=: \bar{\Phi}_{R}^{2}\left(z_{0}\right)\right) . \tag{3.38}
\end{align*}
$$

We next set $r_{1}=r, r_{2}=2 r, t_{1}=r^{2}, t_{2}=2 r^{2}$ and $\bar{z}_{0}=z_{0}$ in Lemma 3.2; Then the left-hand side of (3.38) can be estimated from below as follows:

$$
\begin{align*}
& \text { ess•sup } \\
& \bar{t}_{0}-r^{2}<t \leq \bar{t}_{0} \tag{3.39}
\end{align*} r^{-d} \int_{C_{r}\left(\bar{x}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(t, x) d x .
$$

Combining (3.38) with (3.39), we can conclude our second claim.

## Proof of lemma 3.4

First of all, we introduce a few symbols: For any cube $C$ and a function $f$ on $\mathbb{R}^{1+d}$, we define a few averaging functions of $f$ by

$$
\begin{aligned}
f_{C}(t) & :=\frac{1}{\mathcal{L}^{d}(C)} \int_{C} f(t, \bar{x}) d \bar{x}, \\
\bar{f}_{C}(t) & :=f(t, x)-f_{C}(t), \\
f^{*}(z) & :=f^{*}(t, x)=\sup _{x \in C} \frac{1}{\mathcal{L}^{d}(C)} \int_{C}|f(t, \bar{x})| d \bar{x}, \\
f^{\#}(z) & :=f^{\#}(t, x)=\sup _{x \in C} \frac{1}{\mathcal{L}^{d}(C)} \int_{C}\left|f(t, \bar{x})-f_{C}(t)\right| d \bar{x} .
\end{aligned}
$$

We must remark that without a loss of generality, it suffices to prove this inequality as $\left(\left(\sqrt{e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)}\right)^{p} \eta\right)_{C_{R}\left(x_{0}\right)}$ instead of $\left(\left(\sqrt{e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)}\right)^{p} \eta\right)$.

We divide our proof into two steps; the first claim is to show the following: Recall $D_{R}\left(z_{0}\right)=\left(t_{0}-R^{2}, t_{0}\right] \times C_{R}\left(x_{0}\right)$. For any function $f \in \mathcal{D}\left(D_{R}\left(z_{0}\right)\right)$ with $f_{C_{R}\left(x_{0}\right)}(t)=0$ in each $t \in\left(t_{0}-R^{2}, t_{0}\right]$,

$$
\begin{equation*}
\int_{C_{R}\left(x_{0}\right)}\left|f^{*}(z)\right|^{2+2 / p} d x \leq C_{\mathrm{FP}}^{1} \int_{C_{R}\left(x_{0}\right)}\left|f^{\#}(z)\right|^{2 / p}\left|f^{*}(z)\right|^{2} d x \tag{3.40}
\end{equation*}
$$

holds where $C_{\mathrm{FP}}^{1}$ is a positive constant depending only on $d$.
$\because)$ Let $\alpha_{0}=1 / \mathcal{L}^{d}\left(C_{R}\right) \int_{C_{R}\left(x_{0}\right)}|f(t, \bar{x})| d \bar{x}$. Suppose that $K$ be a certain positive number sufficiently large. A Calderón-Zygmund stopping process yields for each $\alpha>\alpha_{0}$ the following: There exist two sequences of cubes $\left\{C_{k}\right\},\left\{C_{k, l}\right\}(k, l=1,2, \ldots)$ satisfying

$$
\begin{align*}
& C_{k, l} \subset C_{k}, \\
& \alpha \leq \frac{1}{\mathcal{L}^{d}\left(C_{k}\right)} \int_{C_{k}}|f(t, \bar{x})| d \bar{x}<2^{d+3} \alpha,  \tag{3.41}\\
& K \alpha \leq \frac{1}{\mathcal{L}^{d}\left(C_{k, l}\right)} \int_{C_{k, l}}|f(t, \bar{x})| d \bar{x}<2^{d+3} K \alpha .
\end{align*}
$$

Here give a positive number $\delta$ sufficiently small. Note that obviously $f^{\#}>$ $\delta \alpha$ holds on any cubes $C_{k} \ni x$ with

$$
\frac{1}{\mathcal{L}^{d}\left(C_{k}\right)} \int_{C_{k}}\left|f(t, \bar{x})-f_{C_{k}}(t)\right| d \bar{x}>\delta \alpha .
$$

On the remaining cubes, we have

$$
\begin{aligned}
& \delta \alpha \mathcal{L}^{d}\left(C_{k}\right) \geq \int_{C_{k}}\left|f(t, \bar{x})-f_{C_{k}}(t)\right| d \bar{x} \\
& \geq \sum_{l} \int_{C_{k, l}}\left|f(t, \bar{x})-f_{C_{k}}(t)\right| d \bar{x} \\
& \geq \frac{K \alpha}{2} \sum_{l} \mathcal{L}^{d}\left(C_{k, l}\right) \quad \text { as long as } \quad K \geq 2^{d+4} .
\end{aligned}
$$

Thus, we infer

$$
\begin{align*}
& \mathcal{L}^{d}\left(\left\{(t, x) ; f^{*}>K \alpha\right\}\right)=\sum_{k, l} \mathcal{L}^{d}\left(C_{k, l}\right) \\
& =\sum_{k, l} \mathcal{L}^{d}\left(C_{k, l} \cap\left\{(t, x) ; f^{\#} \leq \delta \alpha\right\}\right) \\
& +\sum_{k, l} \mathcal{L}^{d}\left(C_{k, l} \cap\left\{(t, x) ; f^{\#}>\delta \alpha\right\}\right) \\
& \leq \frac{2 \delta}{K} \sum_{k} \mathcal{L}^{d}\left(C_{k}\right)+\mathcal{L}^{d}\left(\left\{(t, x) ; f^{*}>K \alpha\right\} \cap\left\{(t, x) ; f^{\#}>\delta \alpha\right\}\right) \\
& \leq \frac{2 \delta}{K} \mathcal{L}^{d}\left(\left\{(t, x) ; f^{*}>\alpha\right\}\right) \\
& +\mathcal{L}^{d}\left(\left\{(t, x) ; f^{*}>K \alpha\right\} \cap\left\{(t, x) ; f^{\#}>\delta \alpha\right\}\right) \tag{3.42}
\end{align*}
$$

for $\alpha>0$.
By noting

$$
\begin{align*}
& \left\{(t, x) ; f^{*}>K \alpha\right\} \cap\left\{(t, x) ; f^{\#}>\delta \alpha\right\} \\
& \quad \subset\left\{(t, x) ;\left(f^{\#}\right)^{p /(p+1)}\left(f^{*}\right)^{1 /(p+1)}>\delta^{p /(p+1)} K^{1 /(p+1)} \alpha\right\} \tag{3.43}
\end{align*}
$$

we then multiply the above (3.43) by $\alpha^{1+2 / p} d \alpha$ and integrate it from $\alpha_{0}$ to $\infty$ over $\alpha$ to verify

$$
\begin{aligned}
& \int_{\alpha_{0}}^{\infty} \alpha^{1+2 / p} d \alpha \mathcal{L}^{d}\left(\left\{(t, x) ; f^{*}>K \alpha\right\}\right) \\
& \leq \frac{2 \delta}{K} \int_{\alpha_{0}}^{\infty} \alpha^{1+2 / p} d \alpha \mathcal{L}^{d}\left(\left\{(t, x) ; f^{*}>\alpha\right\}\right)
\end{aligned}
$$

$$
+\int_{\alpha_{0}}^{\infty} \alpha^{1+2 / p} d \alpha \mathcal{L}^{d}\left(\left\{(t, x) ;\left(f^{\#}\right)^{p /(p+1)}\left(f^{*}\right)^{1 /(p+1)}>\delta^{p /(p+1)} K^{1 /(p+1)} \alpha\right\}\right) .
$$

Namely, we obtain

$$
\begin{aligned}
& \left(\frac{1}{K}\right)^{2(1+1 / p)} \int_{K \alpha_{0}}^{\infty} \alpha^{1+2 / p} d \alpha \mathcal{L}^{d}\left(\left\{(t, x) ; f^{*}>\alpha\right\}\right) \\
& \leq \frac{2 \delta}{K} \int_{0}^{\infty} \alpha^{1+2 / p} d \alpha \mathcal{L}^{d}\left(\left\{(t, x) ; f^{*}>\alpha\right\}\right) \\
& +\left(\frac{1}{\delta}\right)^{2}\left(\frac{1}{K}\right)^{2 / p} \int_{0}^{\infty} \alpha^{1+2 / p} d \alpha \mathcal{L}^{d}\left(\left\{(t, x) ;\left(f^{\#}\right)^{p /(p+1)}\left(f^{*}\right)^{1 /(p+1)}>\alpha\right\}\right)
\end{aligned}
$$

which is equivalent to

$$
\begin{align*}
& \int_{\left\{x \in C_{R}\left(x_{0}\right) ; f^{*}>\alpha_{0}\right\}}\left|f^{*}(z)\right|^{2+2 / p} d x \leq 2 \delta K^{1+2 / p} \int_{C_{R}\left(x_{0}\right)}\left|f^{*}(z)\right|^{2+2 / p} d x \\
& +\frac{p}{p+2}\left(\frac{1}{\delta}\right)^{2} K^{2(1+2 / p)} \int_{C_{R}\left(x_{0}\right)}\left(f^{\#}(z)\right)^{2}\left(f^{*}(z)\right)^{2 / p} d x . \tag{3.44}
\end{align*}
$$

While, noting $f_{C_{R}}(t)=0, \int_{\left\{x \in C_{R}\left(x_{0}\right) ; f^{*} \leq \alpha_{0}\right\}}\left|f^{*}(z)\right|^{2+2 / p} d x$ is estimated as follows:

$$
\begin{align*}
& \int_{\left\{x \in C_{R}\left(x_{0}\right) ; f^{*} \leq K \alpha \alpha_{0}\right\}}\left|f^{*}(z)\right|^{2+2 / p} d x \\
& \leq \mathcal{L}^{d}\left(C_{R}\left(x_{0}\right)\right) K^{2+2 / p} \alpha_{0}^{2+2 / p} \leq K^{2+2 / p} \int_{C_{R}\left(x_{0}\right)}\left(f^{\#}(z)\right)^{2}\left(f^{*}(z)\right)^{2 / p} d x . \tag{3.45}
\end{align*}
$$

If we take $\delta=1 /\left(4 K^{1+2 / p}\right)$, we thus complete the first claim with $C_{\mathrm{FP}}^{1}=$ $2 p /(p+2)(1 / \delta)^{2} K^{2}+\underline{K}^{2+2 / p}=32 K^{2+6 / p}+K^{2+2 / p}$.

Substituting $f$ for $\left({\overline{\left.\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)\right)^{p / 2} \eta\right)}}_{C_{R}\left(x_{0}\right)}\right.$ with any $\eta \in C_{0}^{\infty}\left(C_{R}\left(x_{0}\right)\right), \sup _{C_{R}\left(x_{0}\right)} \eta$ $\leq 1, p=1$ or $1+2 / d$ and any positive number $\kappa>0$, gives

$$
\begin{aligned}
& \int_{C_{R}\left(x_{0}\right)}\left|\left(\overline{\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{p / 2} \eta(z)}\right)_{C_{R}\left(x_{0}\right)}\right|^{2+2 / p} d x \\
& \leq C_{\mathrm{FP}}^{1} \int_{C_{R}\left(x_{0}\right)}\left(\left(\left(\overline{\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{p / 2} \eta(z)}\right)_{C_{R}\left(x_{0}\right)}\right)^{\#}\right)^{2} \\
& \quad \times\left(\left(\left(\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{p / 2} \eta(z)\right)_{C_{R}\left(x_{0}\right)}\right)^{*}\right)^{2 / p} d x
\end{aligned}
$$

Thus, to establish the result of our lemma, it suffices to show
$\int_{C_{R}\left(x_{0}\right)}\left(\left(\left(\overline{\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{p / 2} \eta(z)}\right)_{C_{R}\left(x_{0}\right)}\right)^{\#}\right)^{2}\left(\left(\left(\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{p / 2} \eta(z)\right)_{C_{R}\left(x_{0}\right)}\right)^{*}\right)^{2 / p} d x$ (3.46)

$$
\leq \frac{p 2^{2 / p} 5^{d}}{2-p} \Phi_{R}^{2}\left(z_{0}\right) \int_{C_{R}\left(x_{0}\right)}\left|\nabla\left(\left(\sqrt{e_{\lambda}^{(k)}\left(u_{\lambda}\right)(z)}\right)^{p} \eta(z)\right)\right|^{2} d x .
$$

$\because)$ Put

$$
\alpha_{0}=\frac{1}{\mathcal{L}^{d}\left(C_{R}\right)} \int_{C_{R}\left(z_{0}\right)}\left|f(t, \bar{x})-f_{C_{R}\left(x_{0}\right)}(t)\right| d \bar{x}
$$

and set $K=2^{d+5}$.
For any $\alpha>\alpha_{0}$ and each $t \in\left(t_{0}-R^{2}, t_{0}\right.$ ], we apply the Calderón-Zygmund stopping process; $\left\{x \in C_{R}\left(x_{0}\right) ; f^{\#}(z)>\alpha\right\}$ and $\left\{x \in C_{R}\left(x_{0}\right) ; f^{\#}(z)>K \alpha\right\}$ are divided into cylinders $C_{k}$, and $C_{k, l}$ with the following properties:

$$
\begin{gathered}
\left\{x \in C_{R}\left(x_{0}\right) ; f^{\#}(t, x)>\alpha\right\}=\bigcup_{k} C_{k}, \\
\left\{x \in C_{R}\left(x_{0}\right) ; f^{\#}(t, x)>K \alpha\right\}=\bigcup_{k, l} C_{k, l} . \\
C_{k, l} \subset C_{k}, \\
\alpha \leq \frac{1}{\mathcal{L}^{d}\left(C_{k}\right)} \int_{C_{k}}\left|f(t, \bar{x})-f_{C_{k}}(t)\right| d \bar{x}<2^{d+3} \alpha, \\
K \alpha \leq \frac{1}{\mathcal{L}^{d}\left(C_{k, l}\right)} \int_{C_{k, l}}\left|f(t, \bar{x})-f_{C_{k, l}}(t)\right| d \bar{x}<2^{d+3} K \alpha .
\end{gathered}
$$

Now observe that

$$
\begin{align*}
& (\nabla f)^{*} \geq \alpha\left(\operatorname{diam} C_{k}\right)^{-1} \quad \text { throughout } \quad C_{k},  \tag{3.47}\\
& \mathcal{L}^{d}\left(C_{k}\right) \geq 2 \mathcal{L}^{d}\left(\cup_{l} C_{k, l}\right) \tag{3.48}
\end{align*}
$$

Indeed, (3.47) follows from

$$
\frac{1}{\mathcal{L}^{d}\left(C_{k}\right)} \int_{C_{k}}\left|f(t, \bar{x})-f_{C_{k}}(t)\right| d \bar{x} \leq\left(\operatorname{diam} C_{k}\right) \frac{1}{\mathcal{L}^{d}\left(C_{k}\right)} \int_{C_{k}}|\nabla f(t, \bar{x})| d \bar{x} .
$$

While (3.48) is a consequence of

$$
\begin{aligned}
2^{d+3} \alpha \mathcal{L}^{d}\left(C_{k}\right) & >\int_{C_{k}}\left|f(t, \bar{x})-f_{C_{k}}(t)\right| d \bar{x} \geq \sum_{l} \int_{C_{k, l}}\left|f(t, \bar{x})-f_{C_{k}}(t)\right| d \bar{x} \\
& \geq \frac{1}{2} \sum_{l} \int_{C_{k, l}}\left|f(t, \bar{x})-f_{C_{k, l}}(t)\right| d \bar{x} \geq \frac{K \alpha}{2} \sum_{l} \mathcal{L}^{d}\left(C_{k, l}\right)
\end{aligned}
$$

and the fact that $K=2^{d+5}$. We thus write

$$
\begin{align*}
& \int_{C_{k} \backslash \cup_{l} C_{k, l}}\left|(\nabla f)^{*}(z)\right|^{2} d x \geq \alpha^{2}\left(\operatorname{diam} C_{k}\right)^{-2} \mathcal{L}^{d}\left(C_{k} / \bigcup_{l} C_{k, l}\right) \\
& \geq \frac{\alpha^{2}}{2}\left(\operatorname{diam} C_{k}\right)^{-2} \mathcal{L}^{d}\left(C_{k}\right) \tag{3.49}
\end{align*}
$$

Also from Corollary 3.1 and the maximal function theory (See Ziemer [122].), we obtain the following:

$$
\begin{align*}
\mu\left(C_{k}\right):= & \int_{C_{k}}\left(\left(\left(\left(\sqrt{\left.e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{p} \eta(z)}\right)_{C_{R}\left(x_{0}\right)}\right)^{*}\right)^{2 / p} d x\right. \\
\leq & \frac{p 2^{2 / p} 5^{d}}{2-p} \int_{C_{k}}\left(\left(\left(\overline{\left.\sqrt{e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)}\right)^{p} \eta(z)}\right)_{C_{R}\left(x_{0}\right)}\right)^{2 / p} d x\right. \\
= & \left.\frac{p 2^{2 / p} 5^{d}}{2-p} \int_{C_{k}} \right\rvert\,\left(\sqrt{e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)}\right)^{p} \eta(z) \\
& \quad-\left.\frac{1}{\mathcal{L}^{d}\left(C_{R}\right)} \int_{C_{R}\left(x_{0}\right)}\left(\sqrt{e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(t, \bar{x})}\right)^{p} \eta(t, \bar{x}) d \bar{x}\right|^{2 / p} d x  \tag{3.50}\\
\leq & \frac{p 2^{4 / p-1} 5^{d}}{2-p} \int_{C_{k}}\left|\left(\sqrt{e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)}\right)^{p} \eta(z)\right|^{2 / p} d x \\
+ & \frac{p 2^{4 / p-1} 5^{d}}{2-p}\left(\frac{1}{\mathcal{L}^{d}\left(C_{R}\right)}\right)^{2 / p} \mathcal{L}^{d}\left(C_{k}\right)\left|\int_{C_{R}\left(x_{0}\right)}\left(\sqrt{e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)}\right)^{p} \eta(z) d x\right|^{2 / p} \\
\leq & \frac{p 2^{4 / p-1} 5^{d}}{2-p}\left(\operatorname{diamC_{k})^{d-2}\Phi _{R}^{2}(z_{0}).}\right.
\end{align*}
$$

Combining (3.49) with (3.50), we infer

$$
\begin{equation*}
\int_{C_{k} / U_{l} C_{k, l}}\left|(\nabla f)^{*}(z)\right|^{2} d x \geq \frac{2-p}{24 p 2^{4 / p-1} 5^{d}}\left(\Phi_{R}^{2}\left(z_{0}\right)\right)^{-1} \frac{\alpha^{2}}{2} \mu\left(C_{k}\right), \tag{3.51}
\end{equation*}
$$

which implies

$$
\begin{aligned}
& \int_{\{\alpha<f \# \leq K \alpha\}}\left|(\nabla f)^{*}(z)\right|^{2} d x \geq \frac{2-p}{24 p 2^{4 / p-1} 5^{d}}\left(\Phi_{R}^{2}\left(z_{0}\right)\right)^{-1} \\
& \quad \times \frac{\alpha^{2}}{2} \mu\left(f^{\#}>\alpha\right) .
\end{aligned}
$$

Let now $\alpha$ range over $2 K^{n} \alpha_{0}(n=0,1,2, \ldots)$ and sum over $n$ to imply

$$
\begin{align*}
& \int_{C_{R}\left(z_{0}\right)}\left|(\nabla f)^{*}(z)\right|^{2} d x  \tag{3.52}\\
& \geq \frac{1}{K^{2}} \cdot \frac{2-p}{p 2^{4 / p-1} 5^{d}} \frac{\left(\Phi_{R}^{2}\left(z_{0}\right)\right)^{-1}}{2} \int_{\left\{f^{\#}>2 \alpha_{0}\right\}}\left|f^{\#}(z)\right|^{2} d \mu
\end{align*}
$$

On the other hand, $\int_{\left\{f \# \leq 2 \alpha_{0}\right\}}\left|f^{\#}(z)\right|^{2} d \mu$ is estimated as follows:

$$
\begin{gather*}
\int_{\left\{f^{\#} \leq 2 \alpha_{0}\right\}}\left|f^{\#}(z)\right|^{2} d \mu \leq 4 \alpha_{0}^{2} \mu\left(C_{R}\left(x_{0}\right)\right)  \tag{3.53}\\
\leq \frac{424 p 2^{4 / p-1} 5^{d}}{2-p}\left(\frac{1}{\mathcal{L}^{d}\left(C_{R}\right)} \int_{C_{R}\left(x_{0}\right)}\left|f(t, \bar{x})-f_{C_{R}\left(x_{0}\right)}(t)\right| d \bar{x}\right)^{2} \Phi_{R}^{2}\left(z_{0}\right) R^{d-2} \\
\leq \frac{424 p 2^{4 / p-1} 5^{d} C_{\mathrm{PO}}}{2-p} \Phi_{R}^{2}\left(z_{0}\right)\left(\int_{C_{R}\left(x_{0}\right)}|\nabla f(t, \bar{x})|^{2} d \bar{x}\right) .
\end{gather*}
$$

Combining (3.52) with (3.53), applying the maximal function theory and integrating it with respect to $t$ on $\left(t_{0}-R^{2}, t_{0}\right]$, establish our claim.

## 5. Proof of theorems

### 5.1. Proof of Theorem 3.2

Set $\sigma \in(0, R / 4)$. Also fix $\bar{z}_{0}=\left(\bar{t}_{0}, \bar{x}_{0}\right) \in Q_{R / 4}\left(z_{0}\right)$.
Since $u_{\lambda}$ is smooth, there exists $\sigma_{0} \in[0, R / 4]$ such that

$$
\begin{equation*}
\left(\frac{R}{4}-\sigma_{0}\right)^{2} \sup _{Q_{0}\left(\bar{z}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)=\max _{0 \leq \sigma \leq R / 4}\left(\frac{R}{4}-\sigma\right)^{2} \sup _{Q_{\sigma}\left(\bar{z}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right) \tag{3.54}
\end{equation*}
$$

Moreover, there exists a point $z_{\max }=\left(t_{\max }, x_{\max }\right) \in \bar{Q}_{\sigma_{0}}\left(\bar{z}_{0}\right)$ such that

$$
\begin{equation*}
\sup _{Q_{\sigma_{0}}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)=e_{\lambda}\left(u_{\lambda}\right)\left(z_{\max }\right):=e_{0} \tag{3.55}
\end{equation*}
$$

We must note that $\sigma_{0}=R / 4$ implies $\sup _{Q_{R / 4}\left(z_{0}\right)} e_{\lambda}(u) \equiv 0$. Thus we can always assume $R / 4-\sigma_{0}>0$.

If we set $\rho_{0}=1 / 2\left(R / 4-\sigma_{0}\right)$, by choice of $\sigma_{0}$ and $z_{\max }$, we obtain

$$
\begin{equation*}
\sup _{Q_{\rho_{0}}\left(z_{\max }\right)} e_{\lambda}\left(u_{\lambda}\right) \leq \sup _{Q_{\sigma_{0}+\rho_{0}}\left(\bar{z}_{0}\right)} e_{\lambda}\left(u_{\lambda}\right) \leq 4 e_{0} . \tag{3.56}
\end{equation*}
$$

Now we define

$$
\begin{aligned}
& r_{0}:=\sqrt{e_{0}} \cdot \rho_{0}, \bar{\lambda}:=\lambda / e_{0}, \\
& v_{\lambda}(\bar{t}, \bar{x}):=u_{\lambda}\left(\frac{\bar{t}}{e_{0}}+t_{\max }, \frac{\bar{x}}{\sqrt{e_{0}}}+x_{\max }\right) .
\end{aligned}
$$

Assume $r_{0} \geq 1$. Note that $v_{\lambda}$ also solves (3.1) in $Q_{r_{0}}$ and moreover $v_{\lambda}$ satisfies

$$
\begin{equation*}
e_{\bar{\lambda}}\left(v_{\lambda}\right)(0,0)=1, \quad \sup _{Q_{r_{0}}(0)} e_{\bar{\lambda}}\left(v_{\lambda}\right) \leq 4 \tag{3.57}
\end{equation*}
$$

By (3.23) in Lemma 3.1 and (3.57), $e_{\bar{\lambda}}\left(v_{\lambda}\right)$ satisfies

$$
\begin{equation*}
\left(\frac{\partial}{\partial \bar{t}}-\triangle\right) e_{\bar{\lambda}}\left(v_{\lambda}\right) \leq 64 e_{\bar{\lambda}}\left(v_{\lambda}\right) \quad \text { in } \quad Q_{r_{0}} \tag{3.58}
\end{equation*}
$$

Thus Lemma 1.3 implies

$$
\begin{equation*}
1=e_{\bar{\lambda}}\left(v_{\lambda}\right)(0,0) \leq C_{\mathrm{H}} \int_{-1}^{+1} d \bar{t} \int_{B_{1}(0)} e_{\bar{\lambda}}\left(v_{\lambda}\right)(\bar{z}) d \bar{x} \tag{3.59}
\end{equation*}
$$

But scaling back, by means of $1 / \sqrt{e_{0}}+\sigma_{0} \leq \rho_{0}<R / 4$, and the monotonicity (3.27) in Corollary 3.1, we have

$$
\begin{align*}
& e_{\bar{\lambda}}\left(v_{\lambda}\right)(0,0) \leq C\left(\sqrt{e_{0}}\right)^{d} \int_{t_{\max }-1 / e_{0}}^{t_{\max }+1 / e_{0}} d t \int_{B_{1 / \sqrt{e_{0}}}\left(x_{\max }\right.} e_{\lambda}\left(u_{\lambda}\right)(z) d x \\
& \leq C \Phi_{R}^{1}\left(z_{0}\right)\left(t_{0}+(R / 4)^{2}, x_{0}\right) \leq C \epsilon_{1} . \tag{3.60}
\end{align*}
$$

We arrive at a contradiction if we take $\epsilon_{1}<1 / C$. Consequently we can assert that $r_{0} \leq 1$, which implies our claim.

### 5.2. Proof of Theorem 3.3

Suppose that $\mathbf{N}^{\mathrm{CL}} \bigcap \operatorname{Reg} \ni z_{0}$ for a point $z_{0} \in Q_{T}$. Then from definition of $\mathbf{N}^{\mathrm{CL}}$ and Reg, there exist a sequence of $\lambda_{j}$ and positive numbers $\lambda_{0}$ and $R_{0}$ such that

$$
\begin{align*}
& \left\{z_{\lambda(j)}\right\}(\lambda(1)<\lambda(2)<\cdots<\infty) \text { with } z_{\lambda(j)} \in \mathbf{N}_{\lambda(j)} \quad \text { s.t. } \quad z_{\lambda(j)} \rightarrow z_{0}  \tag{3.61}\\
& \lambda_{0}, R_{0}>0 \quad \text { s.t. } \quad \Phi_{R_{0}}^{1}\left(t_{0}+2\left(R_{0} / 4\right)^{2}, x_{0}\right) \leq \epsilon_{1} \quad \text { for } \quad \text { any } \lambda \geq \lambda_{0} .
\end{align*}
$$

Theorem 3.2 implies the following:

$$
\begin{equation*}
\sup _{Q_{R_{0} / 4}\left(t_{0}+\left(R_{0} / 4\right)^{2}, x_{0}\right)}\left|\nabla u_{\lambda(j)}\right| \leq \frac{8 \sqrt{2}}{R_{0}} \quad(\lambda(1)<\lambda(2)<\cdots<\infty) . \tag{3.63}
\end{equation*}
$$

Since $z_{\lambda(j)} \rightarrow z_{0}$ as $j \rightarrow \infty$, there exists $j_{0} \in \mathbb{N}$ such that for any $j \geq j_{0}, z_{\lambda(j)} \in$ $Q_{R_{0} / 4}\left(t_{0}+\left(R_{0} / 4\right)^{2}, x_{0}\right)$; and $\left\{u_{\lambda(j)}\right\}\left(j=j_{0}, j_{0}+1, j_{0}+2, \ldots\right)$ is uniform bounded and equi-continuous. Then Ascoli-Arzelà's theorem asserts that for a sub-sequence $\left\{\lambda\left(j^{\prime}\right)\right\}\left(j^{\prime}=1,2, \ldots\right)$ of $\{\lambda(j)\}\left(j=j_{0}, j_{0}+1, \ldots\right), u_{\lambda\left(j^{\prime}\right)}$ uniformly converges to $u_{\infty}$ on $Q_{R_{0} / 4}\left(t_{0}+(R / 4)^{2}, x_{0}\right)$ as $j^{\prime} \rightarrow \infty$ and $u_{\infty}$ is continuous mapping in $Q_{R_{0} / 4}\left(t_{0}+\right.$ $\left.(R / 4)^{2}, x_{0}\right)$. From (3.8), $\left|u_{\infty}\right|=1$ on $Q_{R_{0} / 4}\left(t_{0}+(R / 4)^{2}, x_{0}\right)$. However this forces a contradiction because the following holds:

$$
\begin{align*}
& \left|u_{\infty}\left(z_{0}\right)\right| \leq\left|u_{\infty}\left(z_{0}\right)-u_{\lambda\left(j^{\prime}\right)}\left(z_{0}\right)\right|+\left|u_{\lambda\left(j^{\prime}\right)}\left(z_{0}\right)-u_{\lambda\left(j^{\prime}\right)}\left(z_{\lambda\left(j^{\prime}\right)}\right)\right| \\
& \leq\left|u_{\infty}\left(z_{0}\right)-u_{\lambda\left(j^{\prime}\right)}\left(z_{0}\right)\right|+\frac{8}{R_{0}}\left|z_{0}-z_{\lambda\left(j^{\prime}\right)}\right| \rightarrow 0  \tag{3.64}\\
& \quad \operatorname{as} j^{\prime} \rightarrow \infty . \quad \square
\end{align*}
$$

### 5.3. Proof of Theorem 3.4

First of all, we prove that

$$
\begin{equation*}
\left(\frac{1}{R^{d+2}} \int_{Q_{R / 2}\left(z_{0}\right)} e_{\lambda}^{1+2 / d}\left(u_{\lambda}\right)(z) d z\right)^{d /(d+2)} \leq \frac{C_{R H}^{1}}{R^{d+2}} \int_{Q_{R}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z \tag{3.65}
\end{equation*}
$$

holds for any cylinders $Q_{R / 2}\left(z_{0}\right) \subset Q_{R}\left(z_{0}\right) \subset \subset Q_{T}$ and a positive constant $C_{R H}^{1}$ depending only on $d$.
$\because$ ) Define a sequence of numbers $R_{j}$ by

$$
R_{j}=\left\{\begin{array}{l}
R / 2 \quad(j=0),  \tag{3.66}\\
R / 2+(1-\tau) / \tau \sum_{i=1}^{j} \tau^{i} R / 2 \quad(j=1,2, \ldots) .
\end{array}\right.
$$

Furthermore, give a smooth cut-off function $\eta$ with

$$
\eta(z)=\left\{\begin{array}{ll}
1 & \text { on } Q_{R_{j-1}}\left(z_{0}\right),  \tag{3.67}\\
0 & \text { outside } Q_{R_{j}}\left(z_{0}\right)
\end{array} \text { for } t \leq t_{0}\right.
$$

and

$$
\begin{aligned}
& 0 \leq \eta(z) \leq 1, \quad|\nabla \eta(z)| \leq \frac{4 \tau}{(1-\tau) \tau^{j}} \frac{1}{R}, \\
& |\triangle \eta(z)| \leq \frac{8 \tau^{2}}{(1-\tau)^{2} \tau^{2 j}} \frac{1}{R^{2}},\left|\frac{\partial \eta}{\partial t}(z)\right| \leq \frac{4 \tau}{(1-\tau) \tau^{j}} \frac{1}{R^{2}} .
\end{aligned}
$$

Then, we multiply (3.23) by $\eta^{4}$ and successively integrate it on $Q_{R}\left(z_{0}\right)$ to imply

$$
\begin{align*}
& \int_{Q_{R}\left(z_{0}\right)} \frac{\partial e_{\lambda}}{\partial t}\left(u_{\lambda}\right)(z) \eta^{4}(z) d z-\int_{Q_{R}\left(z_{0}\right)} \Delta e_{\lambda}\left(u_{\lambda}\right)(z) \eta^{4}(z) d z \\
& +\int_{Q_{R}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) \eta^{4}(z) d z \leq 16 \int_{Q_{R}\left(z_{0}\right)} e_{\lambda}^{2}\left(u_{\lambda}\right)(z) \eta^{4}(z) d z . \tag{3.68}
\end{align*}
$$

From the integral by parts in the 1st and the 2 nd term on the left-hand side in (3.68), we obtain

$$
\begin{align*}
& \int_{Q_{R}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) \eta^{4}(z) d z \\
& \leq \int_{Q_{R}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z)\left(4 \eta^{3}(z) \frac{\partial \eta}{\partial t}(z)+12 \eta^{2}(z)|\nabla \eta(z)|^{2}\right. \\
& \left.\quad \times 4 \eta^{3}(z) \triangle \eta(z)\right) d z \\
& +16 \int_{Q_{R}\left(z_{0}\right)}\left(e_{\lambda}\left(u_{\lambda}\right)(z)\right)^{2} \eta^{4}(z) d z . \tag{3.69}
\end{align*}
$$

By recalling a property of $\eta$ and applying Lemma 3.4 as $p=1$ and $\kappa=0$ to the 1st term on the right-hand side in (3.69), we infer

$$
\begin{align*}
& \int_{Q_{R}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) \eta^{4}(z) d z \\
& \leq\left(\frac{14 \cdot 16 \tau^{2}}{(1-\tau)^{2}}+\frac{16 \tau}{(1-\tau)}\right) \frac{1}{\tau^{2 j} R^{2}} \int_{Q_{R}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z \\
& +16 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right) \int_{Q_{R}\left(z_{0}\right)}\left|\nabla\left(\sqrt{e_{\lambda}\left(u_{\lambda}\right)(z)} \eta(z)\right)\right|^{2} d z \tag{3.70}
\end{align*}
$$

Noting $\left|\nabla e_{\lambda}\left(u_{\lambda}\right)\right| \leq 4 \sqrt{f_{\lambda}\left(u_{\lambda}\right)} \sqrt{e_{\lambda}\left(u_{\lambda}\right)}$, we proceed to estimate

$$
\begin{aligned}
& \int_{Q_{R_{j}}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) \eta^{4}(z) d z \\
& \leq\left(\left(14+32 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right)\right) \frac{16 \tau^{2}}{(1-\tau)^{2}}+\frac{16 \tau}{(1-\tau)}\right) \\
& \quad \times \frac{1}{\tau^{2 j} R^{2}} \int_{Q_{R}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z
\end{aligned}
$$

$$
\begin{equation*}
+16 \cdot 8 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right) \int_{Q_{R_{j}}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) d z \tag{3.71}
\end{equation*}
$$

As in the similar calculation as above, we obtain

$$
\begin{align*}
& \underset{t_{0}-R_{j}^{2} \leq t \leq t_{0}}{\text { ess. }} \int_{B_{R_{j}}\left(x_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(t, x) \eta^{4}(t, x) d x \\
& \leq\left(\left(14+32 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right)\right) \frac{16 \tau^{2}}{(1-\tau)^{2}}+\frac{16 \tau}{(1-\tau)}\right) \\
& \quad \times \frac{1}{\tau^{2 j} R^{2}} \int_{Q_{R}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z \\
& +16 \cdot 8 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right) \int_{Q_{R_{j}}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) d z . \tag{3.72}
\end{align*}
$$

We again invoke $\left|\nabla e_{\lambda}\left(u_{\lambda}\right)\right| \leq 4 \sqrt{f_{\lambda}\left(u_{\lambda}\right)} \sqrt{e_{\lambda}\left(u_{\lambda}\right)}$ and (3.71) to estimate as follows:

$$
\begin{aligned}
& \int_{Q_{R_{j}}\left(z_{0}\right)}\left|\nabla\left(e_{\lambda}\left(u_{\lambda}\right)(z) \eta^{4}(z)\right)\right| d z \\
& \leq \int_{Q_{R_{j}}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) \eta^{4}(z) d z+4 \int_{Q_{R_{j}}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) \eta^{4}(z) d z \\
& +4 \int_{Q_{R_{j}}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) \eta^{3}(z)|\nabla \eta(z)| d z \\
& \leq 4 \int_{Q_{R}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z+16 \cdot 8 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right) \int_{Q_{R_{j}\left(z_{0}\right)}} f_{\lambda}\left(u_{\lambda}\right)(z) d z \\
& +\left(\left(14+32 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right)\right) \frac{16 \tau^{2}}{(1-\tau)^{2}}+\frac{32 \tau}{(1-\tau)}\right)
\end{aligned}
$$

$$
\begin{equation*}
\times \frac{1}{\tau^{2 j} R^{2}} \int_{Q_{R}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z \tag{3.73}
\end{equation*}
$$

Thus, from (3.71), (3.72) and (3.73), the Sobolev imbedding theorem of the parabolic type (We refer to Ladyžhenskaya-Solonnikov-Ural'ceva, N.N [ [75], Chapter II, p75].) and definition of $\eta$, it follows that

$$
C_{\mathrm{SO}}^{-1}\left(\int_{Q_{R / 2}\left(z_{0}\right)}\left(e_{\lambda}\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z\right)^{d /(d+2)}+\int_{Q_{R_{j-1}\left(z_{0}\right)}} f_{\lambda}\left(u_{\lambda}\right)(z) d z
$$

$$
\begin{aligned}
& \leq 24 \cdot 16 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right) \int_{Q_{R_{j}}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) d z \\
& +\left(\left(14+16 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right)\right) \frac{48 \tau^{2}}{(1-\tau)^{2}}+\frac{64 \tau}{(1-\tau)}+4\right) \frac{1}{\tau^{2 j} R^{2}} \int_{Q_{R}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z
\end{aligned}
$$

where $C_{\mathrm{SO}}$ is the best Sobolev constant.
Since $24 \cdot 32 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right)<1 / 2$, recalling definition of $\eta$, we have

$$
\begin{aligned}
& C_{\mathrm{SO}}^{-1}\left(\int_{Q_{R / 2}\left(z_{0}\right)}\left(e_{\lambda}^{1+2 / d}\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z\right)^{d /(d+2)}+\int_{Q_{R_{j-1}}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) d z \\
& \leq \frac{1}{2} \int_{Q_{R_{j}}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) d z \\
& +\left(\frac{(1+14 \cdot 48) \tau^{2}}{(1-\tau)^{2}}+\frac{64 \tau}{(1-\tau)}+4\right) \frac{1}{\tau^{2 j} R^{2}} \int_{Q_{R}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z .
\end{aligned}
$$

If we employ the usual iteration technique by Giaquinta [46, Theorem 3.1, p. 159 and Lemma 3.1, p. 161] to the inequality above, we then conclude

$$
\begin{align*}
& C_{\mathrm{SO}}^{-1} \sum_{i=0}^{j-1}\left(\frac{1}{2}\right)^{i}\left(\int_{Q_{R / 2}\left(z_{0}\right)}\left(e_{\lambda}\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z\right)^{d /(d+2)} \\
& +\int_{Q_{R / 2}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) d z \\
& \leq\left(\frac{1}{2}\right)^{j} \int_{Q_{R_{j}}\left(z_{0}\right)} f_{\lambda}\left(u_{\lambda}\right)(z) d z+\left(\frac{(1+14 \cdot 48) \tau^{2}}{(1-\tau)^{2}}+\frac{64 \tau}{(1-\tau)}+4\right) \\
& \quad \times \sum_{i=0}^{j-1}\left(\frac{1}{2 \tau^{2}}\right)^{i} \frac{1}{\tau^{2} R^{2}} \int_{Q_{R}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z . \tag{3.74}
\end{align*}
$$

Let $j \rightarrow \infty$ to obtain the conclusion (3.65) because of $1 / \sqrt{2}<\tau<1$, i.e. $\tau=$ $1 / 2(1+\sqrt{2})$.

We proceed to the second step: Set $\sigma$ be any number with $0<\sigma<1 / 2$. Then we establish a higher integrability of the truncation function of $e_{\lambda}\left(u_{\lambda}\right)$ as follows:

$$
\begin{aligned}
& \left(\int_{Q_{(1-\sigma) R / 2}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)^{2}} d z\right)^{d /(d+2)} \\
& \leq \frac{C_{R H}^{2}}{(\sigma R)^{2}} \int_{Q_{R / 2}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z
\end{aligned}
$$

$$
\begin{equation*}
+32(d+2) R^{4 / d} \kappa^{2 / d(d+2)} \mathcal{L}^{d+2}\left(A_{R / 2}^{(\kappa)}\left(z_{0}\right)\right) \tag{3.75}
\end{equation*}
$$

holds for any cylinders $Q_{(1-\sigma) R / 2}\left(z_{0}\right) \subset Q_{R / 2}\left(z_{0}\right) \subset \subset Q_{T}$ where $C_{R H}^{2}$ is a positive constant independent of $\sigma, R, z_{0}, \kappa$ and $e_{\lambda}\left(u_{\lambda}\right)$.
$\because)$ We define a sequence of numbers $R_{j}$ by

$$
R_{j}= \begin{cases} & (1-\sigma) R / 2 \quad(j=0),  \tag{3.76}\\ & (1-\sigma) R / 2+(1-\tau) / \tau \sum_{i=1}^{j} \tau^{i}(\sigma R) / 2 \quad(j=1,2, \ldots)\end{cases}
$$

Also choose a smooth cut-off function $\eta$ satisfying

$$
\eta(z)=\left\{\begin{array}{ll}
1 & \text { on } Q_{R_{j-1}}\left(z_{0}\right),  \tag{3.77}\\
0 & \text { outside } Q_{R_{j}}\left(z_{0}\right)
\end{array} \text { in } t<t_{0}\right.
$$

with

$$
\begin{aligned}
& 0 \leq \eta(z) \leq 1, \quad|\nabla \eta(z)| \leq \frac{4 \tau}{\sigma(1-\tau) \tau^{j}} \frac{1}{R} \\
& |\triangle \eta(z)| \leq \frac{8 \tau^{2}}{\sigma^{2}(1-\tau)^{2} \tau^{2 j}} \frac{1}{R^{2}}, \quad\left|\frac{\partial \eta}{\partial t}(z)\right| \leq \frac{4 \tau}{\sigma(1-\sigma)(1-\tau) \tau^{j}} \frac{1}{R^{2}} .
\end{aligned}
$$

Set $p=1+2 / d$; A multiplier of (3.23) by $\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)\right)^{2 / d} \eta^{2+2 / p}$ and an integration of it on $Q_{R}\left(z_{0}\right)$ yield

$$
\begin{align*}
& \int_{Q_{R}\left(z_{0}\right)} \frac{\partial e_{\lambda}}{\partial t}\left(u_{\lambda}\right)(z)\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{2 / d} \eta^{2+2 / p}(z) d z \\
& +\frac{2}{d} \int_{Q_{R}\left(z_{0}\right)}\left(\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{2 / d-1}\left|\nabla e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right|^{2} \eta^{2+2 / p}(z) d z\right. \\
& +\int_{Q_{R}\left(z_{0}\right)}\left\langle\nabla e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z),\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{2 / d} \nabla \eta^{2+2 / p}(z)\right\rangle d z \\
& \leq 32 \int_{Q_{R}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{2+2 / d} \eta^{2+2 / p}(z) d z \\
& +32 \kappa^{2} \int_{Q_{R}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{2 / d} \eta^{2+2 / p}(z) d z . \tag{3.78}
\end{align*}
$$

By using the integral by parts in the 1st term, Schwarz's inequality in the 3 rd term on the left-hand side and applying Lemma 3.4 to the 1st term on the right-hand side in (3.78), we obtain

$$
\begin{aligned}
& \frac{d}{d+2} \int_{B_{R}\left(x_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)\left(t_{0}, x\right)\right)^{1+2 / d} \eta^{2+2 / p}\left(t_{0}, x\right) d x \\
& +\frac{4 d}{(d+2)^{2}} \int_{Q_{R}\left(z_{0}\right)}\left|\nabla\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1 / 2(1+2 / d)}\right|^{2} \eta^{2+2 / p}(z) d z \\
& \leq \frac{d}{d+2}\left(2+\frac{2}{p}\right) \int_{Q_{R}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)} \eta^{1+2 / p}(z) \frac{\partial \eta}{\partial t}(z) d z \\
& +d\left(1+\frac{1}{p}\right)^{2} \int_{Q_{R}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)}|\nabla \eta(z)|^{2} d z \\
& +32 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right) \int_{Q_{R}\left(z_{0}\right)} \mid \nabla\left(\left(\sqrt{\left.\left.e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{p} \eta(z)\right)\left.\right|^{2} d z}\right.\right. \\
& +32 \kappa^{2} \int_{Q_{R}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{2 / d} \eta^{2+2 / p}(z) d z .
\end{aligned}
$$

Namely, we infer

$$
\begin{align*}
& \frac{d}{(d+2)^{2}} \int_{Q_{R}\left(z_{0}\right)}\left|\nabla\left[\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1 / 2(1+2 / d)} \eta^{1+1 / p}(z)\right]\right|^{2} d z \\
& +\frac{2 d}{(d+2)^{2}} \int_{Q_{R}\left(z_{0}\right)}\left|\nabla\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1 / 2(1+2 / d)}\right|^{2} \eta^{2+2 / p}(z) d z \\
& \leq 64 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right) \int_{Q_{R}\left(z_{0}\right)}\left|\nabla\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1 / 2(1+2 / d)}\right|^{2} \eta^{2}(z) d z \\
& +\int_{Q_{R}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)}\left(\frac{d}{d+2}\left(2+\frac{2}{p}\right) \eta^{1+2 / p}(z) \frac{\partial \eta}{\partial t}(z)\right. \\
& \quad+d\left(1+\frac{1}{p}\right)^{2}|\nabla \eta(z)|^{2}+\frac{2 d}{(d+2)^{2}}\left(1+\frac{1}{p}\right)^{2}|\nabla \eta(z)|^{2} \\
& \quad+64 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right)|\nabla \eta(z)|^{2} \\
& \left.\quad+\frac{64}{d+2} \frac{1}{R^{2}}\right) d z+\frac{32 d}{d+2} R^{4 / d} \kappa^{2 / d(d+2)} \mathcal{L}^{d+2}\left(A_{R}^{(\kappa)}\left(z_{0}\right)\right) . \tag{3.80}
\end{align*}
$$

As in the similar calculation above, we infer

$$
\begin{aligned}
& \frac{d}{(d+2)^{2}}{ }_{t_{0}-R^{2}<t \leq t_{0}}^{\operatorname{ess} \cdot \sup _{B_{R}\left(z_{0}\right)}} \int_{e_{\lambda}}\left|\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1 / 2(1+2 / d)}\right|^{2} \eta^{2+2 / p}(z) d z \\
& +\frac{2 d}{(d+2)^{2}} \int_{Q_{R}\left(z_{0}\right)}\left|\nabla\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1 / 2(1+2 / d)}\right|^{2} \eta^{2+2 / p}(z) d z
\end{aligned}
$$

$$
\begin{align*}
& \leq 64 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right) \int_{Q_{R}\left(z_{0}\right)}\left|\nabla\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1 / 2(1+2 / d)}\right|^{2} \eta^{2}(z) d z \\
& +\int_{Q_{R}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)}\left(\frac{d}{d+2}\left(1+\frac{2}{p}\right) \eta^{1+2 / p}(z) \frac{\partial \eta}{\partial t}(z)\right. \\
& \quad+d\left(1+\frac{2}{p}\right)^{2}|\nabla \eta(z)|^{2}+\frac{2 d}{(d+2)^{2}}\left(1+\frac{1}{p}\right)^{2}|\nabla \eta(z)|^{2} \\
& \left.\quad+64 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right)|\nabla \eta(z)|^{2}+\frac{64}{d+2} \frac{1}{R^{2}}\right) d z \\
& \quad+\frac{32 d}{d+2} R^{4 / d} \kappa^{2 / d(d+2)} \mathcal{L}^{d+2}\left(A_{R}^{(\kappa)}\left(z_{0}\right)\right) . \tag{3.81}
\end{align*}
$$

Thus, summing up (3.80) with (3.81) and applying the Sobolev imbedding theorem of the parabolic type as before, we arrive at

$$
\begin{align*}
& \frac{C_{\mathrm{SO}}^{-1} d}{(d+2)^{2}}\left(\int_{Q_{R}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)^{2}} \eta^{2(1+1 / p)(1+2 / d)}(z) d z\right)^{d / d+2} \\
& +\frac{4 d}{(d+2)^{2}} \int_{Q_{R}\left(z_{0}\right)}\left|\nabla\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1 / 2(1+2 / d)}\right|^{2} \eta^{2+2 / p}(z) d z \\
& \leq 128 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right) \int_{Q_{R}\left(z_{0}\right)}\left|\nabla\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1 / 2(1+2 / d)}\right|^{2} d z \\
& +2 \int_{Q_{R}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)}\left(\frac{d}{d+2}\left(1+\frac{2}{p}\right) \frac{\partial \eta}{\partial t}(z) \eta^{1+2 / p}(z)\right. \\
& \quad+d\left(1+\frac{1}{p}\right)^{2}|\nabla \eta(z)|^{2}+\frac{2 d}{(d+2)^{2}}\left(1+\frac{1}{p}\right)^{2}|\nabla \eta(z)|^{2} \\
& \quad+64 C_{\mathrm{FP}} \Phi_{R}^{2}\left(z_{0}\right)|\nabla \eta(z)|^{2} \\
& \left.\quad+\frac{64}{d+2} \frac{1}{R^{2}}\right) d z+\frac{64 d}{d+2} R^{4 / d} \kappa^{2 / d(d+2)} \mathcal{L}^{d+2}\left(A_{R}^{(\kappa)}\left(z_{0}\right)\right) \tag{3.82}
\end{align*}
$$

Since $\Phi_{R}^{2}\left(z_{0}\right)<1 /\left(64 C_{\mathrm{FP}}\right) d /(d+2)^{2}$, we then conclude

$$
\begin{aligned}
& \frac{C_{\mathrm{SO}}^{-1} d}{(d+2)^{2}}\left(\int_{Q_{(1-\sigma) R / 2}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)^{2}} d z\right)^{d / d+2} \\
& +\frac{4 d}{(d+2)^{2}} \int_{Q_{R_{j-1}}\left(z_{0}\right)}\left|\nabla\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1 / 2(1+2 / d)}\right|^{2} d z
\end{aligned}
$$

$$
\begin{align*}
& \leq \frac{2 d}{(d+2)^{2}} \int_{Q_{R_{j}}\left(z_{0}\right)}\left|\nabla\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{1 / 2(1+2 / d)}\right|^{2} d z \\
&+\left(\frac{d}{d+2}\left(1+\frac{2}{p}\right) \cdot \frac{4 \tau}{(1-\sigma)(1-\tau)}+d\left(1+\frac{1}{p}\right)^{2} \frac{16 \tau^{2}}{(1-\tau)^{2}}\right. \\
&\left.\quad+\frac{2 d}{(d+2)^{2}}\left(1+\frac{1}{p}\right)^{2} \frac{16 \tau^{2}}{(1-\tau)^{2}}+\frac{d}{(d+2)^{2}} \frac{16 \tau^{2}}{(1-\tau)^{2}}+\frac{64}{d+2}\right) \\
& \quad \times \frac{2}{(\sigma R)^{2}} \frac{1}{\tau^{2 j}} \int_{Q_{R}\left(z_{0}\right)}\left(e_{\lambda}^{(\kappa)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)} d z \\
&+ \frac{64 d}{d+2} R^{4 / d} \kappa^{2 / d(d+2)} \mathcal{L}^{d+2}\left(A_{R}^{(\kappa)}\left(z_{0}\right)\right) . \tag{3.83}
\end{align*}
$$

We here used the iteration technique from Giaquinta [46, Theorem 3.1, p. 159 and Lemma 3.1, p. 161] again; a choice of $\tau$ i.e. $1 / \sqrt{2}<\tau<1$ and the limit for $j \rightarrow \infty$ proves our second step.

Now we are in the position of completing our theorem: To this end, take a sequence of decreasing cylinders:

$$
Q_{R_{j}\left(z_{0}\right)} \quad \text { with } \quad R_{j}=\frac{R}{4}+\frac{R}{2^{j+2}} \quad(j=0,1, \ldots)
$$

and a sequence of increasing levels:

$$
k_{j}=M+M\left(1-\frac{1}{2^{j}}\right) \quad(j=0,1, \ldots)
$$

where $M$ is a certain positive number selected below.
Here in (3.75), choose

$$
\begin{aligned}
& (1-\sigma) R / 2=R_{j+1}, \quad R / 2=R_{j}, \quad \sigma R / 2=R / 2^{j+3} \\
& \kappa=k_{j+1} .
\end{aligned}
$$

Then recalling (3.75), we can estimate $1 /\left(M^{1+2 / d} R^{d+2}\right) \int_{A_{R_{j+1}}^{\left(k_{j+1}\right)}\left(z_{0}\right)}\left(e_{\lambda}^{\left(k_{j+1}\right)}\right.$ $\left.\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z$ as follows:

$$
\begin{gathered}
\frac{1}{M^{1+2 / d} R^{d+2}} \int_{A_{R_{j+1}}^{\left(k_{j+1}\right)}\left(z_{0}\right)}\left(e_{\lambda}^{\left(k_{j+1}\right)}\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z \\
\leq \frac{1}{M^{1+2 / d} R^{d+2}} \mathcal{L}^{d+2}\left(A_{R_{j+1}}^{\left(k_{j+1}\right)}\left(z_{0}\right)\right)^{2 /(d+2)} \\
\mathbf{1 0 2}
\end{gathered}
$$

$$
\begin{aligned}
& \times\left(\int_{A_{R_{j+1}}^{\left(k_{j+1}\right)}\left(z_{0}\right)}\left(e_{\lambda}^{\left(k_{j+1}\right)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)^{2}} d z\right)^{d /(d+2)} \\
\leq & \frac{1}{M^{1+2 / d} R^{d+2}} \mathcal{L}^{d+2}\left(A_{R_{j}}^{\left(k_{j+1}\right)}\left(z_{0}\right)\right)^{2 /(d+2)} \\
& \times\left(\frac{C_{\mathrm{RH}}^{2} 4^{j+4}}{R^{2}} \int_{A_{R_{j}}^{\left(k_{j+1}\right)}\left(z_{0}\right)}\left(e_{\lambda}^{\left(k_{j+1}\right)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)} d z\right. \\
+ & \left.\frac{64 d}{d+2} R^{4 / d}(2 M)^{2 / d(d+2)} \mathcal{L}^{d+2}\left(A_{R_{j}}^{\left(k_{j+1}\right)}\left(z_{0}\right)\right)\right)
\end{aligned}
$$

By means of

$$
\begin{aligned}
& \mathcal{L}^{d+2}\left(A_{R_{j}}^{\left(k_{j+1}\right)}\left(z_{0}\right)\right) \\
& \leq\left(k_{j+1}-k_{j}\right)^{-(1+2 / d)} \int_{A_{R_{j}}^{\left(k_{j}\right)}\left(z_{0}\right)}\left(e_{\lambda}^{\left(k_{j}\right)}\left(u_{\lambda}\right)(z)\right)^{(1+2 / d)} d z
\end{aligned}
$$

we can proceed to estimate

$$
\begin{aligned}
& \frac{1}{M^{1+2 / d} R^{d+2}} \int_{A_{R_{j+1}}^{\left(k_{j+1}\right)}\left(z_{0}\right)}\left(e_{\lambda}^{\left(k_{j+1}\right)}\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z \\
& \leq 4^{1 / d} 4^{(1+1 / d) j}\left(C_{\mathrm{RH}}^{2} 4^{4}+\frac{64 d}{d+2} 2^{3(1+2 / d)} M^{1+2 / d} R^{2(1+2 / d)}\right) \\
& \quad \times\left(\frac{1}{M^{1+2 / d} R^{d+2}} \int_{A_{R_{j}}^{\left(k_{j}\right)}\left(z_{0}\right)}\left(e_{\lambda}^{\left(k_{j}\right)}\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z\right)^{1+\delta_{0}}
\end{aligned}
$$

$$
\begin{equation*}
=C_{\mathrm{RH}}^{3} \cdot 4^{(1 / d+1) j}\left(\frac{1}{M^{1+2 / d} R^{d+2}} \int_{A_{R_{j}}^{\left(k_{j}\right)}\left(z_{0}\right)}\left(e_{\lambda}^{\left(k_{j}\right)}\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z\right)^{1+\delta_{0}} \tag{3.84}
\end{equation*}
$$

with $C_{\mathrm{RH}}^{3}=4^{1 / d}\left(4^{4} C_{\mathrm{RH}}^{2}+(64 d) /(d+2) 3^{2(1+2 / d)}\left(M R^{2}\right)^{1+2 / d}\right)$ and $\delta_{0}=2 /(d+2)$. Thus, an induction for $j$ leads to

$$
\begin{aligned}
& \frac{1}{M^{1+2 / d} R^{d+2}} \int_{A_{R_{j}}^{\left(k_{j}\right)}\left(z_{0}\right)}\left(e_{\lambda}^{\left(k_{j}\right)}\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z \\
& \leq\left(C_{\mathrm{RH}}^{3}\right)^{-1 / \delta_{0}} 4^{-(1+1 / d)\left(1+\delta_{0}\right) / \delta_{0}} \\
& \quad \times\left(\left(C_{\mathrm{RH}}^{3}\right)^{1 / \delta_{0}} 4^{(1+1 / d)\left(1+\delta_{0}\right) / \delta_{0}^{2}} \frac{1}{M^{1+2 / d} R^{d+2}} \int_{Q_{R / 2}\left(z_{0}\right)}\left(e_{\lambda}^{\left(k_{0}\right)}\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z\right)^{\left(1+\delta_{0}\right) j}
\end{aligned}
$$

Here recall (3.65); We infer

$$
\begin{aligned}
& \frac{1}{M^{1+2 / d} R^{d+2}} \int_{A_{R_{j}}^{\left(k_{j}\right)}\left(z_{0}\right)}\left(e_{\lambda}^{\left(k_{j}\right)}\left(u_{\lambda}\right)(z)\right)^{1+2 / d} d z \\
& \leq\left(C_{\mathrm{RH}}^{3}\right)^{-1 / \delta_{0}} 4^{-(1+1 / d)\left(1+\delta_{0}\right) / \delta_{0}} \\
& \times\left(\left(C_{\mathrm{RH}}^{3}\right)^{1 / \delta_{0}} 4^{(1+1 / d)\left(1+\delta_{0}\right) / \delta_{0}^{2}} \frac{1}{M^{1+2 / d}}\left(\frac{C_{\mathrm{RH}}^{1}}{R^{d+2}} \int_{Q_{R / 2}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) d z\right)^{1+2 / d}\right)^{\left(1+\delta_{0}\right) j} \\
& \leq\left(C_{\mathrm{RH}}^{3}\right)^{-1 / \delta_{0}} 4^{-(1+1 / d)\left(1+\delta_{0}\right) / \delta_{0}} \\
& \times\left(\left(C_{\mathrm{RH}}^{3}\right)^{1 / \delta_{0}} 4^{(1+1 / d)\left(1+\delta_{0}\right) / \delta_{0}^{2}}\left(\frac{1}{M R^{2}}\right)^{1+2 / d}\left(C_{\mathrm{RH}}^{1} \Phi_{R}^{2}\left(z_{0}\right)\right)^{1+2 / d}\right)^{\left(1+\delta_{0}\right) j}
\end{aligned}
$$

where we used Corollary 3.1 and
If we choose $M=1 / R^{2}$, since

$$
\Phi_{R}^{2}<\left(C_{\mathrm{RH}}^{3}\right)^{-d /\left(\delta_{0}(d+2)\right)} 4^{-(d+2) /(d+1)\left(1+\delta_{0}\right) / \delta^{2}}\left(C_{\mathrm{RH}}^{1}\right)^{-1},
$$

we can pass to the limit $j \rightarrow \infty$; We conclude

$$
\begin{aligned}
& \int_{A_{R / 4}^{(k \infty)}\left(z_{0}\right)} e_{\lambda}^{\left(k_{\infty}\right)}\left(u_{\lambda}\right)(z) d z=0 \quad \text { which } \quad \text { deduces } \\
& \sup _{Q_{R / 4}\left(z_{0}\right)} e_{\lambda}\left(u_{\lambda}\right)(z) \leq \frac{2}{R^{2}}
\end{aligned}
$$

This provides us the assertion of this theorem.

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